SPECIALIZING CUBULATED RELATIVELY HYPERBOLIC GROUPS

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ABSTRACT. In [1], Agol proved the Virtual Haken and Virtual Fibering Conjectures by confirming a conjecture of Wise: Every cubulated hyperbolic group is virtually special. We extend this result to cocompactly cubulated relatively hyperbolic groups with minimal assumptions on the parabolic subgroups. Our proof proceeds by first recubulating to obtain an improper action with controlled stabilizers (a *weakly relatively geometric* action), and then Dehn filling to obtain many cubulated hyperbolic quotients. We apply our results to prove the Relative Cannon Conjecture for certain cubulated or partially cubulated relatively hyperbolic groups.

One of our main results (Theorem A) recovers via different methods a theorem of Oregón-Reyes [33].

1. INTRODUCTION

If G is a group with a proper, cellular cocompact action on a CAT(0) cube complex X, we say G is *cubulated by* X. (Some authors drop the cocompactness assumption.) Actions on cube complexes typically arise via a construction of Sageev [37] from collections of *codimension-one* subgroups.

A cube complex is *special* if it admits a locally isometric immersion to the Salvetti complex of some right-angled Artin group (see [22], where this notion was introduced, and called *A-special*). The group G is *specially cubulated by* X if the action can be chosen to be free, with quotient a special cube complex. (We may also say that G acts *co-specially* on X.) Such a group G embeds into a finitely generated right-angled Artin group, so in particular it is linear over $\mathbb{Z}$ and hence

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residually finite. It also inherits many useful separability properties from the right-angled Artin group.

The group G is *virtually specially cubulated by* X if there is a finite index subgroup G_0 of G which acts freely on X with quotient a special, compact cube complex. The $\mathbb{Z}$–linearity and nice separability properties of G_0 are passed on to G, so this is nearly as useful a property as being specially cubulated. Indeed, the Virtual Haken and Virtual Fibering Theorems of Agol [1] are proved by showing that any hyperbolic group which is cubulated is virtually specially cubulated.

We note that not all cubulated groups are virtually specially cubulated. Indeed Wise showed there are infinite cubulated groups with no finite index subgroups [42]; Burger and Mozes showed there are even infinite simple cubulated groups [7, 8]. By taking free products of such groups, one can produce cubulated *relatively* hyperbolic groups which are not residually finite and hence not virtually specially cubulated. This suggests that to extend Agol's result about cubulated hyperbolic groups to relatively hyperbolic groups it is necessary to make some assumptions about the parabolic subgroups.

1.1. **Main results.** The following appear to us to be the minimal possible assumptions on a relatively hyperbolic pair $(G, \mathcal{P})$ acting geometrically on a CAT(0) cube complex X, which might allow us to conclude that G acts virtually co-specially on X.

Assumption 1.1. *For each hyperplane stabilizer S and each $P \in \mathcal{P}$ the intersection $S \cap P$ is separable in P.*

Assumption 1.2. *For each pair of hyperplane stabilizers S_1, S_2 and each $P \in \mathcal{P}$, the double coset $(S_1 \cap P)(S_2 \cap P)$ is separable in P.*

The following is our main result, which recovers via different methods a theorem of Oregón-Reyes [33] (see Section 1.2 for the equivalence of our theorems).

Theorem A. [33, Theorem 1.2] *Suppose that $(G, \mathcal{P})$ is relatively hyperbolic and that G acts properly and cocompactly on a CAT(0) cube complex X so Assumptions 1.1 and 1.2 are satisfied. Then G acts virtually co-specially on X.*

Remark 1.3. Suppose that $(G, \mathcal{P})$ is relatively hyperbolic and that G acts properly and cocompactly on a CAT(0) cube complex X. It follows from Sageev–Wise [39, Theorem 1.1] that for each $P \in \mathcal{P}$ there exists a convex P–cocompact sub-complex Y_P in X. It follows from Haglund–Wise [23, Corollary 4.3] that each P acts virtually co-specially on Y_P when $(G, \mathcal{P})$ satisfies Assumptions 1.1 and 1.2. In fact the converse

is also true using work from [33, Appendix A]; see Subsection 1.2 for details. If G acts virtually co-specially on X, then each P also acts virtually co-specially on Y_P. This justifies our belief that Assumptions 1.1 and 1.2 are minimal.

Remark 1.4. In case G is cubulated and the elements of $\mathcal{P}$ are virtually abelian, Assumptions 1.1 and 1.2 always hold. This applies in particular to cubulated fundamental groups of finite volume hyperbolic manifolds and orbifolds.

We use the special case where elements of $\mathcal{P}$ are abelian to prove the Relative Cannon Conjecture for groups which are cubulated (Corollary 6.2) and for those which admit a weakly relatively geometric action on a CAT(0) cube complex (Theorem 6.1). This second result strengthens one of Einstein–Groves [16]. See Definition 1.9 for the definition of a weakly relatively geometric action.

While both assumptions hold whenever G acts virtually co-specially, it is unclear whether Assumption 1.2 is really necessary (see [44, Problem 13.38]). In case the parabolics are hyperbolic, Assumption 1.2 follows from Assumption 1.1, by work of Minasyan [31].

Much of our analysis does not depend on Assumption 1.2, and in particular under only Assumption 1.1 we are able to prove that various relatively quasi-convex subgroups are separable. In particular Theorem 4.7 and Theorem C have the following consequence. We do not see how to obtain this result via Oregón-Reyes' methods.

Theorem B. *Suppose $(G, \mathcal{P})$ is relatively hyperbolic and that G acts properly cocompactly on a CAT(0) cube complex so that Assumption 1.1 is satisfied. Then every hyperplane stabilizer is separable in G.*

More generally Theorem 4.7 states that relatively quasi-convex subgroups are separable whenever their intersections with parabolics are separable in those parabolics.

1.2. **Relationship to work of Agol and Oregón-Reyes.** Formally, Theorem A generalizes Agol's main theorem in [1]. However, we use that theorem in an essential way to prove [18, Theorem D], which is used in an essential way in our proof of Theorem A. In particular we do not give a new proof here of Agol's theorem.

We stated above that Oregón-Reyes' main theorem in [33] is equivalent to ours. At first glance his hypotheses seem slightly weaker, but they are equivalent by a result proved in [33, Appendix A], as we explain in this subsection. We do not use this equivalence (Proposition 1.8) anywhere in our paper, but provide it for the convenience of the reader.

Oregón-Reyes uses the following terminology.

Definition 1.5. Let G be a group, acting properly and cocompactly on a cube complex X. Then (G, X) is a *cubulated group*. If $H < G$ acts properly cocompactly on some convex subcomplex $Y \subset X$ then H is a *convex subgroup*.

The cubulated group (G, X) is *special* if G acts freely and the quotient $G \backslash X$ is special. It is *virtually special* if there is a finite index subgroup $G' < G$ so that (G', X) is special.

The conclusions of [33, Theorem 1.2] and our Theorem A are the same. However as we have mentioned the hypotheses look different. Here is Oregón-Reyes' hypothesis.

Hypothesis 1.6. (G, X) *is a cubulated group, and* $(G, \mathcal{P})$ *is relatively hyperbolic, where each* $P \in \mathcal{P}$ *is a convex subgroup of* G, *preserving a convex subcomplex* Y_P *so that* (P, Y_P) *is virtually special.*

Our hypothesis can be stated as follows.

Hypothesis 1.7. (G, X) *is a cubulated group, and* $(G, \mathcal{P})$ *is relatively hyperbolic, satisfying Assumptions 1.1 and 1.2.*

Proposition 1.8. *Hypotheses 1.6 and 1.7 are equivalent.*

Proof. Assume that (G, X) satisfies 1.6. If S is a hyperplane stabilizer it is a convex subgroup of G. By [33, A.15], the subgroup $S \cap P$ is a convex subgroup of (P, Y_P). Thus by [33, A.1], Assumptions 1.1 and 1.2 hold.

Now assume that (G, X) satisfies 1.7. As pointed out in Remark 1.3, each $P \in \mathcal{P}$ acts properly and cocompactly on some convex subcomplex $Y_P \subset X$ by a theorem of Sageev and Wise. Under Assumptions 1.1 and 1.2, Haglund–Wise show that (P, Y_P) is virtually special. $\square$

1.3. **Our strategy.** Our proof of Theorem A has two steps. The first, which takes up the bulk of this paper, is to replace the given cubulation of G by a *weakly relatively geometric* cubulation. In the following definition, recall that a *full* subgroup of a relatively hyperbolic group is one whose intersection with any parabolic subgroup is either finite or finite index in the parabolic.

Definition 1.9. If $(G, \mathcal{P})$ is relatively hyperbolic, and X is a CAT(0) cube complex, an action $G \curvearrowright X$ is *weakly relatively geometric* if the following hold:

  (1) each $P \in \mathcal{P}$ fixes some point of X;
  (2) G acts cocompactly on X; and

(3) if σ is a cell of X with infinite stabilizer, then
   (a) $\mathrm{Stab}(\sigma)$ is full relatively quasi-convex, and
   (b) $\mathrm{Stab}(\sigma)$ is the fundamental group of a graph of groups, where each edge group is finite and each vertex group is either finite or full parabolic.

The notion of a *relatively geometric* action was defined in [16]; it can be obtained from the above by strengthening (3) to the requirement that every cell stabilizer is either finite or full parabolic.

Under Assumption 1.1 we put a new wallspace structure on the vertices of X. We first find appropriate sub-complexes $\{X_P \mid P \in \mathcal{P}\}$ stabilized by the peripheral subgroups and having certain "superconvexity" properties. Translating these around we get a G–equivariant family of *parabolic* sub-complexes with uniformly bounded pairwise intersection. For each (G–orbit of) hyperplane H of X, we amalgamate the hyperplane stabilizer with finite index subgroups of the stabilizers of all the parabolic sub-complexes it meets, obtaining a relatively quasi-convex subgroup B. Now we associate a wall $\mathcal{W}_H$ to H, declaring two vertices v, w to be on the same "side" of this wall if there is a path joining them which crosses $B \cdot H$ an even number of times. These finitely many walls are completed to a G–equivariant wallspace structure $\mathcal{W}$ on $X^{(0)}$. This is described in more detail in Section 2. In Section 3 we prove that the action on the cube complex dual to this wallspace structure is weakly relatively geometric, establishing:

Theorem C. *Suppose $(G, \mathcal{P})$ is relatively hyperbolic, and that G acts properly cocompactly on a $\mathrm{CAT}(0)$ cube complex X, and that this action satisfies Assumption 1.1.*

There exists a weakly relatively geometric action of G on a $CAT(0)$ cube complex $\widehat{X}$.

The existence of a weakly relatively geometric action is the main input to the second step in our proof of Theorem A, which is completed in Section 4. The weakly relatively geometric action allows us to apply the tools in [18] to find a rich family of hyperbolic virtually special quotients of G (Theorem 4.5). We then use these quotients to prove separability of the hyperplane subgroups and double cosets in the original cubulation. By a criterion of Haglund–Wise [23, Corollary 4.3], this separability implies virtual specialness.

1.4. **Outline and conventions.** We assume the reader is familiar with the theory of relatively hyperbolic groups and relatively quasi-convex subgroups (see Hruska [27]) and also the theory of special cube complexes (see [43]). We always use the locally CAT(0) metric on a

non-positively curved cube complex, and notions such as distance and convexity refer to this metric.

In Section 2, under the assumption that a relatively hyperbolic G acts properly and cocompactly on a CAT(0) cube complex X, we recall and establish some basic properties of this action. Under Assumption 1.1, we define *augmented walls* from the hyperplanes of X which will be used to define a new wallspace structure on X. In Section 3 the cube complex associated to this wallspace structure is analyzed and Theorem C is proved. In Section 4 Dehn fillings are used to deduce Theorem A, as well as Theorem B. In Section 5 we provide an example which Theorem A implies is virtually special, but whose virtual specialness does not seem to follow from previously known results. In Section 6 we provide the promised applications towards the Relative Cannon Conjecture. Finally, in Appendix A we prove a technical generalization of a result from [19] which is required for the proof of Theorem A.

Convention 1.10. *In this paper, whenever we speak of a relatively hyperbolic group pair $(G, \mathcal{P})$ we always assume that each element of $\mathcal{P}$ is infinite. We may always ensure this by removing the finite elements from $\mathcal{P}$, which does not affect relative hyperbolicity. The removal of these finite parabolics also does not affect whether a given action is weakly relatively geometric in the sense of Definition 1.9.*

Note also that we use the notation $H^g = gHg^{-1}$.

2. A NEW WALLSPACE STRUCTURE

Throughout this section and the next we fix a relatively hyperbolic group pair $(G, \mathcal{P})$ and a proper cocompact G–action on a CAT(0) cube complex X satisfying Assumption 1.1.

The goal of this section and the next is to prove Theorem C. In the current section we describe a wallspace structure which gives rise to a new CAT(0) cube complex $\widehat{X}$; in the next we prove that the G–action on $\widehat{X}$ is weakly relatively geometric. Our wallspace has underlying set $X^{(0)}$; the new walls come from amalgamations of the original hyperplanes with carefully chosen finite index subgroups of parabolic groups. They are similar in spirit to the *augmented hyperplanes* used in [3], but we do not work in an augmented cube complex as in that paper.

Definition 2.1. A *wall* in a set S is a partition of S into two nonempty subsets usually written $W = \{W^+, W^-\}$. The two elements of the partition are called the *halfspaces* from the wall. A wall *separates* a from b in S if a and b lie in different halfspaces from the wall. A

space with walls is a pair $(S, \mathcal{W})$ where $\mathcal{W}$ is a collection of nonempty subsets of S which is closed under complementation and which satisfies the finiteness condition:

$(\star)$ $\forall x, y \in S, \; \# \{W \subseteq \mathcal{W} \mid W \text{ separates } x \text{ from } y\} < \infty$

Two walls $W = \{W^+, W^-\}$ and $V = \{V^+, V^-\}$ are said to *cross* if for every choice of $\epsilon_V, \epsilon_W \in \{+, -\}$, the intersection $W^{\epsilon_W} \cap V^{\epsilon_V}$ is non-empty.

This is a special case of a *wallspace* as studied in [28] (see also the references therein, including [37, 32, 12, 21]). In the current paper we use the term "wallspace" in this paper interchangeably with "space with walls". A wallspace gives rise to a CAT(0) cube complex in a way which we revisit in the next section. Conversely, the hyperplanes of the CAT(0) cube complex X give a wallspace structure on $X^{(0)}$ in an obvious way. In the current section we put a less obvious wallspace structure on $X^{(0)}$ which includes information about the peripheral structure. To begin, we need to see that peripheral structure in the cube complex X.

2.1. **Peripheral complexes.** In this subsection we find some sub-complexes of X associated to the peripheral subgroups $\mathcal{P}$ and record some of their properties. In contrast to the peripheral sub-complexes used in [3], our peripheral complexes are not necessarily disjoint, though they have bounded overlap with each other.

The following definition is a slight variant of [15, Definition 2.5] (the difference being that we do not consider actually thin triangles to be relatively thin).

Definition 2.2. Suppose that M is a geodesic metric space, let $a, b, c \in M$ and let $\Delta(a, b, c)$ be a geodesic triangle. Let $\pi \colon \Delta(a, b, c) \to Y_{abc}$ be the map to the comparison tripod. For $\nu \geq 0$, we say that $\Delta(a, b, c)$ is ν–*thin* if for all $p \in Y_{abc}$ we have $\operatorname{diam}(\pi^{-1}(p)) \leq \nu$.

If $U \subseteq M$ is a subset then $\Delta(a, b, c)$ is ν–*thin relative to* U if it is not ν–thin and for every $p \in Y_{abc}$ either

(1) $\operatorname{diam}(\pi^{-1}(p)) \leq \nu$; or
(2) $\pi^{-1}(p) \subseteq N_\nu(U)$.

Definition 2.3 (Thin and fat parts of triangles)**.** Let $\Delta(a, b, c)$ be a geodesic triangle in a metric space M, and let $\nu > 0$. Let $\pi \colon \Delta(a, b, c) \to Y_{abc}$ be the map to the comparison tripod. Let o be the central point of the tripod. The *internal points* of $\Delta(a, b, c)$ are the points in $\pi^{-1}(o)$. The ν–*fat part* of $\Delta(a, b, c)$ is the union of those fibers of π with diameter $\geq \nu$. Let $x \in \{a, b, c\}$, and let l_x be the leg of the tripod joining $\pi(x)$ to o. Let $t_x \subseteq l_x$ be a maximal connected subset containing $\pi(x)$

and so that $\operatorname{diam} \pi^{-1}(p) < \nu$ for all $p \in t_x$. The set $\pi^{-1}(t_x)$ is a union of two segments starting at x, called the ν–*corner segments at* x.

We remark that the ν–fat part of a triangle is always closed. If the metric on M is convex (for example CAT(0)) then any triangle is the union of its ν–fat part and ν–corner segments.

Lemma 2.4. *If Δ is a triangle in a convex metric space which is ν–thin relative to a set Z, and the fat part of some side has length at most L, then Δ is $2(L + \nu)$–thin.*

Proof. In the terminology of Definition 2.3, $\operatorname{insize}(\Delta) = \operatorname{diam}(\pi^{-1}(o))$. In a convex metric space, $\operatorname{insize}(\Delta) \leq K$ implies that Δ is K–thin, for any $K \geq 0$. It therefore suffices to bound $\operatorname{insize}(\Delta)$.

If the ν–fat part of Δ is nonempty, then, using convexity of the metric, $\pi^{-1}(o)$ is in the fat part. Let s be the side of Δ whose fat part has length at most L, and let x be the point of $\pi^{-1}(o)$ contained in s. Let y_1 and y_2 be the other two points. We have $d(x, y_1) \leq 2L_1 + \nu$, and $d(x, y_2) \leq 2L_2 + \nu$, where $L_1 + L_2 = L$. Thus $d(y_1, y_2) \leq 2L + 2\nu$, and $\operatorname{insize}(\Delta) \leq 2L + 2\nu$. $\square$

Definition 2.5. Let M be a geodesic metric space and $\mathcal{U}$ a collection of subspaces. We say that the pair $(M, \mathcal{U})$ has ν–*relatively thin triangles* if for every geodesic triangle $\Delta(a, b, c)$, either $\Delta(a, b, c)$ is ν–thin or else there exists $U \in \mathcal{U}$ so that $\Delta(a, b, c)$ is ν–thin relative to U.

The following is an immediate consequence of [15, Proposition 2.7] (see also the proofs of [39, Theorem 4.1, Proposition 4.2] and [14, §8]).

Proposition 2.6. *Fix $x \in X$ and let $\mathcal{U} = \{gP \cdot x \mid P \in \mathcal{P}, gP \in {}^{G}/_{P}\}$. There exists ν so that $(X, \mathcal{U})$ has ν–relatively thin triangles.*

The following lemma is obvious.

Lemma 2.7. *Suppose $(M, \mathcal{U})$ has ν–relatively thin triangles, and that $\mathcal{V}$ is a collection of subspaces so that every $U \in \mathcal{U}$ is contained in some $V \in \mathcal{V}$. Then $(M, \mathcal{V})$ has ν–relatively thin triangles.*

The next theorem is an immediate consequence of Sageev–Wise [39, Theorem 1.1].

