Chapter 1

Geometry: Nuts and Bolts

1.1 Metric Spaces

Definition 1.1.1. A metric space is <u>proper</u> if all closed balls are compact.

The <u>length pseudo metric</u> of a metric space X is given by

$$(x,y) \mapsto \inf_{p:x \longrightarrow y} |p| \,.$$

If the metric and the induced length pseudo metric coincide, the space X is called a length space.

A geodoesic (segment) in a metric space X is a distance preserving map

$$\gamma: [0, |\gamma|] \to X$$

whose domain is an interval. The length of the domain is the length of the geodesic. A <u>bi-infinite geodesic</u> or a <u>geodesic line</u> is a distance preserving map

 $\gamma: \mathbb{R} \to X,$

and a geodesic ray is a distance preserving map

 $\gamma: \mathbb{R}^+ \to X.$

A <u>geodesic</u> space is a a metric space wherein any two points are joined by a geodesic. A <u>Hadamard</u> space is a complete geodesic space.

Exercise 1.1.2. Let X be a complete metric space. Show that X is geodesic if "it has midpoints", i.e., for every pair $\{x, y\}$ there is a point z such that $d(x, z) = d(y, z) = \frac{1}{2}d(x, y)$.

Exercise 1.1.3. Let X be a complete metric space. Show that X is a length space if "it has approximate midpoints", i.e., for every pair $\{x, y\}$ and every $\varepsilon > 0$ there is a point z such that $d(x, z), d(y, z) \leq \varepsilon + \frac{1}{2}d(x, y)$.

Definition 1.1.4. A sequence $f_i: X \to Y$ of maps between metric spaces is <u>equicontinuous</u> if for any $\varepsilon > 0$ there is a $\delta > 0$ such that, for every *i*: if $d(x,y) \leq \delta$, then $d(f_i(x), f_i(y)) \leq \varepsilon$.

Fact 1.1.5 (Arzelä-Ascoli). Let X be a compact metric space and Y be a separable metric space, then every sequence of equicontinuous functions $f_i: X \to Y$ has a subsequence that converges uniformly on compact subsets to a continuous map $f: X \to Y$.

Corollary 1.1.6. In a complete geodesic space with unique geodesics, those geodesics vary continuously with their endpoints.

Fact 1.1.7 (Hopf-Rinow). Let X be a complete, locally compact, length space. Then X is a proper geodesic space.

Let M_{κ}^{m} be the simply connected Riemannian manifold of constant curvature κ of dimension m. (There is only one up to isometry.)

Definition 1.1.8. A geodesic triangle Δ inside a metric space X is called <u> κ -admissible</u> if there is a triangle in M_{κ}^2 that has the same side length. Such a triangle is called a <u> κ -comparison</u> triangle.

Note that every point of Δ has a corresponding point in the comparison triangle. The triangle Δ is called <u> κ -thin</u> if distances of points in Δ are bounded from above by the distances of their corresponding points in a κ -comparision triangle.

A complete geodesic space X is $CAT(\kappa)$ if any κ -admissible triangle in X is κ -thin. The space X is said to have curvature $\leq \kappa$, if it is locally $CAT(\kappa)$, i.e., every point has an open ball around it so that this ball is a $CAT(\kappa)$ space.

Exercise 1.1.9. Show that any two points in a CAT(0) space are connected by a unique geodesic segment.

Fact 1.1.10 (Cartan-Hadamard). Let X be a connected complete metric space of curvature $\leq \kappa \leq 0$. Then the universal cover of X with the induced length metric is $CAT(\kappa)$. Moreover, geodesic segments in the universal cover are unique and vary continuously with their endpoints.

Definition 1.1.11. Let X be a CAT(0) space. A <u>flat strip</u> in X is a convex subspace that is isometric to a strip in the Euclidean plane bounded by two parallel lines.

Exercise 1.1.12 (Flat Strip Theorem). Let X be CAT(0) and let $\gamma : \mathbb{R} \to X$ and $\gamma' : \mathbb{R} \to X$ be two geodesic lines. Show that the convex hull of these two lines is a flat strip provided that the geodesic lines are asymptotic, i.e., the function $d(\gamma(t), \gamma'(t))$ is bounded.