Theorem 2.8. *Let $x \in X$ be as in Proposition 2.6. For each $P \in \mathcal{P}$ there exists a convex P–invariant sub-complex $Z_P \subseteq X$ with $x \in Z_P$ so that ${}_{P}\backslash^{Z_P}$ is compact.*

For each $P \in \mathcal{P}$ fix some Z_P as in Theorem 2.8, and let $\mathcal{Z} = \{g \cdot Z_P \mid P \in \mathcal{P}, g\}$, where g ranges over a set of coset representatives of ${}^{G}/_{P}$. Combining Proposition 2.6 with Lemma 2.7 and Theorem 2.8 yields the following.

Corollary 2.9. *There exists $\delta \geq 0$ so that $(X, \mathcal{Z})$ has δ–relatively thin triangles.*

The constant δ from Corollary 2.9 will remain fixed for the remainder of this section and the next.

The following definition is a slight variant of [15, Definition 5.1].

Definition 2.10. Let $\nu \geq 0$ and let $\phi \colon \mathbb{R}_{\geq 0} \to \mathbb{R}_{\geq 0}$ be a function. Suppose that M is a geodesic metric space, and that $\mathcal{U}$ is a collection of subspaces of M. The pair $(M, \mathcal{U})$ is a (ν, ϕ)–*relatively hyperbolic pair* if

    (1) $(M, \mathcal{U})$ has ν–relatively thin triangles; and
    (2) For all $r \geq 0$ and all $F_1, F_2 \in \mathcal{U}$ with $F_1 \neq F_2$, we have

$$\operatorname{diam}\left(N_r(F_1) \cap N_r(F_2)\right) \leq \phi(r).$$

The subspaces $\mathcal{U}$ are called *peripheral subspaces*.

The following is an immediate consequence of [14, Theorems 4.1, 5.1 and A.1] and Proposition 2.6.

Lemma 2.11. *Let $x \in X$ and $\mathcal{U}$ be as in Proposition 2.6 and let δ be as in Corollary 2.9. There is a function $f_0 \colon \mathbb{R}_{\geq 0} \to \mathbb{R}_{\geq 0}$ so that $(X, \mathcal{U})$ is a (δ, f_0)–relatively hyperbolic pair.*

The following easy fact is left to the reader.

Lemma 2.12. *Let M be a geodesic metric space and suppose that $\mathcal{U}$ is a set of subspaces so that $(M, \mathcal{U})$ is a (ν, ϕ)–relatively hyperbolic pair (for some $\nu \geq 0$ and function ϕ). Suppose further that $\mathcal{V}$ is a collection of subspaces of M and that there is $r \geq 0$ and a bijection $\rho \colon \mathcal{U} \to \mathcal{V}$ so that for all $U \in \mathcal{U}$ we have $U \subseteq \rho(U) \subseteq N_r(U)$. Then $(M, \mathcal{V})$ is (ν, ϕ')–relatively hyperbolic pair where $\phi'(x) = \phi(x + r)$.*

The following is an immediate consequence of Lemmas 2.11 and 2.12.

Corollary 2.13. *Let $\mathcal{Z}$ be as in Corollary 2.13, let r_0 be the maximum diameter of $P \backslash Z_P$ for $P \in \mathcal{P}$, let f_0 be the function from Lemma 2.11, let f_1 be the function defined by $f_1(x) = f_0(x + r_0)$, and let δ be the constant from Corollary 2.9. Then $(X, \mathcal{Z})$ is a (δ, f_1)–relatively hyperbolic pair.*

The subspaces $\mathcal{Z}$ from Corollary 2.13 are not the ones that we want. Instead, we want them to satisfy the following condition, which is a slightly stronger condition than that of 'attractive' in [15, Definition

5.2] in that we insist that *most* of the geodesic $[a, b]$ is contained in Z, not just *some* of it.

Definition 2.14. Let M be a complete CAT(0) space and $\eta \geq 0$. A convex subspace $Z \subseteq M$ is η–*super-attractive* if for any $K \geq 0$ and any pair of points $a, b \in N_K(Z)$, all but the initial and terminal segments of $[a, b]$ of length $(\eta + K)$ are contained in Z.

Remark 2.15. Let $K \colon \mathbb{R}_{\geq 0} \to \mathbb{R}_{\geq 0}$ be a function. Einstein [15, Definition 5.2] defines a subspace Z of a geodesic space to be K–*attractive* if, for every $m \geq 0$, every geodesic with endpoints in the m–neighborhood of Z either meets Z or has length at most $K(m)$. If Z is η–super-attractive, it is not hard to see that Z is K–attractive, for $K(m) = 2(\eta + m)$.

We now fix notation for closest point projections.

Notation 2.16. *Suppose that M is complete and* CAT(0), *and that A is a closed convex subset of M. We write $\pi_A \colon M \to A$ for the closest point projection map.*

Lemma 2.17. *Suppose that M is complete* CAT(0), *$\mathcal{C}$ is a collection of closed convex subspaces, and $(M, \mathcal{C})$ is (ν, ϕ)–relatively hyperbolic. Let $Z \in \mathcal{C}$, let $\pi_Z \colon M \to Z$ be closest point projection, and let $a, b \in X$. Let Q be the geodesic quadrilateral with vertices $\pi_Z(a), a, b, \pi_Z(b)$. Suppose*

$$\nu' = 4\nu + 2\phi(\nu), \ \nu'' = 4\nu + 2\phi(\nu'), \text{ and } \Delta(\nu, \phi) = \nu' + \nu''.$$

Then either $d(\pi_Z(a), \pi_Z(b)) \leq \phi(\nu') + 2\nu + 3\nu'$ or the quadrilateral Q is $\Delta(\nu, \phi)$–slim.[1]

Proof. We assume that

(1) $d(\pi_Z(a), \pi_Z(b)) > \phi(\nu') + \nu + 3\nu'.$

We divide Q by a diagonal into an "upper" triangle with vertices $a, b, \pi_Z(b)$ and a "lower" triangle with vertices $a, \pi_Z(a), \pi_Z(b)$. See Figure 1.

We show that Q is $\Delta(\nu, \phi)$–slim by showing that the lower triangle is ν'–thin and the upper triangle is ν''–thin.

We examine the lower triangle first. We may suppose it is not ν–thin. There is therefore some $W \in \mathcal{C}$ so that it is ν–thin relative to W.

If $W = Z$, we argue as follows. Let a_1 be the point of the fat part of $[a, \pi_Z(a)]$ closest to a. Since $d(a_1, Z) \leq \nu$, the segment $[a_1, \pi_Z(a)]$ can

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[1]Recall a polygon is μ–*slim* if each side is contained in the μ–neighborhood of the union of the other sides.
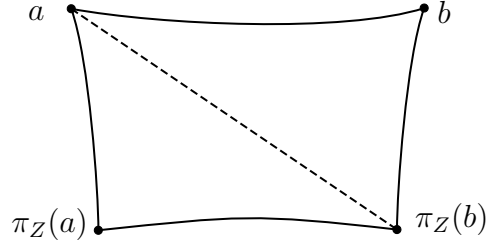
FIGURE 1. Two points and their projections to Z form the vertices of a slim quadrilateral.

have length at most ν. The segment $[a_1, \pi_Z(a)]$ contains the ν–fat part of $[a, \pi_Z(a)]$, and so the lower triangle is 4ν–thin by Lemma 2.4.

In case $W \neq Z$, we argue that the ν–fat part of $[\pi_Z(a), \pi_Z(b)]$ is bounded. Indeed, the entire segment is contained in Z, so the part which is also in a ν–neighborhood of W has diameter bounded by $\phi(\nu)$. Since the ν–fat part of one side of the lower triangle has length at most $\phi(\nu)$, Lemma 2.4 shows that the lower triangle is $2(\phi(\nu) + \nu)$–thin. In either case, we conclude that the lower triangle is $4\nu + 2\phi(\nu)$–thin.

We now show the upper triangle is ν''–thin. Again, we may assume that the upper triangle is not ν–thin, so it is ν–thin relative to some $V \in \mathcal{C}$.

If $V = Z$, then we argue as for the lower triangle, concluding that the ν–fat part of the side $[b, \pi_Z(b)]$ must have length at most ν, so the upper triangle is 4ν–thin by Lemma 2.4.

If $V \neq Z$, we argue as follows. We first note something about the lower triangle: Since $[\pi_Z(a), \pi_Z(b)]$ lies entirely in Z, and $\pi_Z(a)$ is the closest point of Z to a, the Gromov product $(a \mid \pi_Z(b))_{\pi_Z(a)}$ is at most ν'. Let x be the point on the diagonal $[a, \pi_Z(b)]$ which is in the preimage of the central point of the comparison tripod for the lower triangle. The segment $[x, \pi_Z(b)]$ lies in $N_{\nu'}(Z)$ and has length in the interval $[d(\pi_Z(a), \pi_Z(b)) - \nu', d(\pi_Z(a), \pi_Z(b))]$.

Now consider the location of x in the *upper* triangle. There are three cases, depending on whether x is in the ν–corner segment at a, the ν–fat part, or the ν–corner segment at $\pi_Z(b)$.

Suppose x lies in the ν–corner segment at a. Then the ν–fat part of the upper triangle meets the diagonal in a subsegment of $[x, \pi_Z(b)] \subseteq N_{\nu'}(Z)$. Since $V \neq Z$, this subsegment has length at most $\phi(\nu')$. By Lemma 2.4, the upper triangle is $\nu'' = (2\nu + 2\phi(\nu'))$–thin.

Suppose next that x lies in the ν–fat part of the upper triangle. This ν–fat part can only extend $\phi(\nu')$ past x. Consider the point w on the ν–fat part of $[b, \pi_Z(b)]$ closest to $\pi_Z(b)$. The corresponding point on

$[a, \pi_Z(b)]$ is within ν' of $[\pi_Z(a), \pi_Z(b)] \subseteq Z$ (and exactly ν away from w), so $d(w, \pi_Z(b)) = d(w, Z) \leq \nu + \nu'$. This is also the distance from the ν–fat part of $[a, \pi_Z(b)]$ to $\pi_Z(b)$, so we have $d(x, \pi_Z(b)) \leq \phi(\nu') + \nu + \nu'$. Since $d(x, \pi_Z(a)) \leq 2\nu'$, we have $d(\pi_Z(a), \pi_Z(b)) \leq \phi(\nu') + \nu + 3\nu'$, a contradiction to (1).

Finally suppose x lies in the corner segment of the upper triangle adjacent to $\pi_Z(b)$. Let x' be the point on $[\pi_Z(a), \pi_Z(b)]$ which is in the preimage of the central point of the comparison tripod for the lower triangle. The lower triangle is ν'–thin, so $d(x, x') \leq \nu'$. Thus the point x' is at most $\nu + \nu'$ from the corner segment of $[b, \pi_Z(b)]$ adjacent to $\pi_Z(b)$. Since $d(x', b) \geq d(\pi_Z(b), b)$, this corner segment must have length at most $\nu + \nu'$. Since $d(x', a) \geq d(\pi_Z(a), a)$ and the lower triangle is ν'–thin, the distance from $\pi_Z(a)$ to x' is at most ν'. We conclude that $d(\pi_Z(a), \pi_Z(b)) \leq d(\pi_Z(a), x') + d(x', \pi_Z(b)) \leq \nu + 2\nu'$, again contradicting (1). $\square$

Corollary 2.18. *Suppose that M is complete and $\mathrm{CAT}(0)$, $\mathcal{C}$ is a collection of convex subspaces, and $(M, \mathcal{C})$ is (ν, ϕ)–relatively hyperbolic. There exists a constant $C(\nu, \phi)$, depending only on ν and ϕ so that for any distinct $Z, Z' \in \mathcal{C}$ we have*

$$\mathrm{diam}(\pi_Z(Z')) \leq C(\nu, \phi).$$

Proof. Let ν', ν'' and $\Delta(\nu, \phi)$ be as in Lemma 2.17. We set $C(\nu, \phi) = \max\{\phi(\nu') + 2\nu + 3\nu', 2\Delta(\nu, \phi) + \phi(\Delta(\nu, \phi))\}$.

Fix $a, b \in Z'$. We have to prove that $d(\pi_Z(a), \pi_Z(b)) \leq C(\nu, \phi)$. Let Q be the geodesic quadrilateral with vertices $\pi_Z(a), a, b, \pi_Z(b)$. By Lemma 2.17 either $d(\pi_Z(a), \pi_Z(b)) \leq \phi(\nu') + 2\nu + 3\nu'$ or Q is $\Delta(\nu, \phi)$–slim.

In the first case, we are done. Thus, suppose that Q is $\Delta(\nu, \phi)$–slim. Therefore, the geodesic $\pi_Z(a), \pi_Z(b)$ is contained in the $\Delta(\nu, \phi)$–neighborhood of the other three sides. Using $\mathrm{CAT}(0)$ geometry, we see that the only points on $[\pi_Z(a), \pi_Z(b)]$ which lie within $\Delta(\nu, \phi)$ of $[a, \pi_Z(a)]$ lie within $\Delta(\nu, \phi)$ of $\pi_Z(a)$. Similarly, the only points on $[\pi_Z(a), \pi_Z(b)]$ lying within $\Delta(\nu, \phi)$ of $[b, \pi_Z(b)]$ lie within $\Delta(\nu, \phi)$ of $\pi_Z(b)$. Since $[a, b] \subseteq Z'$, the diameter of the set of points on $[\pi_Z(a), \pi_Z(b)]$ lying within $\Delta(\nu, \phi)$ of $[a, b]$ is at most $\phi(\Delta(\nu, \phi))$. Thus, in case Q is $\Delta(\nu, \phi)$–slim, we have

$$d(\pi_Z(a), \pi_Z(b)) \leq 2\Delta(\nu, \phi) + \phi(\Delta(\nu, \phi)),$$

as required. $\square$

The following is a strengthened version of the last assertion in [15, Proposition 5.3, p.23].

Proposition 2.19. *There exists η so that for each $P \in \mathcal{P}$ there exists a convex η–super-attractive P–invariant sub-complex $Y_P \subseteq X$ so that $Z_P \subseteq Y_P$ and $_P\backslash Y_P$ is compact.*

Proof. Let $\mathcal{Z}$, δ, and f_1 be as in the conclusions to Theorem 2.8 and Corollary 2.13. That is, for each $P \in \mathcal{P}$, there is a convex P–invariant P–cocompact sub-complex Z_P of X, and the family $\mathcal{Z}$ is the family of distinct translates of these Z_P under the action of G. Corollary 2.13 says the pair $(X, \mathcal{Z})$ is a (δ, f_1)–relatively hyperbolic pair. Let $\Delta_0 = \Delta(\delta, f_1)$ be the constant from Lemma 2.17.

If E is a subset of a CAT(0) cube complex the *combinatorial hull* $\mathrm{Hull}(E)$ is defined to be the intersection of the convex subcomplexes containing E.

The argument at the beginning of Section 5 of [39] can be adapted to show that there is an S (depending only on $\dim(X)$, δ, f_1 and $\Delta_0 = \Delta(\delta, f_1)$) so that

$$(2) \qquad\qquad \mathrm{Hull}(N_{\Delta_0}(Z)) \subseteq N_S(Z)$$

for every $Z \in \mathcal{Z}$. For $P \in \mathcal{P}$, we take $Y_P = \mathrm{Hull}(N_{\Delta_0}(Z_P))$. We set

$$\eta = \frac{1}{2}\left(2S + f_1(\delta') + 2\delta + 3\delta'\right).$$

From now on we fix P, and set $Z = Z_P$, $Y = Y_P$.

Let $K \geq 0$, and let $a, b \in N_K(Y)$. By (2), $a, b \in N_{K+S}(Z)$. Let π_Z be the closest point projection to Z, and consider the geodesic quadrilateral Q with vertices $\pi_Z(a), a, b, \pi_Z(b)$.

Given Lemma 2.17, we argue as follows. In case

$$d(\pi_Z(a), \pi_Z(b)) \leq f_1(\delta') + 2\delta + 3\delta',$$

we have

$$\begin{aligned}
d(a, b) &\leq d(a, \pi_Z(a)) + d(\pi_Z(a), \pi_Z(b)) + d(\pi_Z(b), b) \\
&\leq 2(K + S) + f_1(\delta') + 2\delta + 3\delta' \\
&\leq 2(K + \eta),
\end{aligned}$$

and there is nothing to show.

Otherwise, every point on $[a, b]$ is within Δ_0 of some point on

$$[a, \pi_Z(a)] \cup [\pi_Z(a), \pi_Z(b)] \cup [b, \pi_Z(b)].$$

Let $[a', b'] \subseteq [a, b]$ be the subsegment beginning and ending on

$$N_{\Delta_0}([a, \pi_Z(a)] \cup [b, \pi_Z(b)]).$$

The lengths of the remaining subsegments $[a, a']$ and $[b, b']$ are at most $K + S + \Delta_0$. Since $[\pi_Z(a), \pi_Z(b)] \subseteq Z$, the subsegment $[a', b']$ lies in $N_{\Delta_0}(Z) \subseteq Y$, as desired. $\qquad\square$

Definition 2.20. For each $P \in \mathcal{P}$, fix a P–invariant sub-complex Y_P of X satisfying the conclusions of Proposition 2.19. Any sub-complex of X of the form gY_P for $g \in G, P \in \mathcal{P}$ is called a *peripheral complex*. We let $\mathcal{B}$ be the collection of all peripheral complexes in X.

The following is an immediate consequence of Corollary 2.13 and Lemma 2.12.

Lemma 2.21 (cf. [15, Proposition 5.3]). *Let δ be as in Corollary 2.9 and define the function $f \colon \mathbb{R}_{\geq 0} \to \mathbb{R}_{\geq 0}$ by $f(x) = f_1(x + r_1)$, where f_1 is the function from Corollary 2.13 and r_1 is the maximum diameter of the spaces ${}_P\backslash Y_P$ from Proposition 2.19. Then the pair $(X, \mathcal{B})$ is (δ, f)–relatively hyperbolic.*

For the remainder of this section and the next we fix the collection $\mathcal{B}$ of convex η–super-attractive peripheral complexes from Definition 2.20 so that $(X, \mathcal{B})$ is a (δ, f)–relatively hyperbolic pair, for η as in Proposition 2.19 and δ, f as in Lemma 2.21.

2.2. **Augmented walls.** Up to the G–action, there are finitely many hyperplanes in X. In this subsection we fix some such hyperplane H, and describe a partition $\mathcal{W}_H = \{W_H^+, W_H^-\}$ of $X^{(0)}$ associated to that hyperplane together with some extra data we now specify.

Definition 2.22. Suppose that H is a hyperplane in X. Let $\mathrm{Stab}(H)$ be the stabilizer of H, and let $Y_1, \ldots, Y_k$ be representatives of the $\mathrm{Stab}(H)$–orbits of peripheral complexes that intersect H.

A *broadcaster* for H is a subgroup of G of the form

$$B = \langle \mathrm{Stab}(H), B_1, \ldots, B_k \rangle,$$

where for each i the subgroup B_i is a finite-index subgroup of $\mathrm{Stab}(Y_i)$. Given a broadcaster B, the associated collection $B \cdot H$ of hyperplanes of X is called the *scattering of H by B*. Given $R > 0$, we say that $B \cdot H$ is an *R–separated scattering* if any two carriers of distinct hyperplanes in $B \cdot H$ are distance at least R from each other.

We make use of the following result of Martínez-Pedroza, which we have slightly rephrased.

Theorem 2.23. [30, Theorem 1.1] *Let $A < G$ be relatively quasi-convex, and let $P \in \mathcal{P}$. There is a finite set $F \subseteq P \setminus A$ so that if $\dot{P} < P$ satisfies $A \cap P \subseteq \dot{P} \subseteq P \setminus F$, then:*

(1) $\widehat{A} := \langle A, \dot{P} \rangle$ is relatively quasi-convex;
(2) $\widehat{A} = A *_{A \cap P} \dot{P}$; and

(3) *Every parabolic subgroup of $\widehat{A}$ is $\widehat{A}$–conjugate either to a subgroup of $\dot{P}$ or a subgroup of A.*

We will apply Theorem 2.23 to hyperplane stabilizers. This requires the (well-known) fact that they are relatively quasi-convex.

Lemma 2.24. *Let H be a hyperplane of X. Then $\mathrm{Stab}(H)$ is relatively quasi-convex in $(G, \mathcal{P})$.*

Proof. Since the hyperplane H is convex in X, there is a quasi-isometry of pairs $(X, H) \to (G, \mathrm{Stab}(H))$. This implies $\mathrm{Stab}(H)$ is undistorted in G. Therefore by [27, Theorem 1.5] $\mathrm{Stab}(H)$ is relatively quasi-convex in $(G, \mathcal{P})$. □

Proposition 2.25. *Let H be a hyperplane in X, let $\{Y_1, \ldots, Y_k\}$ be as above, and let $R > 0$.*

There exists a broadcaster B for H so that B is full relatively quasi-convex in G and the associated scattering $B \cdot H$ is R–separated.

Proof. We use Theorem 2.23 to construct a sequence of relatively quasi-convex subgroups $\mathrm{Stab}(H) = A_0 < A_1 < \cdots < A_k = B$ so that A_i is an amalgam of A_{i-1} with a finite index subgroup of $\mathrm{Stab}(Y_i)$.

By Lemma 2.24, A_0 is relatively quasi-convex in $(G, \mathcal{P})$. We inductively assume that A_{i-1} is relatively quasi-convex and that

$$(\dagger_{i-1}) \qquad A_{i-1} \cap \mathrm{Stab}(Y_j) = A_0 \cap \mathrm{Stab}(Y_j), \ \forall j \geq i.$$

Applying Theorem 2.23 with $A = A_{i-1}$ and $P = \mathrm{Stab}(Y_i)$, we obtain $F_i = F \subseteq \mathrm{Stab}(Y_i) \setminus A_{i-1}$ as in the theorem. Assumption 1.1 guarantees the existence of a finite index $B_i < \mathrm{Stab}(Y_i)$ which contains $A_0 \cap \mathrm{Stab}(Y_i)$ but misses F_i. We can thus apply Theorem 2.23 with $\dot{P} = B_i$ to obtain a relatively quasi-convex $A_i = A_{i-1} *_{A_0 \cap \mathrm{Stab}(Y_i)} B_i$.

In order to continue the induction we must establish Condition $(\dagger_i)$; this follows easily from [30, Lemma 5.4]. It also follows from that result that the final amalgam $B = A_k$ is full.

It remains to show that by expanding the finite sets F_i if necessary we can ensure that the scattering $B \cdot H$ is R–separated. Since $B \cdot H$ consists of the B–orbit of a single hyperplane, it suffices to ensure that the distance from H to $B \cdot H \setminus H$ is at least $R + 1$. For fixed R, there exists a finite set $\{g_1, \ldots, g_l\} \subseteq G \setminus \mathrm{Stab}(H)$ so that any hyperplane within $R + 1$ of H is of the form $a \cdot g_i \cdot H$ for some $a \in \mathrm{Stab}(H)$. Since $\mathrm{Stab}(H) \leq B$, if $a \cdot g_i \cdot H \in B \cdot H$ then $g_i \cdot H \in B \cdot H$ also. Therefore, we need to exclude the finite set $\{g_1 \cdot H, \ldots, g_l \cdot H\}$ from $B \cdot H$. It is easy to see (again using $\mathrm{Stab}(H) \leq B$) that this is the same as excluding the finite set $\{g_1, \ldots, g_l\}$ from B. That this can be done (by choosing F_i

appropriately, depending on R) is an easy consequence of [30, Lemma 3.6 and Lemma 5.2] – we find a short geodesic between 1 and g_i which has no large $\dot{P}$–components, but on the other hand if $g_i \in B$ then there is some path in B which is not contained in $\mathrm{Stab}(H)$ and necessarily contains a large $\dot{P}$–component. This contradicts [30, Lemma 3.6]. This argument completes the proof of the proposition. $\square$

We are now ready to describe the augmented walls W_H. There is some freedom in this description; further constraints are imposed in Assumption 2.40 and Definition 2.41 where we pick the particular augmented walls for our wallspace.

Definition 2.26. Given a hyperplane H, and $R > 0$, fix a broadcaster B whose associated scattering $B \cdot H$ is R–separated as in Proposition 2.25. Define an equivalence relation on $X^{(0)}$ by declaring $v \sim w$ if there is a path in the 1–skeleton of X which crosses $B \cdot H$ an even number of times. Let $W_{H,B}$ be the pair of equivalence classes.

We observe:

Lemma 2.27. *Let B and $W_{H,B} = \{W_{H,B}^+, W_{H,B}^-\}$ be as above. Both $W_{H,B}^+$ and $W_{H,B}^-$ are nonempty, $\mathrm{Stab}(W_{H,B}) = B$, and $\mathrm{Stab}(W_{H,B}^+) = \mathrm{Stab}(W_{H,B}^-)$ is a subgroup of B of index at most two.*
In particular, $\mathrm{Stab}(W_{H,B})$ is full relatively quasi-convex in $(G, \mathcal{P})$.

Remark 2.28. The hyperplane H descends to an embedded hyperplane of $_B\backslash^X$. The index of $\mathrm{Stab}(W_{H,B}^+)$ in B is one if this hyperplane is separating; otherwise the index is two.

2.3. **Connected quasi-convex sub-complexes associated to walls.** Later we fix an R–separated scattering $B \cdot H$ of H with R very large. Therefore, though $B \cdot H$ is quasi-convex, the quasi-convexity constant is very large. In order to associate a connected *uniformly* quasi-convex subspace of X to the wall $W_{H,B}$, we adjoin peripheral complexes to the hyperplane carriers.

There are three results in this subsection used extensively in the sequel. In Proposition 2.37 we establish the uniform quasi-convexity of the *thick carriers* defined below in Definition 2.29. In Lemma 2.36 we quantify the statement that peripheral complexes which come near to a thick carrier for a long time must be contained in the thick carrier. In Lemma 2.32, we quantify the fact that two peripheral complexes in a thick carrier can only come near to each other if they are both near to a hyperplane of the scattering. It is crucial for our applications that all these results are uniform for R–scatterings, so long as R is sufficiently large.

Definition 2.29 (Thick carrier)**.** Let H be a hyperplane in X, $R > 0$ and $B \cdot H$ an R–separated scattering of H.

Let $\mathcal{A}$ be the collection of carriers of translates bH where $b \in B$. As before $\mathcal{B}$ is the set of peripheral complexes. Form an abstract cube complex

$$Y_{H,B} = \sqcup \mathcal{A} \bigsqcup \sqcup \mathcal{B}/ \sim \, .$$

The equivalence relation $\sim$ is generated by the following identifications: For each bH with $b \in B$ and carrier $A \in \mathcal{A}$, and each $Z \in \mathcal{B}$ meeting bH, glue A to Z along their intersection in X. Now let $S_{H,B}$ be the component of $Y_{H,B}$ containing H. (The other components are just elements of $\mathcal{B}$.) There is a canonical map $\phi_{H,B} \colon S_{H,B} \to X$ which restricts to the inclusion on any hyperplane carrier or peripheral complex. We define the *thick carrier of* $W_{H,B}$ to be $T(W_{H,B}) = \phi_{H,B}(S_{H,B})$. The thick carrier $T(W_{H,B})$ is a union of convex sub-complexes.

We observe:

Lemma 2.30. $T(W_{H,B})$ *is a connected sub-complex of* X *on which* B *acts properly cocompactly.*

The next result uses work of Einstein [15] to show that $T(W_{H,B})$ is quasi-isometrically embedded and quasi-convex.

Proposition 2.31. *There exist constants* $R_0 \geq 0$, $\lambda \geq 1$, *and* $\epsilon \geq 0$ *depending only on* $(X, \mathcal{B})$ *so that the following holds. Let* $R > R_0$, *let* H *be a hyperplane, and let* $B \cdot H$ *be an* R–*separated scattering of* H. *Let* $S = S_{H,B}$ *and* $\phi_{H,B}$ *be as in Definition 2.29. Then for any* $p, q \in S$ *we have*

$$(*) \quad d_X(\phi_{H,B}(p), \phi_{H,B}(q)) \leq d_S(p, q) \leq \lambda \, d_X(\phi_{H,B}(p), \phi_{H,B}(q)) + \epsilon.$$

Proof. We would like to apply Einstein's [15, Proposition 5.16], with $\mathcal{A}$ equal to the carriers of hyperplanes in the R–scattering $B \cdot H$, and $\mathcal{B}_0$ equal to the collection of peripheral complexes meeting some $A \in \mathcal{A}$. We have fixed a (δ, f) so that our pair $(X, \mathcal{B})$ is (δ, f)–relatively hyperbolic, but we have to temporarily modify f in order to apply Einstein's results. This is allowable because $(X, \mathcal{B})$ is also (δ, f')–relatively hyperbolic for any function f' which dominates f (in the sense that $f'(r) \geq f(r)$ for all r).

Hypothesis 5.5 of [15] requires that the pair $(X, \mathcal{B})$ is (δ, f')–relatively hyperbolic, and every $B \in \mathcal{B}$ is K–attractive, where $K(m) = 3f'(5\delta) + 21\delta + 6m$. Each $B \in \mathcal{B}$ is η–super-attractive. Thus by Remark 2.15, each $B \in \mathcal{B}$ is K_0–attractive, where $K_0(m) = 2\eta + 2m$. As long as K dominates K_0, each B will also be K–attractive. In order to ensure K

dominates K_0, we set

$$f'(r) = \max\{\eta, f(r)\}.$$

Since f' dominates f, the pair $(X, \mathcal{B})$ is still (δ, f')–relatively hyperbolic.

Now [15, Hypotheses 5.15] amounts to the assertion that $\mathcal{A}$ is an R–scattering for $R \geq 500f'(5\delta) + 10000\delta$. We therefore take

$$R_0 = 500f'(5\delta) + 10000\delta.$$

Then [15, Proposition 5.16] implies that $\phi_{H,B}$ is a (λ, ϵ)–quasi-isometry, for $(\lambda, \epsilon) = (2, 110f'(5\delta) + 1592\delta)$. These constants only depend on $(X, \mathcal{B})$. Since $\phi_{H,B}$ is obviously distance non-increasing, we have the inequalities $(*)$. $\qquad \square$

> We fix the constants R_0, λ, ϵ from Proposition 2.31 for the remainder of this section and the next.

The next lemma says that peripheral complexes in a thick carrier can only be close to each other if they are close to a hyperplane associated to the carrier.

Lemma 2.32. *There exists a function $F_{2.32}\colon \mathbb{R}_{\geq 0} \to \mathbb{R}_{\geq 0}$, depending only on $(X, \mathcal{B})$, so that the following holds whenever $R > R_0$.*

Let H be a hyperplane, let B be a broadcaster for H so that the associated scattering $B \cdot H$ is R–separated, and let $T(W_{H,B})$ be the corresponding thick carrier. For any $m \geq 0$ and any distinct peripheral complexes Z_1, Z_2 in $T(W_{H,B})$, there is some $g \in B$ so that

$$N_m(Z_1) \cap N_m(Z_2) \subseteq N_{F_{2.32}(m)}(gH).$$

Proof. Fix $p \in N_m(Z_1) \cap N_m(Z_2)$. For $i = 1, 2$, let p_i be a point of Z_i with $d_X(p_i, p) \leq m$, and let $\hat{p}_i$ be the corresponding point of the complex $S_{H,B}$. Using the second inequality of $(*)$ in Proposition 2.31, we have $d_S(\hat{p}_1, \hat{p}_2) \leq \lambda d_X(p_1, p_2) + \epsilon \leq 2\lambda m + \epsilon$. Choose gH so that the hyperplane carrier for gH separates Z_1 from Z_2 in the complex $S_{H,B}$. Any path from $\hat{p}_1$ to $\hat{p}_2$ in $S_{H,B}$ must pass through the carrier of gH, so in particular $d_S(\hat{p}_1, gH) \leq 2\lambda m + \epsilon + \frac{1}{2}$. Thus (using the first inequality of $(*)$) the distance between p and gH is at most $2\lambda m + \epsilon + m + \frac{1}{2}$. Since the diameter of $N_m(Z_1) \cap N_m(Z_2)$ is at most $f(m)$, we can set $F_{2.32}(m) = 2\lambda m + \epsilon + m + \frac{1}{2} + f(m)$. $\qquad \square$

For the next two results we prove, we need another result from Einstein [15]. Note that the result there uses peripheral cosets, whereas we will use the peripheral complexes $\mathcal{Z}$. Since their Hausdorff distance is finite, Proposition 2.34 follows from [15, Theorem 4.2].

Definition 2.33 (Relative fellow traveling). Let $l \geq 0$. Let σ_1 and σ_2 be two paths in X with the same endpoints, and suppose that these paths can be subdivided into an equal number of sub-paths, occurring in the same order. Suppose further that if $J_{\sigma_1} \subseteq \sigma_1$ and $J_{\sigma_2} \subseteq \sigma_2$ are corresponding subpaths (called *paired subpaths*), then they begin and end within l of one another and that either

(1) the Hausdorff distance between J_{σ_1} and J_{σ_2} is at most l; or
(2) there exists some $Z \in \mathcal{B}$ so $N_l(Z)$ contains both J_{σ_1} and J_{σ_2}.

Then σ_1 and σ_2 are said to l–*relatively fellow travel, relative to* $\mathcal{B}$.

Quasi-geodesics in spaces with relatively thin triangles relatively fellow travel one another:

Proposition 2.34. *(cf.* [15, Theorem 4.2], [25, Proposition 4.1.6]*) Let* $\mu \geq 1$ *and* $\varkappa \geq 0$. *There exists* l, *depending only on* μ, $\varkappa$, *and the pair* $(X, \mathcal{B})$, *so that* $(\mu, \varkappa)$–*quasi-geodesics with the same endpoints in* X *must* l–*relatively fellow travel, relative to* $\mathcal{B}$.

The following lemma says that if a geodesic spends any time in a peripheral complex, then a quasi-geodesic with the same endpoints must spend a similar amount of time close to that peripheral complex. (Recall that λ, ϵ are fixed constants coming from Proposition 2.31. If they were allowed to vary the lemma would still be true, but l' would have to be allowed to depend on them.)

Lemma 2.35. *There is an* l' *depending only on* $(X, \mathcal{B})$ *so that the following holds. Let* γ *be a geodesic in* X, *and let* σ *be a* (λ, ϵ)–*quasi-geodesic with the same endpoints as* γ. *Let* Z *be some peripheral complex so that* $\gamma' = \gamma \cap Z$ *is nonempty. Then there is a subpath* σ' *of* σ *whose endpoints are within* l' *of the endpoints of* γ', *and which is contained in an* l'–*neighborhood of* Z.

Proof. Let l be the constant of relative fellow travelling from Proposition 2.34 applied to (λ, ϵ)–quasi-geodesics.

We claim first that there are points on σ within

$$l_1 = \max\{2l + \eta, f(l) + l\}$$

of the endpoints of γ'. Indeed, let a be an endpoint of γ', and let J_γ, J_σ be paired subpaths of γ and σ so that J_γ contains a. There are three possibilities:

(1) J_γ and J_σ are Hausdorff distance at most l from each other;
(2) J_γ and J_σ are both contained in the l–neighborhood of Z, or
(3) J_γ and J_σ are both contained in the l–neighborhood of some peripheral complex $W \neq Z$.

In case (1) we find a point of σ at most l away from a. In case (2), we note that any component of $J_\gamma \setminus Z$ has diameter at most $l + \eta$, by η–super-attractiveness. Thus an endpoint of J_γ is at most $l + \eta$ from a. The corresponding endpoint of J_σ is at most $2l + \eta$ from a. In case (3), we note that $J_\gamma \cap Z$ has diameter at most $f(l)$, so there is an endpoint of J_γ at most $f(l)$ from a. The corresponding endpoint of J_σ is at most $f(l) + l$ from a. In any case we have found a point of σ at most l_1 away from a.

We let σ' be a subsegment of σ whose endpoints are at most l_1 from the endpoints of γ'. Let β be the path obtained from σ' by adjoining geodesics between the endpoints of γ' and those of σ'. Then β is a $(\lambda, \epsilon + 4l_1)$–quasi-geodesic with the same endpoints as γ. Let l_2 be the constant of relative fellow travelling from Proposition 2.34 applied to $(\lambda, \epsilon + 4l_1)$–quasi-geodesics. We claim that β (and hence σ') lies in an l_3–neighborhood of Z, where

$$l_3 = \frac{\lambda^2}{2} \left(f(l_2) + 2l_2 + \epsilon + 4l_1 \right) + \epsilon + 4l_1 + l_2.$$

Indeed, let b be a point of β, and let $J_{\gamma'}$ and J_β be paired subpaths of γ' and β so that $b \in J_\beta$. As before there are three possibilities:

(1) $J_{\gamma'}$ and J_β are Hausdorff distance at most l_2 from each other;
(2) $J_{\gamma'}$ and J_β are both contained in the l_2–neighborhood of Z, or
(3) $J_{\gamma'}$ and J_β are both contained in the l_2–neighborhood of some peripheral complex $W \neq Z$.

In cases (1) and (2) there is clearly a point of Z within l_2 of b. In case (3), the diameter of $N_{l_2}(W) \cap N_{l_2}(Z)$ is at most $f(l_2)$. Thus the segment $J_{\gamma'}$ has length at most $f(l_2)$. The endpoints of J_β are thus at most $f(l_2) + 2l_2$ apart from one another. A computation shows that b is at most

$$\frac{\lambda^2}{2} \left(f(l_2) + 2l_2 + \epsilon + 4l_1 \right) + \epsilon + 4l_1$$

from one of these endpoints, and thus at most l_3 from some point on $\gamma' \subseteq Z$.

Setting $l' = l_3$, we have established the lemma. $\square$

The next lemma shows that a thick carrier which has large coarse intersection with a peripheral complex must contain that peripheral complex.

Lemma 2.36. *There exists a function $F_{2.36} \colon \mathbb{R}_{\geq 0} \to \mathbb{R}_{\geq 0}$ and a constant $R_1 \geq R_0$ depending only on $(X, \mathcal{B})$ so that the following holds. Let $B \cdot H$ be an R–separated scattering of some hyperplane H, where*

$R > R_1$. *Let $T = T(W_{H,B})$ be the associated thick carrier, and let Z be a peripheral complex.*

For any $d \geq 0$, if

$$\mathrm{diam}(Z \cap N_d(T)) \geq F_{2.36}(d),$$

then $Z \subseteq T$.

Proof. We take $R_1 = \max\{R_0, f(l')\}$, where l' is the constant from Lemma 2.35, and suppose $R \geq R_1$. Our proof is based on the following claim.

Claim. *There is an L_0 depending only on $(X, \mathcal{B})$ so that if $a, b \in T$ and $[a, b]$ has a subsegment of length $> L_0$ in some peripheral complex Z, then $Z \subseteq T$.*

Given the claim, we argue as follows. Fix $d > 0$. We define $F_{2.36}(d) = L_0 + 4d + 2\eta$. Suppose that x and y satisfy the following three properties:

(1) $x, y \in Z$;
(2) $d(x, y) > F_{2.36}(d)$; and
(3) $d(x, T)$ and $d(y, T)$ are at most d.