Exercise 1.1.13. Let X be a connected complete metric space of curvature $\leq \kappa \leq 0$. Show that every free homotopy class has a

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representative that is a closed geodesic. Moreover, any two such representatives bound a "flat annulus", i.e., they lift to bi-infinite geodesics in the universal cover that bound a flat strip.

Definition 1.1.14. A subset $X' \subseteq X$ is <u>convex</u> if with any pair of points in X it contains all geodesic segments joining them.

Fact 1.1.15. Let X' be a convex complete subspace of the proper CAT(0) space X. Then there is a nearest-point projection

$$\pi: X \to X'$$

that takes every point $x \in X$ to the point in X' that is nearest to x. This image point exists by properness and is unique by CAT(0)-ness. For any point x outside X', the geodesic segment $[x, \pi(x)]$ is perpendicular to X'. Moreover π is a distance non-increasing map.

1.2 Piecewise Geometric Complexes

Recall that M_{κ}^m is the simply connected manifold of constant curvature κ of dimension m.

Definition 1.2.1. A <u>piecewise</u> M_{κ} -complex is a CW-complex whose cells have the structure of convex polyhedra in some M_{κ} and whose attching maps are isometric identifications with faces.

Fact 1.2.2 (Bridson). If a connected piecewise M_{κ} complex has only finitely many shapes, then it is a complete geodesic space.

Fact 1.2.3. Let X be a piecewise M_{κ} complex. For $\kappa \leq 0$, the following are equivalent:

- 1. X is $CAT(\kappa)$.
- 2. X has unique geodesics.
- 3. All links in X are CAT(1) and X does not contain a closed geodesic.
- 4. All links in X are CAT(1) and X is simply connected.
- For $\kappa > 0$, the following are equivalent:
 - 1. X is $CAT(\kappa)$.
 - 2. For any two points $x, y \in X$ of distance $d(x, y) < \frac{\pi}{\sqrt{\kappa}}$, there is a unique geodesic segment joining x and y.
 - 3. All links in X are CAT(1) and X does not contain a closed geodesic of length $< \frac{2\Pi}{\sqrt{\kappa}}$.

Fact 1.2.4 (Gromov's Lemma). A piecewise spherical simplicial complex all of whose edges have length $\frac{\pi}{2}$ is CAT(1) if and only if it is a <u>flag complex</u>, i.e., any collection of vertices that are pairwise joined by edges forms a simplex. (Whenever you see a possible 1-skeleton of a simplex, the simplex is actually there.)

A piecewise spherical simplicial complex is called <u>metrically flag</u> if every collection of vertices that are pairwise joined by edges forms a simplex provided there is a non-degenerate spherical simplex with those edge lengths.

Fact 1.2.5 (Moussong's Lema). Let X be a piecewise spherical simplicial complex all of whose edges have length $\geq \frac{\pi}{2}$. Then X is CAT(1) if and only if X is metrically flag.

Proof that metrically flag implies CAT(1). We follow the argument
of D. Krammer [?]. !!! ... !!!
q.e.d.

Exercise 1.2.6. Prove that a CAT(1) piecewise spherical simplicial complex is metrically flag.

1.3 Group Actions

Definition 1.3.1. Let X be a metric space, and let $\lambda : X \to X$ be an isometry. The displacement function of λ is the map

$$D_{\lambda}: x \mapsto d(x, \lambda(x)).$$

The displacement of λ is

$$D(\lambda) := \inf_{x \in X} D(x) \,.$$

The min-set of λ is the set

$$\operatorname{Min}(\lambda) := \left\{ x \in X \mid D(x) = D(\lambda) \right\}.$$

The isometry is <u>parabolic</u> if its min-set is empty. It is <u>semi-simple</u> otherwise. A semi-simple isometry is called <u>elliptic</u> if its displacement is 0 and hyperbolic otherwise.

Observation 1.3.2. Let X be CAT(0). Then the min-set of any semi-simple isometry is a closed, convex, and complete subspace.

Observation 1.3.3. Let X be CAT(0), let λ be a semi-simple isometry of X, and let X' be a closed, convex, complete, and λ -invariant subspace. Then

$$D_X(\lambda) = D_{X'}(\lambda)$$

since the nearest-point projection to X' is λ -equivariant and distance non-increasing.