Let x', y' be closest points on T to x, y respectively. We have $d(x', y') > L_0 + 2d + 2\eta$. By η–super-attractiveness, a subsegment of $[x', y']$ of length greater than L_0 lies in Z. Applying the Claim with $a = x', b = y'$, we conclude $Z \subseteq T$.

It remains to prove the claim.

Proof of Claim. We prove the claim with $L_0 = 2f(l') + 4l' + 2\eta$. Let T be the thick carrier as in the statement of the lemma and $S = S(W_{H,B})$ the associated abstract complex. Let σ be the (λ, ϵ)–quasi-geodesic joining a to b which is the image of a geodesic in S. Suppose that $\gamma = [a, b]$ is the X–geodesic with the same endpoints and that γ intersects the peripheral complex Z in a segment γ' of length greater than L_0. Lemma 2.35 gives a subpath σ' of σ starting and ending within l' of the endpoints of L_0, so that σ' is contained in the l'–neighborhood of Z.

This subpath σ' must have length bigger than $L_0 - 2l' = 2f(l') + 2l' + 2\eta$; it is a broken geodesic made alternately of segments inside peripheral complexes and carriers of hyperplanes.

If there are four or more such subsegments, one is a peripheral segment between two different hyperplane carriers in the R–scattering; in particular it has length at least $R > f(l')$. But since the endpoints of this peripheral segment are within l' of Z, the peripheral segment must actually be a Z–segment, and so Z was in T to begin with. A similar

argument shows $Z \subseteq T$ if σ' begins or ends with a peripheral segment of length bigger than $f(l')$.

If there is a hyperplane segment of length greater than $2l' + 2\eta$, then the η–super-attractiveness of Z implies that this hyperplane segment meets Z. In particular a hyperplane of the scattering meets Z, and again we conclude that $Z \subseteq T$.

The only remaining possibility is that σ' consists of three or fewer segments, at most one of which is a (short) hyperplane segment. The total length of σ' is thus at most $2f(l') + 2l' + 2\eta$, contrary to our choice of L_0. This completes the proof of the claim. $\qquad \square$

Once the claim is proved, the lemma is proved. $\qquad \square$

Proposition 2.37. *There is a Q depending only on $(X, \mathcal{B})$ so that the following holds. Let $R > R_1$, where R_1 is the constant from Lemma 2.36. Let $B \cdot H$ be an R–separated scattering of some hyperplane H of X. The thick carrier $T(W_{H,B})$ is Q–quasi-convex in X.*

Proof. We prove the Proposition with $Q = 2l + \eta + \frac{1}{2}F_{2.36}(2l + \eta)$, where l is the constant of relative fellow-traveling of (λ, ϵ)–quasi-geodesics in $(X, \mathcal{B})$, η is the super-attractiveness constant of elements of $\mathcal{B}$, and $F_{2.36}$ is the function from Lemma 2.36.

Let $T = T(W_{H,B})$, and let $S = S(W_{H,B})$. Recall that T is the image of S under a (λ, ϵ)–quasi-isometric embedding (Proposition 2.31). Let γ be a geodesic with endpoints in T, and let σ be the image of an S–geodesic with the same endpoints. Since S is (λ, ϵ)–quasi-isometrically embedded, σ is a (λ, ϵ)–quasi-geodesic in X. In particular it l–relatively fellow travels γ relative to $\mathcal{B}$.

Let J_γ and J_σ be paired subpaths of γ and σ respectively. In case they are Hausdorff distance l from each other, we clearly have $J_\gamma \subseteq N_Q(T)$. Otherwise, they are both in the l–neighborhood of some peripheral complex Z. If the length of J_γ is at most $2(l + \eta) + F_{2.36}(2l + \eta)$, it is also contained in the Q–neighborhood of T, since its endpoints are distance at most l from the endpoints of $J_\sigma \subseteq T$. Otherwise, the η–super-attractiveness of Z implies that there is a subsegment of J_γ of length at least $F_{2.36}(2l + \eta)$, whose endpoints are distance at most $l + \eta$ from the endpoints of J_γ, hence at most $2l + \eta$ from the endpoints of J_σ. Lemma 2.36 then shows that $Z \subseteq T$, so $J_\gamma \subseteq N_Q(T)$ in this case as well. $\qquad \square$

2.4. **The wallspace.** We now construct the wallspace which we use to build the cubulation for Theorem C. In order to do this, we first fix some constants, and our assumptions on the constant of separatedness of the scatterings we use.

Notation 2.38. *Let η be as in Proposition 2.19 and suppose that $\mathcal{B}$ is a collection of convex η–super-attractive complexes as in Definition 2.20. Let δ and f be so that $(X, \mathcal{B})$ is (δ, f)–relatively hyperbolic, as in the conclusion of Lemma 2.21. Let $n = \dim(X)$.*

We now recall and fix some more constants, and note that like η, δ, f and n, all of them depend only on the pair $(X, \mathcal{B})$.

The constant R_1 previously appeared in Lemma 2.36 and Proposition 2.37. We will assume that all scatterings are R–scatterings for some $R > R_1$.

   (1) $C = C(\delta, f)$ is the bound on the diameter of projections of peripheral complexes to one another (see Corollary 2.18).
   (2) Q is the constant of quasi-convexity of thick carriers of scatterings (see Proposition 2.37);
   (3) $\theta_n = \arcsin(\frac{1}{\sqrt{n}})$ (a geodesic in X which is not too short must meet some hyperplane at this angle or greater, see Lemma 3.15 below).

Notation 2.39. *The following constants also depend only on the pair $(X, \mathcal{B})$. They may seem somewhat mysterious but we need to choose them carefully now in order to fix $R_\star$ below.*

   (1) (first used in Lemma 3.21);

$$\kappa = F_{2.32}(Q + 1) + 2Q + C + \frac{\sqrt{n}}{2} + 2$$

   (2) (first used in Lemma 3.17)

$$\omega = 2F_{2.36}(0) + \left(8 + \frac{2}{\sin(\frac{\theta_n}{2})} \right) Q + 20\eta + 8f(\delta) + 16\delta + 2\sqrt{n};$$

   (3) (first used in Lemma 3.17)

$$\tau = F_{2.32}(Q) + \left(3 + \frac{1}{\sin(\frac{\theta_n}{2})} \right) Q + 4\eta + f(\delta) + 2\delta + \frac{\sqrt{n}}{2};$$

   (4) (first used in Definition 3.22)

$$D = \max \left\{ 2\sqrt{n}\kappa + \sqrt{n}, \ F_{2.36}(0) + 6\eta + 2f(\delta) + 6\delta, \ 2C + 1 \right\} + 1$$

Assumption 2.40. *Fix once and for all some number $R_\star$ so that $R_\star$ is strictly bigger than all of the following:*

   (1) (Required so Propositions 2.31 and 2.37 may be applied)

$$R_1$$

   (2) (required in Proposition 3.19)

$$F_{2.36}(0) + 4(\eta + \delta) + 2f(\delta) + \tau$$

(3) (required in Proposition 3.23)

$$8(Q + F_{2.32}(Q) + 2\eta + \delta + \frac{1}{2}f(\delta))$$

(4) (required in Proposition 3.23)

$$\frac{8}{3}(D + 2\eta + 2\delta + f(\delta))$$

(5) (required in Lemma 3.24)

$$D + \tau$$

(6) (required in Lemma 3.27)

$$\frac{8}{3}\left(26 \cdot \max\left\{f(5\delta), \eta, \frac{1}{3}\max\{\omega, 2(D+\tau)\}\right\} + 250\delta\right)$$

The constant $R_\star$ is the same for the remainder of this section and the next; we only consider $R_\star$–scatterings from now on.

Definition 2.41 (The wallspace $(X^{(0)}, \mathcal{W})$). Choose representatives H_i of the finitely many G–orbits of hyperplanes of X, and for each i choose a broadcaster B_i so that $B_i \cdot H_i$ is an $R_\star$–separated scattering. Such a broadcaster exists by Proposition 2.25. Let $W_i = W_{H_i,B_i}$ be the wall from Definition 2.26 and let $\phi_i = \phi_{H_i,B_i}$ be the map defined in Definition 2.29. It follows that $T(W_i)$, ϕ_i satisfy the conclusion of Propositions 2.31 and 2.37. Let

$$\mathcal{W} = \{gA \mid g \in G, A \in W_i \text{ for some } i\}.$$

Since $\mathcal{W}$ is defined G–equivariantly, there is an action of G on the wallspace $(X^{(0)}, \mathcal{W})$.

The following is immediate from the fact that walls are unions of hyperplanes in X and from the equivalence relation defined in Definition 2.26.

Lemma 2.42. *Let v, w be adjacent vertices of X. Then there is exactly one wall of $\mathcal{W}$ separating v from w.*

Definition 2.43. Lemma 2.42 says in particular that each hyperplane of X is associated to a single wall W of $\mathcal{W}$. Such a hyperplane is called a W–*hyperplane*. Let $W = gW_{H_i,B_i}$ for some $g \in G$ and one of the hyperplanes H_i discussed in Definition 2.41. We write $T(W)$ for the complex $gT(W_{H_i,B_i})$ and note that it is Q–quasi-convex and a (λ, ϵ)–quasi-isometric image of S_{H_i} (see Proposition 2.31). We refer to $T(W)$ as the *thick carrier for W*. If Z is one of the peripheral complexes used to build S_{H_i}, then gZ is called a W–*peripheral complex*.

Lemma 2.44. *Let Z be a peripheral complex and let W be a wall. Then Z is a W–peripheral complex if and only if W separates two vertices of Z.*

Lemma 2.45. *The collection $\mathcal{W}$ defined in Definition 2.41 makes $X^{(0)}$ into a space with walls.*

Proof. We must show the finiteness condition $(\star)$ from Definition 2.1. But Lemma 2.42 implies that the number of walls in $\mathcal{W}$ separating two vertices is at most their distance in $X^{(1)}$. $\qquad\square$

3. Ultrafilters and Stabilizers for the action

The goal of this section is to prove Theorem C. To that end, we fix a wallspace structure $(X^{(0)}, \mathcal{W})$ as described in Definition 2.41. By Sageev's construction this gives rise to a new CAT(0) cube complex $\widehat{X} = C(\mathcal{W})$ with a G–action. Many properties of this cube complex (for instance dimension and the precise vertex stabilizers) depend strongly on the choices made in the last section. However, as long our cube complex is built from $R_\star$–scatterings where $R_\star$ satisfies Assumption 2.40, this cube complex will satisfy the conclusions of Theorem C.

We briefly recall the Sageev construction (see [37, 38, 28] for more details). Given a wallspace $(S, \mathcal{V})$, an *ultrafilter* on $(S, \mathcal{V})$ is a subset $\mathfrak{U}$ of $\mathcal{V}$ satisfying the following two properties:

(1) (Consistency) If $A \subseteq B$ are two halfspaces and $A \in \mathfrak{U}$, then $B \in \mathfrak{U}$; and

(2) (Completeness) If A is a halfspace, then either A or A^c is in $\mathfrak{U}$.

A *DCC ultrafilter* is one which contains no infinite descending chain

$$A_1 \supsetneq A_2 \supsetneq \cdots.$$

Convention 3.1. *All ultrafilters considered below are assumed to be DCC.*

An ultrafilter is *principal* if, for some $x \in S$, it is of the form:

$$\mathfrak{U}[x] := \{A \in \mathcal{V} \mid x \in A\}.$$

Notation 3.2. *Completeness means we can also think of an ultrafilter $\mathfrak{U}$ as a function from the set of walls to the set of halfspaces. Abusing notation slightly, if $W = \{A, A^c\}$ is a wall and $\mathfrak{U}$ is an ultrafilter so $A \in \mathfrak{U}$, we write $\mathfrak{U}(W) = A$.*

We build a cube complex $C'(\mathcal{V})$ as follows. The 0–cells are the DCC ultrafilters on $\mathcal{V}$. Two ultrafilters are connected by an edge if they

differ on a single wall. (In other words $\mathfrak{U}_1 = (\mathfrak{U}_2 \setminus \{A\}) \cup \{A^c\}$.) Higher dimensional cubes are added wherever their 1–skeleta appear. The principal ultrafilters all lie in the same component of $C'(\mathcal{V})$, and it is this component which we name $C(\mathcal{V})$. We say $C(\mathcal{V})$ is *the cube complex obtained by applying the Sageev construction to $\mathcal{V}$*.

The following result is essentially due to Sageev, though he did not phrase things in terms of wallspaces. See [28, Section 3], and the references therein. See also [38, 36] for a slightly more general discussion of the cube complex dual to a "pocset" (poset with complementation).

Theorem 3.3. [37] *For any wallspace $(S, \mathcal{V})$, the cube complex $C(\mathcal{V})$ is* CAT(0).

3.1. **Parabolic sub-complexes of $\widehat{X}$ are finite.** In [28, Section 3.4], Hruska and Wise introduce the notion of a *hemiwallspace*, a subcollection of the halfspaces of a wallspace containing at least one from every wall. When $(S, \mathcal{V})$ is a wallspace and $T \subseteq S$, one obtains the *hemiwallspace induced by T* (see [28, Example 3.20]):

$$\mathcal{V}_T = \{U \in \mathcal{V} \mid U \cap T \neq \emptyset\}.$$

This hemiwallspace also gives rise to a cube complex $C(\mathcal{V}_T)$ defined to be the cube complex obtained by applying the Sageev construction to the collection of halfspaces in $\mathcal{V}_T$ whose complements are also in $\mathcal{V}_T$. We have the following result of Hruska–Wise.

Lemma 3.4. [28, Lemmas 3.23, 3.24] *The cube complex $C(\mathcal{V}_T)$ embeds naturally into $C(\mathcal{V})$ as a convex sub-complex.*

We apply this result with $S = X^{(0)}$, $\mathcal{V} = \mathcal{W}$, and $T = Y^{(0)}$ for Y equal to some peripheral complex. In this case we have:

Proposition 3.5. $C(\mathcal{W}_{Y^{(0)}})$ *is a finite cube complex.*

Proof. We show that there are only finitely many walls $W \subseteq \mathcal{W}$ so that $W \subseteq \mathcal{W}_{Y^{(0)}}$. The Sageev construction applied to a wallspace with finitely many walls yields a finite cube complex, so this establishes the proposition.

Suppose that $W = \{W^+, W^-\} \subseteq \mathcal{W}_{Y^{(0)}}$. This means both $W^+ \cap Y^{(0)}$ and $W^- \cap Y^{(0)}$ are nonempty. We first show that W is determined by the partition

$$\{W^+ \cap Y^{(0)}, W^- \cap Y^{(0)}\}.$$

Indeed, since Y is connected, there is a pair of adjacent vertices $v, w \in Y^{(0)}$ lying in different halfspaces. But Lemma 2.42 shows that W is the only wall in $\mathcal{W}$ separating v from w.

We next claim that there is a fixed finite index subgroup of $\mathrm{Stab}(Y)$ which preserves the partition $\{W^+ \cap Y^{(0)}, W^- \cap Y^{(0)}\}$ for every $W \subseteq \mathcal{W}_{Y^{(0)}}$. Each such partition is is preserved by some finite index subgroup of $\mathrm{Stab}(Y)$ conjugate in G to one of the subgroups of the $\mathrm{Stab}(Y_j)$ in the definition of the broadcasters for the H_i. There are only finitely many such subgroups of $\mathrm{Stab}(Y)$, so some finite index subgroup N_Y of $\mathrm{Stab}(Y)$ is contained in all of them. In particular, W descends to a partition of $_{N_Y}\backslash Y^{(0)}$, and is determined by that partition.

Since there are only finitely many partitions of a finite set, the set of walls in $\mathcal{W}_{Y^{(0)}}$ is finite. $\qquad\square$

Work of Hruska–Wise [28] gives the following.

Corollary 3.6. *The action of G on $C(\mathcal{W})$ is cocompact. In particular $C(\mathcal{W})$ is finite dimensional. Moreover each $P \in \mathcal{P}$ fixes a point of $C(\mathcal{W})$.*

Proof. By Lemma 2.27, the wall stabilizers for $G \curvearrowright \mathcal{W}$ are full relatively quasi-convex.

Theorem 7.12 of [28] (with $\heartsuit = \frac{1}{4}$) shows that for $(G, \mathcal{P})$ relatively hyperbolic acting on a wallspace with relatively quasi-convex wall stabilizers, the G–action on the associated cube complex is "relatively cocompact." Since the sub-complexes associated to the peripheral subgroups are compact (cocompact under the action of the peripheral subgroups is enough), the G–action is cocompact.

Let $P \in \mathcal{P}$. Then P preserves a peripheral complex $Y \subseteq X$, so it preserves the convex sub-complex $C(\mathcal{W}_{Y^{(0)}}) \subseteq \widehat{X}$. As this is a complete bounded diameter CAT(0) space (Proposition 3.5), there is a fixed point for the action of P (see [6, II.2.8]). $\qquad\square$

3.2. **Associating a characteristic subspace of X to an ultrafilter.** In general not every ultrafilter $\mathfrak{U}$ on $\mathcal{W}$ is principal. In other words the intersection of all the halfspaces in $\mathfrak{U}$ may be empty. We show in this subsection that by appropriately augmenting and thickening the halfspaces of $\mathfrak{U}$ we do obtain a nonempty intersection (see Proposition 3.12).

Definition 3.7 (Halfspace carriers)**.** In Definition 2.43 we defined thick carriers for walls. If $W = \{A, A^c\}$, then define the *halfspace carrier* $\overline{A}$ to be the full sub-complex of X on $A \cup \left(T(W) \cap X^{(0)} \right)$.

The full sub-complex on a halfspace A is not connected, but the halfspace carrier is connected, as the following lemma shows. We will use the observations in this lemma repeatedly in the rest of the section.

Lemma 3.8. *Let $A \in \mathcal{W}$ be a halfspace. Then $\overline{A}$ is a connected subcomplex of X. Moreover, $\overline{A} \cap \overline{A^c} = T(W)$ and $\overline{A} \cup \overline{A^c} = X$.*

Proof. Every component of the full subcomplex on A meets $T(W)$, which is connected. Thus $\overline{A}$ is connected.

The intersection of full subcomplexes is a full subcomplex, so $\overline{A} \cap \overline{A^c}$ is the full subcomplex on the zero-skeleton of $T(W)$. This is $T(W)$.

Any cube of X with all its vertices in A is in the full subcomplex on A, so it is contained in $\overline{A}$. Similarly any cube of X with all its vertices in A^c is contained in $\overline{A^c}$. A cube with vertices in both A and A^c must be in the carrier of some hyperplane of the scattering associated to W, hence in $T(W)$. So $\overline{A} \cup \overline{A^c} = X$. $\qquad\square$

Next we show that halfspace carriers have the same "attractiveness" property as we showed for thick carriers in Lemma 2.36.

Lemma 3.9. *Let $m > 0$ and let $F_{2.36}(m)$ be as in Lemma 2.36. Let $\overline{A}$ be a halfspace carrier and let Z be a peripheral complex. If*

$$\mathrm{diam}(Z \cap N_m(\overline{A})) \geq F_{2.36}(m),$$

then $Z \subseteq \overline{A}$.

Proof. Let $W = \{A, A^c\}$ be the associated wall and let $T = T(W)$. If Z contains vertices of both A and A^c, it must meet some W–hyperplane, so $Z \subseteq T \subseteq \overline{A}$. If Z contains only vertices of A then $Z \subseteq \overline{A}$.

We are left with the case that every vertex of Z is in A^c. Let $x, y \in Z \cap N_m(\overline{A})$. Since x, y are not in A, a shortest path to $\overline{A}$ must pass through T, so they are in $N_m(T)$. Using the case of wall carriers, if $d(x, y) \geq F_{2.36}(m)$, then $Z \subseteq T \subseteq \overline{A}$, and we are done. $\qquad\square$

Lemma 3.10. *Suppose W, V are walls of $\mathcal{W}$ so that $V^+ \subseteq W^+$. Then $T(V) \subseteq \overline{W^+}$.*

Proof. It is enough to show that if $v \in T(V)^{(0)}$, then $v \in \overline{W^+}$. If v is in the carrier of a V–hyperplane, it is distance ≤ 1 from a vertex in V^+. Since the W–hyperplanes and the V–hyperplanes are disjoint, this means v must actually be in W^+.

Suppose then that v is contained in a V–peripheral complex Z, and that $v \in W^-$. Since Z is a V–peripheral complex, by Lemma 2.44 it must contain vertices in both V^+ and V^-. In particular it contains some $w \in V^+ \subseteq W^+$. Since Z contains vertices of both W^+ and W^-, it must also be a W–peripheral complex, and so $Z \subseteq \overline{W^+}$. $\qquad\square$

We next prove a lemma about coarse intersections of thick carriers of crossing walls.

Lemma 3.11. *For each positive integer m there exists a $\Theta_m \geq 0$ so that for any collection of pairwise crossing walls $\{W_0, \ldots, W_m\}$ of $\mathcal{W}$,*

$$\bigcap_{i=0}^{m} N_{\Theta_m}(T(W_i)) \neq \emptyset.$$

Proof. The proof is by induction, so we start by establishing the base case $m = 1$. We prove the contrapositive with $\Theta_1 = 0$. Suppose that there are walls W_0, W_1, so that $T(W_0) \cap T(W_1) = \emptyset$. Since $X = \overline{W_1^+} \cup \overline{W_1^-}$, we have $T(W_0) \subseteq \overline{W_1^+} \cup \overline{W_1^-}$. On the other hand $T(W_0)$ does not meet $T(W_1) = \overline{W_1^+} \cap \overline{W_1^-}$. It is therefore contained in a connected component of $X \setminus T(W_1)$. Each such connected component is contained either in the full subcomplex on W_1^+ or the full subcomplex on W_1^-. In particular we have $T(W_0)^{(0)} \subseteq W_1^+$ or $T(W_0)^{(0)} \subseteq W_1^-$.

Arguing similarly for $T(W_1)$, there are $\epsilon_0, \epsilon_1 \in \{\pm\}$ so that

$$T(W_0)^{(0)} \subseteq W_1^{\epsilon_1}, \quad T(W_1)^{(0)} \subseteq W_0^{\epsilon_0},$$

but this implies $W_1^{-\epsilon_1} \cap W_0^{-\epsilon_0} = \emptyset$. In other words W_0 and W_1 do not cross.

For the inductive step suppose that $W_0, \ldots, W_m$ pairwise cross, and let $T_i = T(W_i)$ for each i. The base case implies that $T_0 \cap T_m \neq \emptyset$, whereas the inductive hypothesis implies that

$$I_1 := N_{\Theta_{m-1}}(T_0) \cap \cdots \cap N_{\Theta_{m-1}}(T_{m-1}) \text{ and}$$
$$I_2 := N_{\Theta_{m-1}}(T_1) \cap \cdots \cap N_{\Theta_{m-1}}(T_m)$$

are nonempty. Take $a \in I_1$, $b \in I_2$, and $c \in T_0 \cap T_m$, and consider the geodesic triangle Δ with corners a, b, c. Let $L_m = F_{2.36}(Q + \Theta_{m-1})$. We may assume without loss of generality that $L_m \geq \delta$, where δ is the relatively thin triangles constant for $(X, \mathcal{B})$. We argue that we can take $\Theta_m = Q + \Theta_{m-1} + 2L_m + 2\delta$.

Suppose first that the δ–fat part of Δ contains a segment of length at least L_m in each side. Then in particular there is some peripheral complex Z so that Δ is δ–thin relative to Z. Lemma 2.36 applied to the side $[a, c]$ implies that Z is contained in T_0; the same lemma applied to $[b, c]$ implies that Z is contained in T_m; and the same lemma applied to $[a, b]$ implies Z is contained in each of $T_1, \ldots, T_{m-1}$. In particular $Z \subseteq \bigcap_{i=0}^{m} T_i$.

If on the other hand some δ–fat part of a side of Δ has length bounded above by L_m, then Lemma 2.4 shows that Δ is $(2L_m + 2\delta)$–thin. In particular if x is the point on $[a, b]$ which is in the preimage of the central point of the comparison tripod for Δ, then x is contained in the

intersection of the Θ_m–neighborhoods of the thick carriers $T_0, \ldots, T_m$.
$\square$

The main result of this subsection is the following.

Proposition 3.12. *Let $\mathfrak{U}$ be a DCC ultrafilter. There is some $K \geq 0$ so that $\bigcap\limits_{A \in \mathfrak{U}} N_K(\overline{A}) \neq \emptyset$.*

Proof. We inductively define a certain collection of pairwise crossing walls $W_0, \ldots, W_k$, and show that the coarse intersection of their carriers is coarsely contained in every halfspace of $\mathfrak{U}$.

To begin, choose A_0 minimal in $\mathfrak{U}$ (with respect to inclusion) and let $W_0 = \{A_0, A_0{}^c\}$. Note that such an A_0 exists because $\mathfrak{U}$ is DCC. Suppose now we have chosen $W_0, \ldots, W_{s-1}$, and let I_s be the set of walls which cross W_i for all $i < s$. If I_s is nonempty, let A_s be a minimal element of $\{\mathfrak{U}(W) \mid W \in I_s\}$, and let $W_s = \{A_s, A_s{}^c\}$. By Corollary 3.6, the dimension of $C(\mathcal{W})$ is finite. For s bigger than this dimension, the set I_s is empty, so the process of choosing the W_i eventually terminates.

Let $W_0, \ldots, W_k$ be the resulting collection, and let $T_i = T(W_i)$. Now we decompose $\mathfrak{U}$ as $\mathfrak{U}_0 \sqcup \cdots \sqcup \mathfrak{U}_k$, where

$$\mathfrak{U}_0 = \{A \in \mathfrak{U} \mid \{A, A^c\} \text{ does not cross } W_0\},$$

and for $i > 1$,

$$\mathfrak{U}_i = \{A \in \mathfrak{U} \mid \{A, A^c\} \text{ crosses } W_0, \ldots, W_{i-1} \text{ but does not cross } W_i\}.$$

The minimality assumptions on the W_i imply that if $A \in \mathfrak{U}_i$, then $\mathfrak{U}(W_i) \subseteq A$. By Lemma 3.10, this implies that $T_i \subseteq \overline{A}$. In particular, we have

$$\bigcap_{i=1}^{k} N_{\Theta_k}(T_i) \subseteq \bigcap_{A \in \mathfrak{U}} N_{\Theta_k}(\overline{A}).$$

Lemma 3.11 shows that the left hand side is nonempty, and the Proposition follows, with $K = \Theta_k$. $\square$

3.3. **Classification of stabilizers.** Given a DCC ultrafilter $\mathfrak{U}$, fix K so that

$$N_K(\mathfrak{U}) := \bigcap_{A \in \mathfrak{U}} N_K(\overline{A})$$

is nonempty. The existence of such a K is guaranteed by Proposition 3.12. We observe:

Lemma 3.13. *The stabilizer of $N_K(\mathfrak{U})$ contains the stabilizer of $\mathfrak{U}$.*

Since the action of G on X is proper, we immediately obtain:

Corollary 3.14. *If $N_K(\mathfrak{U})$ is bounded, then $\mathrm{Stab}(\mathfrak{U})$ is finite.*

We thus focus on the case that $N_K(\mathfrak{U})$ is unbounded. In this case, we will see in Proposition 3.19 below that there is always at least one peripheral complex contained in $N_K(\mathfrak{U})$, in fact in the intersection $N_0(\mathfrak{U})$ of the carriers themselves. Although the constant K depends on $\dim(C(\mathcal{W}))$, and hence is *not* independent of the choice of $R_\star$ made in Assumption 2.40, this constant will disappear from the discussion once we have found this peripheral complex in $N_0(\mathfrak{U})$.

We need a lemma about the geometry of CAT(0) cube complexes, which is very similar to Remark 3.2 of Sageev–Wise [39].

Lemma 3.15. *Let Ξ be a k–dimensional CAT(0) cube complex, and let $\theta_k = \arcsin(\frac{1}{\sqrt{k}})$. Let d_Ξ be the CAT(0) metric on Ξ. Suppose that $d_\Xi(x,y) > 2\sqrt{k}$, and let m be the midpoint of $[x,y]$. Then there is a hyperplane H meeting $[x,y]$ within $\frac{\sqrt{k}}{2}$ of m, and making an angle of at least θ_k with $[x,y]$. This hyperplane satisfies $d_\Xi(H, \{x,y\}) > \frac{d_\Xi(x,y) - \sqrt{k}}{2\sqrt{k}}$.*

Proof. The idea here is from Section 3 of [39]. In [39, Lemma 3.1] it is shown that if $\mathbf{v}$ is a nonzero vector in $\mathbb{R}^k$, and $\mathcal{E}$ is the standard basis of $\mathbb{R}^k$, then there is a subset $\mathcal{E}' \subseteq \mathcal{E}$ of cardinality $k-1$ so that every vector in the hyperplane spanned by $\mathcal{E}'$ makes an angle of at least θ_k with $\mathbf{v}$. It is observed in [39, Remark 3.2] that if γ is a ray starting at a corner of a cube σ and with a nondegenerate initial segment in σ, then γ meets some midcube of σ at an angle of at least θ_k.

The difference in our situation is that m need not be a vertex. There is however some nondegenerate segment $\sigma = [m, m']$ contained in a cube σ of Ξ, which we suppose is of minimal dimension to contain such a segment. Let σ' be a maximal length parallel segment beginning at a vertex of σ. By [39, Remark 3.2], there is a midcube of σ meeting σ' at an angle of at least θ_k. Let H be the hyperplane determined by this midcube. We show that $[x,y]$ meets H as in the conclusion of the lemma.

The carrier C of H can be identified with $H \times [0,1]$, where H is identified with $H \times \{\frac{1}{2}\}$. Let $\lambda \colon [0,T] \to H \times [0,1]$ be a unit speed geodesic with image the intersection of $[x,y]$ with C. The geodesic λ projects to constant speed geodesics $\lambda_H \colon [0,T] \to H$ and $\lambda_I \colon [0,T] \to [0,1]$. Any geodesic in C makes a well-defined constant angle $\arctan(\dot{\lambda}_I/\dot{\lambda}_H)$ with H, and this angle is invariant under translation inside a cube. Since the angle is at least $\theta_k = \arcsin(\frac{1}{\sqrt{k}})$, the length T of λ is at most $\sqrt{k}$. In particular neither x nor y lies in C, and λ_I is surjective. Let $t \in [0,T]$ satisfy $\lambda_I(t) = \frac{1}{2}$, so $\lambda(t)$ lies on the hyperplane H. The distance from $\lambda(t)$ to m is at most $\frac{T}{2} \le \frac{\sqrt{k}}{2}$.

The last assertion is an easy calculation.   □

In the next lemma we return to the setting of our (δ, f)–relatively hyperbolic pair $(X, \mathcal{B})$.

Lemma 3.16. *(Pushing across triangles) Suppose that $a, b, c \in X$, $Z \in \mathcal{B}$, and that there is a subsegment $[x, y] \subseteq [a, b] \cap Z$ satisfying:*

(1) The length of $[x, y]$ is at least $2\delta + 2\eta + f(\delta)$; and
(2) $[x, y]$ does not cross the internal point of $[a, b]$, in other words $d(a, x) < d(a, y) \leq (b, c)_a$.

Then there is a subsegment $[x', y'] \subseteq [a, c] \cap Z$ with $|d(a, x') - d(a, x)| \leq \delta + \eta$ and $|d(a, y') - d(a, y)| \leq \delta + \eta + f(\delta)$.
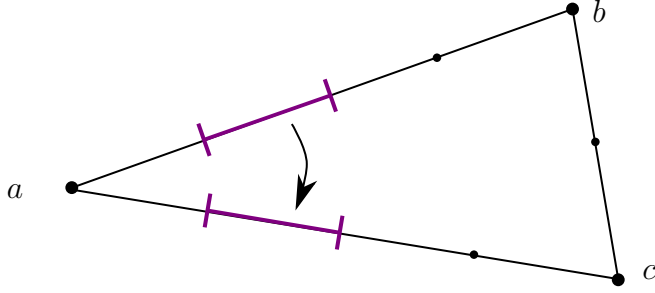

FIGURE 2. Lemma 3.16. The small points are the points in the preimage of the central point of the comparison tripod.

Proof. Let Δ be the triangle with corners a, b, c. Let $\pi \colon \Delta \to T_\Delta$ be the canonical map to a comparison tripod T_Δ. Let $I = [x, y]$. The assumptions on $d(a, x)$ and $d(a, y)$ imply that $\pi(I)$ lies entirely in one leg of T_Δ. Let I' be the subsegment of $[a, c]$ with the same image in T_Δ. There are three cases.

In case Δ is δ–thin, the segment I' has endpoints δ–close to those of I. In particular it begins and ends within δ of Z, so it intersects Z in a subsegment whose endpoints are at most $\eta + \delta$ from those of I', and we are finished.

In case Δ is δ–thin relative to Z, then every point of I' is within δ of some point of I or some point of Z. Since $I \subseteq Z$, the segment I' begins and ends within δ of Z as before.

In case Δ is δ–thin relative to some $W \neq Z$, we note that the δ–fat part of $[a, b]$ can intersect I in a segment of length at most $f(\delta)$. Removing the δ–fat part thus leaves a subsegment I_0. The corresponding subsegment $I_0' \subseteq I'$ begins and ends within δ of Z, and so we can find a subsegment of I_0' with the desired properties.   □

The main use of the next two lemmas is in the proof of Proposition 3.19, which says that whenever $N_K(\mathfrak{U})$ is unbounded $N_0(\mathfrak{U})$ contains a peripheral complex. Both will be used again later in slightly simpler circumstances.

In the following statement ω and τ are the constants which were fixed in Notation 2.39; their definitions are recalled in the proof.

Lemma 3.17. *For any $J \geq 0$, if $x, y \in N_J(\mathfrak{U})$ satisfy $d(x, y) > \left(\frac{2\pi}{\theta_n} + 2\right) J + \omega$, then there is a peripheral complex Z which intersects $[x, y]$ in a subsegment I so that*

(1) the length of I is at least $\min\{R_\star - \tau, \frac{1}{2}d(x, y) - \tau - J\}$, and
(2) the distance from I to the midpoint of $[x, y]$ is at most τ.

Proof. We first remark that it is easy to check that $\left(\frac{2\pi}{\theta_n} + 2\right) \geq 2\sqrt{n} + 2$. Recall from Notation 2.39 the definition of the following two constants:

$$\omega = 2F_{2.36}(0) + \left(8 + \frac{2}{\sin(\frac{\theta_n}{2})}\right) Q + 20\eta + 8f(\delta) + 16\delta + 2\sqrt{n},$$

and

$$\tau = F_{2.32}(Q) + \left(3 + \frac{1}{\sin(\frac{\theta_n}{2})}\right) Q + 4\eta + f(\delta) + 2\delta + \frac{\sqrt{n}}{2};$$

Since $d(x, y) \geq \omega \geq 2\sqrt{n}$, we can apply Lemma 3.15 to find a hyperplane H meeting $[x, y]$ at an angle of at least θ_n, at a point $z \in [x, y]$ satisfying

$$(3) \qquad\qquad d(z, \{x, y\}) > \frac{d(x, y) - \sqrt{n}}{2}.$$

Since $\left(\frac{2\pi}{\theta_n} + 2\right) > 2\sqrt{n}$ and $\omega > \sqrt{n}$, the last assertion of Lemma 3.15 implies that H misses the J–balls around x and y:

$$d(H, \{x, y\}) \geq \frac{\left(\frac{2\pi}{\theta_n} + 2\right) J + \omega - \sqrt{n}}{2\sqrt{n}} = \frac{\left(\frac{2\pi}{\theta_n} + 2\right)}{2\sqrt{n}} J + \frac{\omega}{2\sqrt{n}} - \frac{1}{2} > J.$$

Let W be the wall corresponding to H, and let $A = \mathfrak{U}(W)$. There are points x_A, y_A in $\overline{A}$ within J of x, y respectively.

Since H misses the J–balls around x and y, it must separate x_A from y_A. Observe that z lies in the thick wall carrier $T = T(W)$.

Claim 1. *Either one of x_A, y_A lies in T, or there is a point $z' \in T \cap ([x_A, z] \cup [z, y_A])$ lying in a W–hyperplane other than H.*
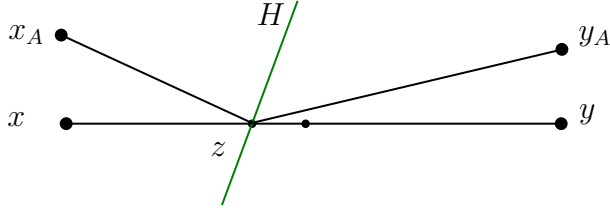
FIGURE 3. The points x_A and y_A are within J of x, y respectively, so they are separated by the hyperplane H. The unlabeled point is the midpoint of $[x, y]$, which is distance at most $\sqrt{n}/2$ from z.

Proof. If neither x_A nor y_A is in T, they both lie in the full sub-complex on A. It follows that W does not separate x_A from y_A, and hence there is a second W–hyperplane H' separating x_A from y_A. The hyperplane H' meets either $[x, x_A]$ or $[y, y_A]$ at a some point z'. □

In case one of x_A, y_A lies in T, we relabel so that y_A lies in T. If not, we similarly relabel so that the point z' found in Claim 1 lies in the segment $[z, y_A]$.

Claim 2. *There is a W–peripheral complex Z intersecting $[z, y_A]$ in a segment I_0 of length at least*

$$\min \left\{ R_\star - (F_{2.32}(Q) + 4Q + 2\eta) , \right.$$
$$\left. \frac{d(x,y) - \sqrt{n}}{2} - \left(\frac{Q}{\sin(\frac{\theta_n}{2})} + 2Q + 2\eta \right) - J \right\},$$

and so that $d(I_0, z) \leq \frac{Q}{\sin(\frac{\theta_n}{2})} + Q + \eta$.

Proof. Note that the angle ψ between $[z, y]$ and $[z, y_A]$ is less than $\frac{\theta_n}{2}$. Indeed, the hypothesis on $d(x, y)$, and the inequalities (3), $\omega > \sqrt{n}$ and $d(y, y_A) \leq J$ together imply (since at any rate $\psi < \frac{\pi}{2}$):
(4)
$$\psi \leq \frac{\pi}{2} \sin(\psi) \leq \frac{\pi}{2} \left(\frac{d(y, y_A)}{\min\{d(z, y), d(z, y_A)\}} \right) < \frac{\pi}{2} \left(\frac{J}{\pi J/\theta_n} \right) = \frac{\theta_n}{2}.$$

(Here we are using the fact that angles in a CAT(0) triangle are dominated by the angles in the comparison triangle.) Since the angle $[z, y]$ makes with H is at least θ_n, the angle $[z, y_A]$ makes with H is at least $\theta_n - \psi > \frac{\theta_n}{2}$. It follows that the subsegment $[z, p]$ of $[z, y_A]$ lying in $N_Q(H)$ has length at most $\frac{Q}{\sin(\frac{\theta_n}{2})}$.

The point p just defined must lie in the Q–neighborhood of some W–peripheral complex Z. This is the peripheral complex in which we will find the segment I_0.

In case all of $[p, y_A]$ lies in $N_Q(Z)$, we use η–super-attractiveness to obtain a segment $I_0 \subseteq [p, y_A] \cap Z$ so that

$$|I_0| \geq d(p, y_A) - (2Q + 2\eta) \geq \frac{d(x, y) - \sqrt{n}}{2} - \left(\frac{Q}{\sin(\frac{\theta_n}{2})} + 2Q + 2\eta \right) - J,$$

as desired.

Next we suppose that not all of $[p, y_A]$ lies in $N_Q(Z)$. It follows that y_A does not lie in Z, since the Q–neighborhood of Z is convex. Claim 1 implies that either y_A or some point $z' \in [p, y_A]$ lies on a W–hyperplane or W–peripheral complex not equal to Z, so either $[z, y_A]$ or $[z, z']$ is contained in $N_Q(T)$ but not entirely contained in $N_Q(Z)$. Let q be the first point on $[p, y_A]$ within Q of some W–hyperplane $H'' \neq H$ or some W–peripheral complex $Z' \neq Z$. Note the point q must also lie in $N_Q(Z)$. In the case q is within Q of a W–peripheral complex $Z' \neq Z$, there exists a hyperplane H'' so that $d(q, H'') \leq F_{2.32}(Q)$. In either case there is a hyperplane $H'' \neq H$ so that $d(q, H'') \leq \max\{Q, F_{2.32}(Q)\}$, and so we have

$$d(p, q) \geq R_\star - (Q + \max\{Q, F_{2.32}(Q)\}) \geq R_\star - (F_{2.32}(Q) + 2Q).$$

The η–super-attractiveness gives us a subsegment I_0 of $[p, q] \cap Z$ of length at least

$$d(p, q) - (2Q + 2\eta) \geq R_\star - (F_{2.32}(Q) + 4Q + 2\eta).$$

In either case $d(I_0, z) \leq d(p, z) + Q + \eta \leq \frac{Q}{\sin(\frac{\theta_n}{2})} + Q + \eta$, as desired. □

We now wish to apply Lemma 3.16 (Pushing across triangles) to the segment I_0 from the last claim, but it may extend past the internal point of the side $[z, y_A]$ of the triangle with corners $\{z, y, y_A\}$. We note however that $(y \mid y_A)_z \geq \frac{d(x,y) - \sqrt{n}}{2} - J$ and $d(z, I_0) \leq \frac{Q}{\sin(\frac{\theta_n}{2})} + Q + \eta$ by Claim 2, so I_0 contains a subsegment I_1 as in the hypothesis of that lemma with

$$|I_1| \geq \min\left\{ |I_0|, \frac{d(x, y) - \sqrt{n}}{2} - \left(\frac{Q}{\sin\left(\frac{\theta_n}{2}\right)} + Q + \eta \right) - J \right\}.$$

This is a better lower bound than that already given for I_0 in the statement of Claim 2, so we may assume that I_0 already satisfies the hypotheses of Lemma 3.16. Pushing across the triangle we obtain a subsegment I in $[z, y] \subseteq [x, y]$ which is contained in Z and has length

at least $|I_0| - (2\delta + 2\eta + f(\delta))$. Moreover the distance from I to z is no more than $d(I_0, z) + \eta + \delta$.

Adding up the constants we obtain the inequalities asserted in the lemma. $\square$

Lemma 3.18. *Let $J \geq 0$, and $x, y \in N_J(\mathfrak{U})$. Suppose that Z is a peripheral complex so that $Z \cap [x, y]$ contains a segment σ so that $\text{length}(\sigma) > F_{2.36}(0) + 4(\eta + \delta) + 2f(\delta)$, and $d(\sigma, \{x, y\}) > J + \delta + \eta$. Then $Z \subseteq N_0(\mathfrak{U})$.*

Proof. Let $B \in \mathfrak{U}$. There are points x_B, y_B of $\overline{B}$ within J of x, y respectively. We claim that there is a subsegment σ' of $[x_B, y_B] \cap Z$ of length at least $F_{2.36}(0)$. Lemma 3.9 then implies that $Z \subseteq \overline{B}$. Since $B \in \mathfrak{U}$ was arbitrary, we obtain $Z \subseteq \bigcap_{A \in \mathfrak{U}} \overline{A} = N_0(\mathfrak{U})$.

Finding the subsegment σ' is a matter of applying Lemma 3.16 (Pushing across triangles) twice; first the Lemma is applied to a triangle whose corners are x, y, y_B, and then to a triangle whose corners are x, x_B, y_B. The lower bound on $d(\sigma, \{x, y\})$ implies the hypothesis about Gromov products in Lemma 3.16. Each time we push across a triangle, we can lose only up to $2(\eta + \delta) + f(\delta)$ in length, so we are left with at least $F_{2.36}(0)$ in the end. $\square$

Proposition 3.19. *If $N_K(\mathfrak{U})$ is unbounded then there is a peripheral complex contained in*

$$N_0(\mathfrak{U}) := \bigcap_{A \in \mathfrak{U}} \overline{A}.$$

Proof. Assuming $N_K(\mathfrak{U})$ is unbounded, we may choose two vertices $x, y \in N_K(\mathfrak{U})$ so $d(x, y)$ is as large as we like. In particular we make the following assumption:

$$(5) \quad d(x, y) > \max \left\{ \left(\frac{2\pi}{\theta_n} + 2 \right) K + \omega, 2R_\star + 2K + 2\delta + 2\eta \right\}.$$

In particular, we have $\frac{1}{2} d(x, y) > R_\star + K$, so Lemma 3.17 with $J = K$ gives us a peripheral complex Z and a segment $I \subseteq [x, y]$ so that

(1) the length of I is at least $R_\star - \tau$, and
(2) the distance from I to the midpoint of $[x, y]$ is at most τ.

Note also that we have the following inequalities. (The first line follows from Assumption 2.40.(2); the second from (5).)

$$|I| \geq R_\star - \tau > F_{2.36}(0) + 4(\eta + \delta) + 2f(\delta)$$
$$\frac{1}{2} d(x, y) > R_\star + (K + \delta + \eta).$$

Since $d(x, y) > 2(R_\star + K + \delta + \eta)$ we can choose such an I to satisfy $d(I, \{x, y\}) > K + \delta + \eta$. Applying Lemma 3.18, we see $Z \subseteq N_0(\mathfrak{U})$. $\square$

Proposition 3.20. *Let Z be a peripheral complex. The following are equivalent:*

(1) $Z \subseteq N_0(\mathfrak{U})$.
(2) $\mathrm{Stab}(\mathfrak{U})$ contains a finite index subgroup of $\mathrm{Stab}(Z)$.
(3) $\mathrm{Stab}(\mathfrak{U})$ contains an infinite subgroup of $\mathrm{Stab}(Z)$.

Proof. We first prove (1) $\Longrightarrow$ (2). The hypothesis that $Z \subseteq N_0(\mathfrak{U})$ implies that for every wall W, either $Z^{(0)} \subseteq \mathfrak{U}(W)$ or Z is a W–peripheral complex. Let $\mathfrak{U}' \subseteq \mathfrak{U}$ consist of those halfspaces $A \in \mathfrak{U}$ so that $Z^{(0)} \subseteq A$. Note that every element of $\mathrm{Stab}(Z)$ preserves $\mathfrak{U}'$. If $\mathfrak{U}(W) \notin \mathfrak{U}'$, then Z is a W–peripheral complex. There are only finitely many such W, so $\mathfrak{U} \setminus \mathfrak{U}'$ is finite. Let $S = (\mathfrak{U} \setminus \mathfrak{U}') \cup \{A^c \mid A \in \mathfrak{U} \setminus \mathfrak{U}'\}$. The finite set S is preserved by $\mathrm{Stab}(Z)$ and the kernel of $\mathrm{Stab}(Z) \to \mathrm{Sym}(S)$ lies in $\mathrm{Stab}(\mathfrak{U})$.

The implication (2) $\Longrightarrow$ (3) is obvious, since the peripheral subgroups of $(G, \mathcal{P})$ are assumed to be infinite (recall Convention 1.10).

Finally we show (3) $\Longrightarrow$ (1). Let Z be a peripheral complex so that $\mathrm{Stab}(Z) \cap \mathrm{Stab}(\mathfrak{U})$ is infinite. Let x be any point of $N_0(\mathfrak{U})$. Choose $g \in \mathrm{Stab}(Z) \cap \mathrm{Stab}(\mathfrak{U})$ so that $d(x, gx) = E \geq F_{2.36}(Q) + 2(d(x, Z) + \eta)$.

Let $A = \mathfrak{U}(W)$ where W is a wall. Both x and gx lie in $\overline{A}$, which is Q–quasi-convex, so $[x, gx]$ lies in $N_Q(\overline{A})$. The super-attractiveness of Z ensures that a subsegment of $[x, gx]$ of length at least $E - 2(d(x, Z) + \eta) \geq F_{2.36}(Q)$ lies in Z. The endpoints are distance at most Q from $\overline{A}$, so Lemma 3.9 implies that $Z \subseteq \overline{A}$. Since $A \in \mathfrak{U}$ was arbitrary, $Z \subseteq N_0(\mathfrak{U})$. $\square$

3.4. **A $\mathrm{Stab}(\mathfrak{U})$–tree.** For the rest of this section we focus on the case that $\mathrm{Stab}(\mathfrak{U})$ is infinite and not parabolic. By Corollary 3.14 and Proposition 3.19, there must be at least one peripheral complex contained in $N_0(\mathfrak{U})$. If there is only one, then its stabilizer obviously contains $\mathrm{Stab}(\mathfrak{U})$, so we can assume there is more than one peripheral complex in $N_0(\mathfrak{U})$. We consider projections of these peripheral complexes to each other. These have diameter bounded by C (see Notation 2.38 and Corollary 2.18). For any pair Z, Z' of peripheral complexes in $N_0(\mathfrak{U})$, the next lemma shows that the ultrafilter $\mathfrak{U}$ is "weakly principal" for any point in $\pi_Z(Z')$.

Lemma 3.21. *For κ as in Notation 2.39, the following holds: If Z, Z' are peripheral complexes contained in $N_0(\mathfrak{U})$, then*

$$\pi_Z(Z') \subseteq \bigcap_{A \in \mathfrak{U}} N_\kappa(A).$$

Proof. Recall $\kappa = F_{2.32}(Q+1) + 2Q + C + \frac{\sqrt{n}}{2} + 2$, where $F_{2.32}$ is the function from Lemma 2.32, and C is the constant from Corollary 2.18. Fix $A \in \mathfrak{U}$ and suppose that $A = \mathfrak{U}(W)$. Or goal is to show that $\pi_Z(Z') \subseteq N_\kappa(A)$.

First suppose that Z is not a W–peripheral complex. In this case, since $Z \subseteq N_0(\mathfrak{U}) \subseteq N_0(\overline{A})$ we see that $Z^{(0)} \subseteq A$, so $Z \subseteq N_\kappa(A)$. Since $\pi_Z(Z') \subseteq Z$ we are done in this case.

Therefore, we suppose henceforth that Z is a W–peripheral complex, so in particular $Z \subseteq T(W)$. Let $b \in Z'$ be arbitrary, and consider the geodesic $[b, \pi_Z(b)]$.

We remark that peripheral complexes intersect, so it is possible that $b = \pi_Z(b)$.

Case 1. $b = \pi_Z(b)$.

If Z' is also a W–peripheral complex, Lemma 2.32 implies that $\pi_Z(b)$ is within $F_{2.32}(0) \leq F_{2.32}(Q+1) < \kappa$ of some $T(W)$–hyperplane. It follows that in this case $\pi_Z(Z') \subseteq N_\kappa(A)$, as required.

If Z' is not a W–peripheral complex, then we have $(Z')^{(0)} \subseteq A$, and hence $b \in N_1(A)$.

We suppose for the remainder of the proof that $b \neq \pi_Z(b)$, and so $[b, \pi_Z(b)]$ is a non-degenerate geodesic which only intersects Z at $\pi_Z(b)$.

Case 2. $b \neq \pi_Z(b)$ *and* $[b, \pi_Z(b)] \cap T(W) \neq \{\pi_Z(b)\}$.

In this case, let $x \in [b, \pi_Z(b)] \cap (T(W) \smallsetminus Z)$. Since $Z \subseteq T(W)$ and $T(W)$ is Q–quasi-convex (Notation 2.38), the geodesic $[x, \pi_Z(b)]$ lies in the Q–neighborhood of $T(W)$. There are two subcases:

Subcase 2.1. $d(x, \pi_Z(b)) \geq Q + 1$.

In this subcase let y be the point on $[x, \pi_Z(b)]$ at distance $Q+1$ from $\pi_Z(b)$. Since $\pi_Z(b)$ is the closest point on Z to b, the point y is not within Q of Z, so it is within Q of some W–hyperplane or some other W–peripheral complex Z_1. If it is within Q of a W–hyperplane, we are done, since $Q < \kappa$. Otherwise it is within distance $Q+1$ of both Z and Z_1, and so it is distance at most $F_{2.32}(Q+1)$ from some W–hyperplane (Lemma 2.32). Since $F_{2.32}(Q+1) < \kappa$ we are finished in this case as well.

Subcase 2.2. $d(x, \pi_Z(b)) < Q + 1$

In this case the point x itself is either on a hyperplane or on a $W-$peripheral complex $Z_1 \neq Z$, and can argue as in the previous subcase, substituting x for y.

Case 3. $b \neq \pi_Z(b)$ *and* $[b, \pi_Z(b)] \cap T(W) = \pi_Z(b)$.

In this case, since $(Z')^{(0)} \subseteq A$, it must be that the geodesic $[b, \pi_Z(b)]$ lies entirely in the full sub-complex on A, meaning that $\pi_Z(Z')$ lies in $N_\kappa(A)$, as required. $\qquad\square$

We want to build a bipartite $\mathrm{Stab}(\mathfrak{U})$–tree in order to analyze the structure of $\mathrm{Stab}(\mathfrak{U})$ and prove Property (3b) of Definition 1.9. The equivalence classes under the relation defined in Definition 3.22 will form one color of vertex of this tree. The other color will be the set of peripheral complexes in $N_0(\mathfrak{U})$.

Recall from Notation 2.39 that

$$D = \max\left\{2\sqrt{n}\kappa + \sqrt{n},\ F_{2.36}(0) + 6\eta + 2f(\delta) + 6\delta,\ 2C + 1\right\} + 1.$$

Definition 3.22. Define a relation on pairs (Z, Z') where $Z \neq Z'$ are contained in $N_0(\mathfrak{U})$ by saying $(Z_1, Z_1') \sim (Z_2, Z_2')$ if for every geodesic γ joining $\pi_{Z_1}(Z_1')$ to $\pi_{Z_2}(Z_2')$, and every peripheral complex Z, we have $\mathrm{diam}(Z \cap \gamma) < D$.

Proposition 3.23. *The relation defined in Definition 3.22 is an equivalence relation.*

Proof. Symmetry is obvious, and reflexivity follows from Corollary 2.18 because $D > C$ (the upper bound on the diameter of $\pi_Z(Z')$).

To show transitivity, we argue by contradiction. Suppose $(Z_1, Z_1') \sim (Z_2, Z_2') \sim (Z_3, Z_3')$, but $(Z_1, Z_1') \not\sim (Z_3, Z_3')$. For each i, let $S_i = \pi_{Z_i}(Z_i')$. Since $(Z_1, Z_1') \not\sim (Z_3, Z_3')$, there is a geodesic γ joining S_1 to S_3 and a peripheral complex Z_0 so that $\mathrm{diam}(\gamma \cap Z_0) \geq D$. Denote the endpoints of γ by x_1, x_3, so $x_i \in S_i$. We first show that for either this or some other peripheral complex, the diameter must be much larger.

Claim. *There exists a peripheral complex Z so that* $\mathrm{diam}(\gamma \cap Z) > \frac{3}{4} R_\star$.

Proof of Claim. Let m be the midpoint of $\gamma \cap Z_0$, and let x_1', x_3' be the endpoints of $\gamma \cap Z_0$. By Lemma 3.15 there exists a hyperplane H cutting γ at a point m_0 within $\sqrt{n}$ of m so that

$$d(H, \{x_1, x_3\}) > d(H, \{x_1', x_3'\}) > \frac{d(x_1', x_3') - \sqrt{n}}{2\sqrt{n}} > \kappa.$$

(The last inequality holds because $d(x_1', x_3') \geq D > 2\sqrt{n}\kappa + \sqrt{n}$.) Let W be the wall determined by H. Since $m_0 \in \gamma \cap Z_0$ it is clear that Z_0 is a W–peripheral complex.

We claim some W–hyperplane $H' \neq H$ comes within κ of γ. Indeed, if no such hyperplane crosses γ, then one endpoint of γ is not in the full subcomplex on $\mathfrak{U}(W)$. From Lemma 3.21 we see that the endpoint must nonetheless lie in $N_\kappa(\mathfrak{U}(W))$, so it must lie within κ of some W–hyperplane H'.

Let $y \in H'$ and $y_0 \in \gamma$ satisfy $d(y, y_0) \leq \kappa$. Consider the geodesic $\gamma' = [y, m_0]$. Since y and m_0 lie in distinct W–hyperplanes and $T(W)$ is Q–quasi-convex, $[y, m_0] \subseteq N_Q(T(W))$. Moreover, distinct hyperplanes are distance at least $R_\star$ apart, so there must be a segment of $[a, b]$ of length at least $R_\star - 2F_{2.32}(Q)$ which lies outside the $F_{2.32}(Q)$–neighborhood of all the W–hyperplanes. By Lemma 2.32, this subsegment must lie in the Q–neighborhood of a single W–peripheral complex Z. By η–super-attractiveness of peripheral complexes, there is a subsegment I of $[y, m_0]$ of length at least $R_\star - 2F_{2.32}(Q) - 2(Q+\eta)$ contained in Z. Now consider the geodesic triangle with vertices y, y_0, m_0. Since $d(y, y_0) \leq \kappa$ we have $(y, y_0)_{m_0} \geq |\gamma| - \kappa$. By adjusting an endpoint of I by at most κ and labeling the endpoints of I appropriately by u, v, we can ensure the inequalities $d(m_0, u) < d(m_0, v) \leq (y, y_0)_{m_0}$. We still have a lower bound on the length $|I| \geq R_\star - 2F_{2.32}(Q) - 2(Q+\eta) - \kappa$. Applying Lemma 3.16 (Pushing across triangles) to the adjusted I, there is a subsegment J of $[y_0, m_0]$ contained in Z of length at least $|I| - (2\delta + 2\eta + f(\delta)) \geq R_\star - 2F_{2.32}(Q) - 2Q - 4\eta - 2\delta - f(\delta)$. Because of Assumption 2.40.(3), this implies $|J| > \frac{3}{4}R_\star$, as required. □

Now consider a point $x_2 \in S_2$ and consider the geodesic triangle with vertices $[x_1, x_2, x_3]$. Since the side $[x_1, x_3]$ has a segment contained in Z of length at least $\frac{3}{4}R_\star$ there is a subsegment of length at least $\frac{3}{8}R_\star$ not crossing the internal point. Lemma 3.16 can be applied to this segment to obtain a subsegment of either $[x_1, x_2]$ or $[x_2, x_3]$ which lies in Z and has length at least $\frac{3}{8}R_\star - (2\eta + 2\delta + f(\delta))$. By Assumption 2.40.(4) the segment has length greater than D. This contradicts $(Z_1, Z_1') \sim (Z_2, Z_2') \sim (Z_3, Z_3')$, completing the proof of Proposition 3.23. □

Lemma 3.24. *If $Z, Z' \subseteq N_0(\mathfrak{U})$, then*

$$\mathrm{diam}\left(\bigcup \{\pi_{Z_1}(Z_1') \mid (Z_1, Z_1') \sim (Z, Z')\}\right) < \max\{\omega, 2(D+\tau)\}.$$

Proof. Recall ω and τ are the constants defined in Notation 2.39 and used in Lemma 3.17.

Suppose that Z, Z', Z_1 and Z_1' are peripheral complexes in $N_0(\mathfrak{U})$, and that $x \in \pi_Z(Z')$ and $y \in \pi_{Z_1}(Z_1')$ satisfy $d(x, y) \geq \max\{\omega, 2(D + \tau)\}$. Our goal is to show $(Z, Z') \not\sim (Z_1, Z_1')$.

By Lemma 3.17 (with $J = 0$), since $d(x, y) \geq \omega$ and $x, y \in N_0(\mathfrak{U})$, there is a peripheral complex Z_0 which intersects $[x, y]$ in a segment I of length at least $\min\{R_\star - \tau, \frac{1}{2}d(x, y) - \tau\}$. Since $R_\star > D + \tau$ because of Assumption 2.40.(5), we see that $|I| \geq D$. It follows from the definition of the relation that $(Z, Z') \not\sim (Z_1, Z_1')$, as required. $\qquad\square$

Definition 3.25 (The graph Λ). Let V_0 be the set of peripheral complexes contained in $N_0(\mathfrak{U})$, and let V_1 be the set of equivalence classes $[Z, Z']$ where both Z, Z' are contained in $N_0(\mathfrak{U})$. To form the graph Λ, connect a vertex Z of V_0 to every vertex of the form $[Z, Z']$ by an edge.

Lemma 3.26. *The graph Λ is connected.*

Proof. We argue by contradiction. If Λ is disconnected, then there are vertices corresponding to peripheral complexes Z_1, Z_2 which are in separate components. Choose such a pair so that $d(Z_1, Z_2)$ is minimal among such pairs.

Since Z_1 and Z_2 are in different components we must have $(Z_1, Z_2) \not\sim (Z_2, Z_1)$. Let γ be a geodesic joining $\pi_{Z_1}(Z_2)$ to $\pi_{Z_2}(Z_1)$ and containing a subsegment σ_0 of length at least D in some peripheral complex Z. We claim that Z cannot be equal to either Z_1 or Z_2. Indeed, let ρ be a shortest geodesic from Z_1 to Z_2, so the endpoints of ρ lie in $\pi_{Z_1}(Z_2)$ and $\pi_{Z_2}(Z_1)$, respectively, and note that ρ intersects Z_1 only at its initial point, and Z_2 only at its terminal point. Since $\mathrm{diam}\left(\pi_{Z_1}(Z_2)\right), \mathrm{diam}\left(\pi_{Z_2}(Z_1)\right) \leq C$ (see Notation 2.38), it follows that

$$|\rho| \leq |\gamma| \leq |\rho| + 2C,$$

and that γ spends no more than C in either Z_1 or Z_2. Since $D > C$ (see Notation 2.38), Z cannot be equal to either Z_1 or Z_2. Since $D > F_{2.36}(0) + 4(\eta + \delta) + 2f(\delta) + 2(\eta + \delta)$, there is a subsegment σ of σ_0 of length at least $F_{2.36}(0) + 4(\eta + \delta) + 2f(\delta)$ at distance at least $\eta + \delta$ from $\{x, y\}$. We can therefore apply Lemma 3.18 with $K = 0$ to conclude that $Z \subseteq N_0(\mathfrak{U})$.

We claim that $d(Z, Z_1)$ is smaller than $d(Z_1, Z_2)$. Indeed, if ξ is a geodesic between Z_1 and Z_2 realizing $d(Z_1, Z_2)$ then ξ starts in $\pi_{Z_1}(Z_2)$ and ends in $\pi_{Z_2}(Z_1)$. It follows from Corollary 2.18 that $|\gamma| \leq |\xi| + 2C$. On the other hand, the distance from Z_1 to Z is at most $|\gamma| - D \leq |\xi| + 2C - D < |\xi| = d(Z, Z_1)$ (recall from Notation 2.39 that $D \leq 2C + 1$). Therefore, by the minimality of $d(Z_1, Z_2)$, Z and Z_1 lie in the same component of Λ. Similarly, $d(Z, Z_2) < d(Z_1, Z_2)$, and so Z and Z_2 lie in the same component of Λ, a contradiction. $\qquad\square$

Lemma 3.27. *The graph Λ is a bipartite tree.*

Proof. That Λ is bipartite follows immediately from the definition. We now prove that Λ is a tree.

In order to obtain a contradiction, suppose that σ is an oriented cycle of length $2n$ in Λ. The vertices of σ are labeled (with subscripts to be understood modulo n:

$$Z_0, \ [Z_0, Z_0''] = [Z_1, Z_1'], \ Z_1, \ [Z_1, Z_1''] = [Z_2, Z_2'], \ldots, [Z_n, Z_n''] = [Z_0, Z_0'].$$

For each i let b_i be a geodesic segment in Z_i from $p_i \in \pi_{Z_i}(Z_i')$ to $q_i \in \pi_{Z_i}(Z_i'')$, and let a_i be the geodesic from q_i to p_{i+1}. Let γ be the broken geodesic loop $b_0 a_0 \cdots a_{n-1}$. By Lemma 3.24 we have $|a_i| < \max\{\omega, 2(D+\tau)\}$.

We claim that the path γ satisfies the hypothesis of [15, Theorem 5.6], and is therefore a good quality quasi-geodesic (and hence not a loop). In order to make our situation line up with the constants in [15], we apply a similar trick as in the proof of Proposition 2.31. Namely we temporarily modify the function f. To that end, define the function $f'(m) = \max\{f(m), \eta, \frac{1}{3}\max\{\omega, 2(D+\tau)\}\}$, and note that $(X, \mathcal{B})$ is (δ, f')–relatively hyperbolic. Let $M = f'(5\delta)$ as in [15]. Also note that since the peripheral complexes are η–super-attractive, they are $2(\eta + m)$–attractive in the sense of Einstein (see Remark 2.15), and thus satisfy the attractiveness hypothesis of [15, Hypotheses 5.5]. We now check that the six conditions from [15, Theorem 5.6] hold.

Certainly the first is satisfied, and the second is satisfied because σ is embedded. The third is satisfied because $(X, \mathcal{B})$ is (δ, f')–relatively hyperbolic and $M = f'(5\delta)$. The fourth is satisfied because by the proof of Proposition 3.23 between inequivalent projections there is a peripheral path of length at least $\frac{3}{4}R_\star$, and Assumption 2.40.(6) forces $\frac{3}{4}R_\star \geq 26M + 250\delta$. Since $|a_i| < \max\{\omega, 2(D+\tau)\}$, and by the choice of f', we have $|a_i| \leq 3M + 63\delta$, which trivially imply that the fifth and sixth conditions from [15, Theorem 5.6] hold.

It follows from the conclusion of [15, Theorem 5.6] that a geodesic joining the endpoints of γ must be long, and in particular γ is not a loop, contrary to hypothesis. It follows that Λ is a tree.   □

3.5. **Infinite non-parabolic cell stabilizers.** The goal of this subsection is the following:

Theorem 3.28. *Suppose that* $\mathrm{Stab}(\mathfrak{U})$ *is infinite and non-parabolic. Then* $\mathrm{Stab}(\mathfrak{U})$ *is a finite graph of groups where the vertex groups are either full parabolic or finite, and the edge groups are finite.*

For the proofs of Theorems 3.28 and C we need some facts about various kinds of quasi-convexity in relatively hyperbolic groups.

Definition 3.29. [40] Let G be finitely generated, and let Γ be a Cayley graph for G. The subgroup G_0 is *strongly quasi-convex* if for every $\lambda \geq 1$, $\epsilon \geq 0$ there is an r so that any (λ, ϵ)–quasi-geodesic in Γ with endpoints in G_0 lies in an r–neighborhood of G_0.

Notice that strongly quasi-convex subgroups are always finitely generated and undistorted (see for example [6, III.Γ.3.5]).

We deduce the next lemma from theorems of Tran and Hruska.

Lemma 3.30. *Let $(G, \mathcal{P})$ be relatively hyperbolic, and let $G_0 < G$ be full. The following are equivalent:*

  (1) G_0 is finitely generated and undistorted in G.
  (2) G_0 is relatively quasi-convex in $(G, \mathcal{P})$.
  (3) G_0 is strongly quasi-convex in G.

Proof. Theorem 1.5 of [27] gives (1) $\implies$ (2) (even without the assumption that G_0 is full). Theorem 1.4 of [27] gives (2) $\implies$ (1) when G_0 is full.

Theorem 1.9 of [40] gives (1) $\implies$ (3) when G_0 is full, since finite index and finite subgroups are strongly quasi-convex. We have already noted that strongly quasi-convex subgroups are finitely generated and undistorted, so (3) $\implies$ (1). $\square$

Corollary 3.31. *The subgroup $\mathrm{Stab}(\mathfrak{U})$ is full relatively quasi-convex in $(G, \mathcal{P})$. In particular it is finitely generated.*

Proof. The hyperplane stabilizers for $G \curvearrowright \widehat{X}$ are full relatively quasi-convex (Lemma 2.27) so by Lemma 3.30, they are strongly quasi-convex. By [18, Theorem 3.26] the cube stabilizers of $G \curvearrowright \widehat{X}$ are also strongly quasi-convex. In particular $\mathrm{Stab}(\mathfrak{U})$ is strongly quasi-convex in G. It is full by Proposition 3.20. Now apply Lemma 3.30 to deduce that $\mathrm{Stab}(\mathfrak{U})$ is relatively quasi-convex. $\square$

Proof of Theorem 3.28. The subgroup $\mathrm{Stab}(\mathfrak{U})$ acts on the tree Λ described in the last subsection. A vertex corresponding to a peripheral complex in $N_0(\mathfrak{U})$ has full parabolic stabilizer by Proposition 3.20. The stabilizer of a vertex corresponding to an equivalence class $[(Z, Z')]$ must also stabilize the bounded set from Lemma 3.24, so it must be finite. Since every edge is connected to some vertex of this type, edge stabilizers are also finite.

Since $\mathrm{Stab}(\mathfrak{U})$ is finitely generated there exists a $\mathrm{Stab}(\mathfrak{U})$–invariant sub-tree Λ_0 of Λ so that $\mathrm{Stab}(\mathfrak{U}) \backslash \Lambda_0$ is finite. $\square$

3.6. **Proof of Theorem C.** See Definition 1.9 for the definition of a *weakly relatively geometric* action.

Theorem C. *Suppose $(G, \mathcal{P})$ is relatively hyperbolic, and that G acts properly cocompactly on a $\mathrm{CAT}(0)$ cube complex X, and that this action satisfies Assumption 1.1.*

There exists a weakly relatively geometric action of G on a $CAT(0)$ cube complex $\widehat{X}$.

Proof. We take the cube complex $\widehat{X}$ to be the one dual to the wallspace fixed in Definition 2.41.

The cocompactness of $G \curvearrowright \widehat{X}$ and ellipticity of peripheral subgroups is Corollary 3.6.

It suffices to prove the statement about cube stabilizers for vertex stabilizers, since each cube stabilizer is an intersection of vertex stabilizers, and the description passes to intersections.

So, let $\mathfrak{U}$ be an ultrafilter so that $\mathrm{Stab}(\mathfrak{U})$ is infinite. Corollary 3.31 implies that $\mathrm{Stab}(\mathfrak{U})$ is full relatively quasi-convex.

Theorem 3.28 implies that $\mathrm{Stab}(\mathfrak{U})$ is a graph of finite and full parabolic subgroups as in the conclusion. $\square$

4. Proof of Theorem A

In this section we prove Theorem A. The strategy is to use the re-cubulation given by Theorem C and relatively hyperbolic Dehn filling results. See [34, 17, 2, 1, 19, 18] for more information on relatively hyperbolic Dehn filling. We first recall the definition.

Definition 4.1 (Dehn filling). Suppose that $(G, \mathcal{P})$ is a group pair, and that $\mathcal{N} = \{N_P \trianglelefteq P \mid P \in \mathcal{P}\}$ is a collection of normal subgroups of the elements of P. The *Dehn filling* induced by $\mathcal{N}$ is

$$G(\mathcal{N}) := G \Big/ \langle\!\langle \bigcup N_P \rangle\!\rangle_G \,.$$

Definition 4.2 (Wide subgroups and fillings). If P is a group, $B < P$, and $F \subseteq P$ a finite set, then $N \trianglelefteq P$ is (B, F)–*wide* if, for all $b \in B$ and $f \in F \setminus B$, the product bf does not lie in N.

Let H be a relatively quasi-convex subgroup of $(G, \mathcal{P})$, so there is a collection of infinite maximal parabolic subgroups $\mathcal{D}$ of H so that $(H, \mathcal{D})$ is relatively hyperbolic. For each $D \in \mathcal{D}$ there is some $c_D \in G$ and some $P_D \in \mathcal{P}$ so that $D^{c_D^{-1}} \leq P_D$.

Let $F \subseteq G \setminus \{1\}$ be finite. Let $G(\mathcal{N})$ be a Dehn filling, with $K = \langle\!\langle \bigcup \mathcal{N} \rangle\!\rangle_G$. We say the filling $G(\mathcal{N})$ is (H, F)–*wide* if for every $D \in \mathcal{D}$, the intersection $K \cap P_D$ is $(D^{c_D^{-1}}, F \cap P_D)$–wide.

Definition 4.3 (Sufficiently long and wide Dehn fillings)**.** We say that a statement S holds *for all sufficiently long Dehn fillings* if there is a finite set $F \subseteq G \setminus \{1\}$ so that S holds for all $G(\mathcal{N})$ so that $\bigcup \mathcal{N}$ contains no element of F.

Let $H < G$ be a quasi-convex subgroup. The statement S holds *for all sufficiently H–wide Dehn fillings* if there is a finite set $F \subseteq G \setminus \{1\}$ so that S holds for all $G(\mathcal{N})$ which are (H, F)–wide.

For the Dehn filling results, we make the following assumption (*weakly relatively geometric* was defined in Definition 1.9).

Assumption 4.4. *The pair $(G, \mathcal{P})$ is relatively hyperbolic, and admits a weakly relatively geometric action on a* $\mathrm{CAT}(0)$ *cube complex* $\widehat{X}$*. Further, each element of $\mathcal{P}$ is residually finite.*

A key reason for our interest in weakly relatively geometric actions is the following result.

Theorem 4.5. *Under Assumption 4.4, there exist finite-index subgroups $\{L_P \trianglelefteq P \mid P \in \mathcal{P}\}$ so that the following holds:*
Let $\mathcal{N} = \{N_P \trianglelefteq P \mid P \in \mathcal{P}\}$ be chosen so that for each $P \in \mathcal{P}$,
  (1) $N_P \leq L_P$, and
  (2) P/N_P is hyperbolic and virtually special.
Then the Dehn filling $G(\mathcal{N})$ is hyperbolic and virtually special.

Proof. Since the G–action on $\widehat{X}$ is cocompact, there are cells $\sigma_1, \ldots, \sigma_k$ in $\widehat{X}$ forming a collection of representatives of the G–orbits of cells. For $1 \leq i \leq k$ let Q_i be the finite-index subgroup of $\mathrm{Stab}(\sigma_i)$ consisting of elements which fix σ_i pointwise, and let $\mathcal{Q} = \{Q_1, \ldots, Q_k\}$. Note that each infinite Q_i is a full relatively quasi-convex subgroup which admits a graph of groups decomposition with finite edge groups and finite or full parabolic vertex groups. By combining [34, Theorem 1.1], [2, Propositions 4.3, 4.4] and [18, Corollary 6.5], and the assumption that elements of $\mathcal{P}$ are residually finite, we see that there are finite-index subgroups $\{L_P \trianglelefteq P \mid P \in \mathcal{P}\}$ so that for any $N_P \leq L_P$ so P/N_P is hyperbolic and virtually special in P, the Dehn filling

$$\overline{G} = G/K := G\left(\{N_P \mid P \in \mathcal{P}\}\right)$$

satisfies
  (1) $\overline{G}$ is hyperbolic;
  (2) The image of each Q_i is quasi-convex in $\overline{G}$, and splits as a graph of virtually special hyperbolic groups with finite edge groups (and in particular the image of each Q_i is hyperbolic and virtually special); and

(3) The space $\overline{X} := {}_K\backslash\widehat{X}$ is a CAT(0) cube complex.

Let $\overline{G}$ be any such Dehn filling. Then $\overline{G}$ acts cocompactly on the CAT(0) cube complex $\overline{X}$. By (1) $\overline{G}$ is hyperbolic. By (2), the cell stabilizers for the $\overline{G}$–action on $\overline{X}$ are quasi-convex and virtually special. It now follows from [18, Theorem D] that $\overline{G}$ is virtually special, as required. $\square$

The following is an immediate consequence of results of Haglund–Wise [22, Corollary 7.4] and Minasyan [31, Theorem 1.1].

Theorem 4.6. *Suppose that Γ is a hyperbolic virtually special group. Then every quasi-convex subgroup of Γ is separable, and every finite product of quasi-convex subgroups of Γ is separable.*

Given Theorem C, the next two results are the technical core of the proof of Theorem A.

Theorem 4.7. *Under Assumption 4.4, suppose further that S is a relatively quasi-convex subgroup of $(G, \mathcal{P})$ so that for all $P \in \mathcal{P}$ and $g \in G$ the subgroup $P \cap S^g$ is separable in P.*
    Then S is separable in G.

Proof. Let $g_0 \in G \smallsetminus S$, and let $\{L_P \mid P \in \mathcal{P}\}$ be as in Theorem 4.5. By [19, Proposition 4.5, 4.7], for sufficiently long and S–wide fillings of $(G, \mathcal{P})$, the image of S is quasi-convex and does not contain g_0. However, by [19, Lemma 5.2], and the assumption on separability of the subgroups $S^g \cap P$ in P, there are such long and S–wide fillings.

Taking these fillings to also have filling kernels contained in the L_P as above, and we obtain a virtually special hyperbolic quotient $\pi\colon G \to \overline{G}$ so that the image $\overline{S}$ of S is quasi-convex and $\pi(g_0) \notin \overline{S}$. By applying Theorem 4.6, there is a finite quotient $\lambda\colon \overline{G} \to Q$ so that $\lambda(\pi(g_0)) \notin \lambda(\pi(S))$. Since $g_0 \in G \smallsetminus S$ was arbitrary, this shows that S is separable in G, as required. $\square$

The following result relies on Proposition A.4 which is proved in Appendix A, using techniques from [19].

Theorem 4.8. *Under Assumption 4.4, suppose further that S_1, S_2 are relatively quasi-convex subgroups of $(G, \mathcal{P})$ so that for all $P \in \mathcal{P}$ and $g_1, g_2 \in G$ the double coset $(P \cap S_1^{g_1})(P \cap S_2^{g_2})$ is separable in P.*
    Then the product $S_1 S_2$ is separable in G.

Proof. Let $g \in G \smallsetminus S_1 S_2$. Applying Proposition A.4 and proceeding similarly to the proof of Theorem 4.7, there exists a Dehn filing $\pi\colon G \to \overline{G}$ so that

(1) $\overline{G}$ is a virtually special hyperbolic group;
(2) $\pi(S_1)$ and $\pi(S_2)$ are quasi-convex in $\overline{G}$; and
(3) $\pi(g) \notin \pi(S_1)\pi(S_2)$.

Since double cosets of quasi-convex subgroups are separable in virtually special hyperbolic groups, as noted in Theorem 4.6, there is a further finite quotient of $\overline{G}$ which can be used to separate g from S_1S_2 in G. □

Finally, we restate and prove Theorem A.

Theorem A. [33, Theorem 1.2] *Suppose that $(G, \mathcal{P})$ is relatively hyperbolic and that G acts properly and cocompactly on a $\mathrm{CAT}(0)$ cube complex X so Assumptions 1.1 and 1.2 are satisfied. Then G acts virtually co-specially on X.*

Proof of Theorem A. That each element of $\mathcal{P}$ is residually finite is part of the hypothesis of Theorem A, and the rest of Assumption 4.4 follows from Theorem C.

Let S_1, S_2 be hyperplane stabilizers for the G–action on X. By Lemma 2.24 these are relatively quasi-convex. The separability and double coset separability assumptions in Theorems 4.7 and 4.8 are part of the hypotheses of Theorem A. Therefore, it follows from Theorem 4.7 that S_1 is separable in G, and from Theorem 4.8 that S_1S_2 is separable in G. It now follows from [23, Corollary 4.3] that the G–action on X is virtually special, as required. □

5. An example

In this section we give an example of a group to which Theorem A applies, and for which it is at least not obvious how to apply previous results to deduce virtual specialness. Note that this example is merely indicative of many examples that could be built using this technique, or others. That the example is virtually special follows from the following application of our main result. (By a *standard cubical torus* we mean a unit cube of some dimension with opposite faces identified via translation.)

Proposition 5.1. *Let Y be a 1–vertex non-positively curved cell complex built from a finite wedge of standard cubical tori by attaching finitely many regular right-angled hyperbolic polygons rescaled to have side-length 1. Then Y is homeomorphic to a cube complex C, and this cube complex is virtually special.*

Proof. We first note that the complex Y is negatively curved away from the tori, any two of which meet only in a point. It follows that the universal cover of Y is $\mathrm{CAT}(0)$ with isolated flats, and that $\pi_1 Y$

is hyperbolic relative to the free abelian subgroups represented by the cubical tori (see [26]).

Now we describe a cube complex homeomorphic to Y, obtained by subdividing the cells of Y. The complex Y has a single vertex (the wedge point), so all corners of all the polygons are glued at the wedge point. The only based loops in a cubical torus of length 1 are the edges of the standard cellulation of that torus. To obtain C, we subdivide each n–torus into 2^n cubes of dimension n, and each p–sided polygon into p squares. The link at the wedge point is unchanged, but now there are additional vertices. The link of one of the new vertices in an n–torus is a standard $(n-1)$–sphere, together possibly with some arcs of length π joining its north and south poles. (This is if the new vertex lies in the middle of an edge of the standard cellulation which is traversed by some of the polygons.) The new vertex at the center of a p–gon has link which is a circle of length $\frac{p\pi}{2}$. Since $p \geq 5$, the link condition is satisfied here as well.

The universal cover of C is therefore a CAT(0) cube complex on which $\pi_1 Y$ acts geometrically. Since the parabolic subgroups are abelian, the Assumptions 1.1 and 1.2 both hold, and we may apply our main theorem to conclude that G acts virtually co-specially.   □

Example 5.2. Let G be given by the following presentation:

$$\left\langle a_1 \ldots, a_6, b_1, \ldots, b_6 \;\middle|\; \begin{array}{c} [a_1, b_1], \ldots, [a_6, b_6], \\ a_1 a_2 a_3 a_4 a_5 a_6, b_1 b_2 b_3 b_4 b_5 b_6, \\ a_4 b_2 b_5 a_3 a_1, a_3 a_5 b_1 b_4 a_6 \end{array} \right\rangle.$$

A presentation complex for G can be built from the wedge of six two-dimensional tori by attaching two right-angled hexagons and two right-angled pentagons. One can check (by hand or with a computer) that the link of the vertex is a graph of girth 4. This link is highly non-planar, suggesting that the boundary at infinity is most likely non-planar (but see [13, 5] for some cautionary tales). If the boundary at infinity is non-planar, this gives a proof that G is not virtually a 3–manifold group, and therefore not covered by previous theorems about 3–manifolds [35, 41, 1].

6. Application to the Relative Cannon Conjecture

To any relatively hyperbolic pair $(G, \mathcal{P})$ is associated its *Bowditch boundary* $\partial(G, \mathcal{P})$ [4]. The Relative Cannon Conjecture asserts that if $\mathcal{P}$ is a non-empty collection of free abelian groups and $\partial(G, \mathcal{P})$ is homeomorphic to a 2–sphere, then G is Kleinian (see [20, Conjecture 1.3] and the discussion in that paper). The usual Cannon Conjecture

makes the same assertion when $\mathcal{P}$ is empty and G has no non-trivial finite normal subgroup (see [9, Conjecture 11.34] and [11, Conjecture 5.1]).

The following result is a generalization of [16, Theorem 1.1]. Given the work we have already done, the proof is very similar.

Theorem 6.1. *Suppose that $(G, \mathcal{P})$ is relatively hyperbolic and $\mathcal{P}$ is a non-empty collection of free abelian groups. Suppose further that $\partial(G, \mathcal{P}) \cong \mathbb{S}^2$, and that $(G, \mathcal{P})$ acts weakly relatively geometrically on a $\mathrm{CAT}(0)$ cube complex. Then G is Kleinian.*

Proof. Note that each element $P \in \mathcal{P}$ fixes a point ξ_P in $\partial(G, \mathcal{P}) \cong \mathbb{S}^2$ and acts properly cocompactly on the complement [4]. Since this complement is homeomorphic to $\mathbb{R}^2$, each $P \in \mathcal{P}$ must have rank 2.

Since $(G, \mathcal{P})$ acts weakly relatively geometrically on a $\mathrm{CAT}(0)$ cube complex, we may apply Theorem 4.5. Let $\{L_P \mid P \in \mathcal{P}\}$ be the subgroups from the conclusion of that theorem. For any family of infinite cyclic subgroups $\mathcal{N} = \{N_P \mid P \in \mathcal{P}\}$ with each $N_P \leq L_P$ the quotient group $G(\mathcal{N})$ is a hyperbolic virtually special group (each P/N_P is virtually cyclic, and hence hyperbolic and virtually special). By [20, Theorem 1.2], the boundary of $G(\mathcal{N})$ is a 2–sphere so long as the filling is sufficiently long. Since the elements of $\mathcal{P}$ are free abelian, the parent group G has no nontrivial finite normal subgroup. By [17, Theorem 7.2], $G(\mathcal{N})$ also has no finite normal subgroup (at least for sufficiently long fillings of this form), so $G(\mathcal{N})$ acts faithfully on its boundary. Haïssinsky [24, Theorem 1.10] states that a cubulated hyperbolic group with planar boundary is virtually Kleinian.

We claim that in fact the quotient $G(\mathcal{N})$ is Kleinian for sufficiently long such fillings. We argue as in the last paragraph of Section 1.3 of Markovic [29]. Haïssinsky's theorem gives us a finite index $\Gamma < G(\mathcal{N})$ so that Γ is cocompact Kleinian and hence quasi-isometric to $\mathbb{H}^3$. This implies $G(\mathcal{N})$ is quasi-isometric to $\mathbb{H}^3$. By a result of Cannon–Cooper [10] the group $G(\mathcal{N})$ acts geometrically on $\mathbb{H}^3$. Since $G(\mathcal{N})$ has no finite normal subgroup, it acts faithfully. In other words it is cocompact Kleinian.

We now take a sequence of longer and longer fillings of this form, obtaining a collection $\{G \twoheadrightarrow G_i\}$ of quotients so that each G_i is Kleinian. By the fundamental theorem of relatively hyperbolic Dehn filling [34, Theorem 1.1] we may assume that this sequence is *stably faithful* in the sense of [20, Definition 10.1]. Each $G \twoheadrightarrow G_i$ gives a representation $\rho_i \colon G \to \mathrm{Isom}(\mathbb{H}^3)$. We now argue as in the proof of [20, Corollary

1.4] that these representations can be conjugated to a sequence of representations that subconverge to a discrete faithful representation of G into $\mathrm{Isom}(\mathbb{H}^3)$. $\qquad\square$

The following is an immediate consequence of Theorems C and 6.1.

Corollary 6.2. *Suppose that $(G,\mathcal{P})$ is relatively hyperbolic, that elements of $\mathcal{P}$ are free abelian, that $\partial(G,\mathcal{P}) \cong \mathbb{S}^2$, and that G acts properly and cocompactly on a $\mathrm{CAT}(0)$ cube complex. Then G is Kleinian.*

Appendix A. About double coset separability

In this appendix we generalize [19, Proposition 6.2], a technical result which helps to prove double coset separability. Most of the proof is the same as in [19], and we largely keep the same notation from there.

Definition A.1. (cf. [19, Definition 3.1]) Let P be a group, $B_1, B_2 \subseteq P$ are subgroups, and S a finite subset. A normal subgroup $N \trianglelefteq P$ is (B_1, B_2, S)–*wide* if whenever there are $b_1 \in B_1$, $b_2 \in B_2$ and $s \in S$ so that $b_1 s b_2 \in N$ we have $s \in B_1 B_2$.

Remark A.2. This is a generalization of wideness as in Definition 4.2. Namely, if N is (B, B, S)–wide, then N is (B, S)–wide.

Lemma A.3. *(cf. [19, Lemma 5.1]) Suppose that P is a group and that B_1, B_2 are subgroups so that $B_1 B_2$ is a separable subset of P. For any finite set S there exists a finite-index normal subgroup $K_S \leq P$ so that for any $N \trianglelefteq P$ with $N \leq K_S$, the subgroup N is (B_1, B_2, S)–wide in P.*

Proof. For each $s \in S \smallsetminus B_1 B_2$, choose some $P_s \leq P$ finite-index so that $B_1 B_2 \subseteq P_s$ and $s \notin P_s$. Let $P_S = \bigcap \{P_s \mid s \in S \smallsetminus B_1 B_2\}$ and let K_S be the normal core of P_S. The subgroups $K_S \leq P_S$ are both finite-index in P. The double coset $B_1 B_2$ is contained in P_S.

Choose $N \trianglelefteq P$ finite-index and contained in K_S. It follows that N is contained in P_S, which is all we will use to show N is (B_1, B_2, S)–wide. Let $b_1 \in B_1, b_2 \in B_2$ and $s \in S$ and suppose $b_1 s b_2 \in N$. If $s \in B_1 B_2$ then there is nothing to prove so suppose that $s \notin B_1 B_2$. Then $s \notin P_S$. However, $b_1 s b_2 \in N \subseteq P_S$, and also $b_1^{-1} \in B_1 \subseteq B_1 B_2 \subseteq P_S$ and similarly $b_2^{-1} \in P_S$. Since P_S is a subgroup, we have $s = b_1^{-1}(b_1 s b_2)b_2^{-1} \in P_S$, which contradicts $s \notin P_S$. $\qquad\square$

The following theorem is a generalization of [19, Proposition 6.2] and is the same as [33, Theorem 3.21]. Our proof is similar to the one there.

Proposition A.4. *(cf. [19, Proposition 6.2]) Suppose $(G,\mathcal{P})$ is relatively hyperbolic. Let $\mathcal{H}$ be a finite collection of relatively quasi-convex*

subgroups of $(G, \mathcal{P})$, so that for any $H_1, H_2 \in \mathcal{H}$, any $g_1, g_2 \in G$, and any $P \in \mathcal{P}$ the double coset $(H_1^{g_1} \cap P)(H_2^{g_2} \cap P)$ is separable in P.[2]

Let $F \subseteq G$ be a finite subset. There exist finite-index subgroups $\{K_P \trianglelefteq P \mid P \in \mathcal{P}\}$ so that if $\mathcal{N} = \{N_P \trianglelefteq P \mid P \in \mathcal{P}\}$ is a collection with $N_P \leq K_P$ for each P, and $K = \langle\!\langle \bigcup \mathcal{N} \rangle\!\rangle_G$, then for all $f \in F$ and $\Psi, \Theta \in \mathcal{H}$ for which $1 \notin \Psi \Theta f$ we have $K \cap \Psi \Theta f = \emptyset$.

Proof. We will follow the proof from [19, Proposition 6.2], keeping most of the notation and indicating only the changes which must be made.

We have the following setup from [19]. It suffices to deal with a single pair (Ψ, Θ) from $\mathcal{H}$, for we can then take intersections of the K_P over each of the finitely many pairs to get the required result. We therefore fix such a pair.

The cusped space for $(G, \mathcal{P})$ is denoted X, and is δ–hyperbolic. Let λ be a quasi-convexity constant for each $H \in \mathcal{H}$, let $M = \max\{d_X(1, f) \mid f \in F\}$ and let $\alpha = 10\delta + 2M + 4\lambda$. Associated to Ψ is a finite collection $\mathcal{D}$ of Ψ–conjugacy classes of maximal uniquely parabolic subgroups of Ψ, and for each $D \in \mathcal{D}$ there are $P_D \in \mathcal{P}$ and $c_D \in G$ so $D \leq P_D^{c_D}$. Similarly for Θ we have a finite collection $\mathcal{E}$ and for $E \in \mathcal{E}$ there are $P_E \in \mathcal{P}$ and $d_E \in G$ so $E \leq P_E^{d_E}$. For $P \in \mathcal{P}$ choose the set $S_P \subset P$ exactly as in [19]. Namely, we define

$$S_P \supseteq \{p \in P \mid d_X(1, p) \leq 44\delta + 8M + 16\lambda + 2L_1 + 3\}$$

to be a finite set so that any filling which is (H, S_P)–wide for every $H \in \mathcal{H}$ will satisfy the conclusion of [19, Lemma 4.2] with L_1, L_2 as specified in the proof of [19, Proposition 6.2].

We make a change from [19] to the requirements on the filling kernels, as we now explain. In [19] the additional requirements were indexed over certain pairs (B_1, B_2) of parabolic subgroups of Ψ and Θ. We instead index our requirements over the finite set of triples (c_D, d_E, p), where $P_E = P_D$ and $p \in P_D$ satisfies $d_X(1, p) \leq 2\alpha + 4\delta$. For such a triple $q = (c_D, d_E, p)$ choose a finite index normal subgroup $K_q \leq P_D$ so that any $N \trianglelefteq P_D$ with $N \leq K_q$ is $\left(D^{c_D^{-1}}, \left(E^{d_E^{-1}}\right)^p, S_P\right)$–wide. This is possible by Lemma A.3. For each $P \in \mathcal{P}$ for which $P = P_D$ in one of these triples, let K_P be the intersection of all such K_q.

Choose $N_P \leq K_P$ and consider the filling

$$G \to G\left(\{N_P \mid P \in \mathcal{P}\}\right) = G/K.$$

We remark that this filling must be (H, S_P)–wide for every $H \in \mathcal{H}$, by Remark A.2.

[2]In particular (taking $H_1 = H_2$ and $g_1 = g_2$) the subgroups $H_1^{g_1} \cap P$ are separable in P.

There is no issue with the setup for proving $K \cap \Psi\Theta f = \emptyset$. Moreover, Case 1 just uses (Ψ, S_P)–wideness, and works verbatim in this setting.

For Case 2, the beginning of the proof works as written. The first issue with the proof from [19] in this setting comes with the calculation about $u^{-1}ku$, which in [19] uses the assumption that parabolics are abelian.

We pick up the argument at the reference to Figure 2 in that proof, and adjust it as follows (keeping the notation from [19]):

Note that $k \in K \cap \mathrm{Stab}(A)$, where A is the horoball based on scP and $w \in scP$, so $w^{-1}kw \in N_P \leq P$. Also

$$
\begin{aligned}
w^{-1}kw &= (w^{-1}u)(u^{-1}kv)(v^{-1}z)(z^{-1}w) \\
&= (w^{-1}u)\left[(u^{-1}kv)(z^{-1}w)\right]\left((z^{-1}w)^{-1}(v^{-1}z)(z^{-1}w)\right).
\end{aligned}
$$

Let $B_1 = D^{c^{-1}}$, $B_2 = (E^{d^{-1}})^{(z^{-1}w)^{-1}}$, and $s = (u^{-1}kv)(z^{-1}w)$. Note also that $z^{-1}w \in P$, so $B_1, B_2 \leq P$. Moreover, $d_X(1, (z^{-1}w)^{-1}) \leq 2\alpha + 4\delta$ (see [19] for details of this claim). Thus, the triple $(c, d, (z^{-1}w)^{-1})$ is one of the finitely many triples described above, so N_P is (B_1, B_2, S_P)–wide.

As in [19], the X–length of $(u^{-1}kv)$ is at most $2\alpha + 2L_1 + 3$ and the X–length of $(z^{-1}w)$ is at most $2\alpha + 4\delta$, so $[(u^{-1}kv)(z^{-1}w)] \in S_P$. Let $b_1 = w^{-1}u \in B_1$, and $b_2 = (z^{-1}w)^{-1}(v^{-1}z)(z^{-1}w)$. The above expression shows $b_1\left[(u^{-1}kv)(z^{-1}w)\right]b_2 \in N_P$. Because N_P is (B_1, B_2, S_P)–wide, we know that $[(u^{-1}kv)(z^{-1}w)] \in B_1B_2$, so $w^{-1}kw \in B_1B_2$. Choose $\beta_1 \in B_1$ and $\beta_2 \in B_2$ so $w^{-1}kw = \beta_1\beta_2$. From the definition of B_2 there is $e \in E$ so that $\beta_2 = w^{-1}zd^{-1}edz^{-1}w$.

Recall the following equations from [19]:

$$w = \psi_w c, \quad z = \psi\theta_z d, \quad v = \psi\theta_v d,$$

where $\psi_w \in \Psi$, $\theta_z, \theta_v \in \Theta$.

Now, similar to [19], but with a slightly different calculation:

$$
\begin{aligned}
k\psi\theta &= w(w^{-1}kw)(w^{-1}z)(z^{-1}v)(v^{-1}\psi\theta) \\
&= w\left(\beta_1 w^{-1}zd^{-1}edz^{-1}w\right)(w^{-1}z)(z^{-1}v)(v^{-1}\psi\theta) \\
&= w\beta_1(w^{-1}z)d^{-1}ed(z^{-1}v)(v^{-1}\psi\theta) \\
&= \psi_w(c\beta_1 c^{-1})c(w^{-1}\psi)(\psi^{-1}z)d^{-1}ed(z^{-1}v)(v^{-1}\psi\theta) \\
&= \left[\psi_w(c\beta_1 c^{-1})\psi_w^{-1}\psi\right] \cdot \left[\theta_z \, e \, \theta_z^{-1}\theta\right]
\end{aligned}
$$

giving an expression for $k\psi\theta$ as an element of $\Psi\Theta$. Thus, $k\cdot g = k\psi\theta f \in \Psi\Theta f$, the same contradiction as in [19]. $\qquad\square$

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