

Abelian networks and a weak version of Merino's theorem

Swee Hong Chan
Cornell University

Banff International Research Station-CMO

November 8, 2015

Merino's Theorem

Merino's Theorem for undirected graphs

Theorem 1 ([ML97])

Let G be a connected, undirected graph with a chosen vertex $s \in V$. If $\text{Rec}(G, s)$ is the set of recurrent states of the sandpile model $\text{Sand}(G, s)$, then:

$$\sum_{\mathbf{q} \in \text{Rec}(G, s)} y^{|\mathbf{q}|} = T_G(1; y),$$

where $T_G(x; y)$ is the Tutte polynomial for the graph G .

Corollary 2 (weak version of Merino's Theorem)

The polynomial $\sum_{\mathbf{q} \in \text{Rec}(G, s)} y^{|\mathbf{q}|}$ does not depend on the choice of sink $s \in V$.

Merino's Theorem for undirected graphs

Theorem 1 ([ML97])

Let G be a connected, undirected graph with a chosen vertex $s \in V$. If $\text{Rec}(G, s)$ is the set of recurrent states of the sandpile model $\text{Sand}(G, s)$, then:

$$\sum_{\mathbf{q} \in \text{Rec}(G, s)} y^{|\mathbf{v}(\mathbf{q})|} = T_G(1; y),$$

where $T_G(x; y)$ is the Tutte polynomial for the graph G .

Corollary 2 (weak version of Merino's Theorem)

The polynomial $\sum_{\mathbf{q} \in \text{Rec}(G, s)} y^{|\mathbf{v}(\mathbf{q})|}$ does not depend on the choice of sink $s \in V$.

A conjecture of Perrot and Pham

Conjecture 1 ([PV13])

Let G be a strongly connected digraph with a chosen vertex $s \in V$. Let $\text{Rec}(G, s, \sim)$ be the set of recurrent classes of the sandpile model on the digraph. If the polynomial $\mathcal{P}(G, s; y)$ is given by:

$$\mathcal{P}(G, s; y) = \sum_{[\mathbf{q}] \in \text{Rec}(G, s, \sim)} y^{|\mathbf{q}|},$$

then $\mathcal{P}(G, s; y)$ does not depend on the choice of vertex s .

Weak version of Merino's theorem for abelian networks

Theorem 3 ([Cha14])

Let \mathcal{M} be a Markovian network and let $s \in A$ be a letter of \mathcal{M} . Let $\text{Rec}(G, s, \sim)$ be the set of recurrent classes of \mathcal{M}_s . If the polynomial $\mathcal{P}(\mathcal{M}, s; y)$ is given by:

$$\mathcal{P}(\mathcal{M}, s; y) = \sum_{[\mathbf{q}] \in \text{Rec}(\mathcal{M}_s; \sim)} y^{|\mathbf{v}|([\mathbf{q}])}.$$

Then $\mathcal{P}(\mathcal{M}, s; y)$ does not depend on the choice of sink s for the Markovian network.

Remark

In particular, Theorem 3 verifies Conjecture 1 by taking \mathcal{M} to be the sandpile model on digraphs.

Weak version of Merino's theorem for abelian networks

Theorem 3 ([Cha14])

Let \mathcal{M} be a Markovian network and let $s \in A$ be a letter of \mathcal{M} . Let $\text{Rec}(G, s, \sim)$ be the set of recurrent classes of \mathcal{M}_s . If the polynomial $\mathcal{P}(\mathcal{M}, s; y)$ is given by:

$$\mathcal{P}(\mathcal{M}, s; y) = \sum_{[\mathbf{q}] \in \text{Rec}(\mathcal{M}_s; \sim)} y^{|\nu([\mathbf{q}])|}.$$

Then $\mathcal{P}(\mathcal{M}, s; y)$ does not depend on the choice of sink s for the Markovian network.

Remark

In particular, Theorem 3 verifies Conjecture 1 by taking \mathcal{M} to be the sandpile model on digraphs.

Merino's Theorem (ct'd)

There are several notions in Theorem 3 that needs to be properly defined, namely:

- Markovian network;
- Sink of a Markovian network;
- Recurrent classes;
- Level of a recurrent class.

Abelian networks

Abelian networks

An **abelian network** \mathcal{N} [BL13] consists of the following data:

- The **state space** $Q = \{\mathbf{q}_1, \mathbf{q}_2, \dots, \mathbf{q}_m\}$;
- The **alphabet space** $A = \{a_1, a_2, \dots, a_n\}$;
- For each $a \in A$, a **transition function** $t_a : Q \rightarrow Q$ and an **output vector** $\mathbf{o}_a : Q \rightarrow \mathbb{N}^A$ that satisfies the *abelian property*, i.e.:

$$t_a \circ t_b = t_b \circ t_a$$

$$\mathbf{o}_b(t_a(\mathbf{q})) + \mathbf{o}_a(\mathbf{q}) = \mathbf{o}_a(t_b(\mathbf{q})) + \mathbf{o}_b(\mathbf{q}),$$

for all $a, b \in A$ and $\mathbf{q} \in Q$.

Abelian networks (ct'd)

We use the pair $\mathbf{x}.\mathbf{q}$ to describe the current state $\mathbf{q} \in Q$ of the network and the number of letters $\mathbf{x} \in \mathbb{Z}^A$ waiting to be executed.

Executing a letter $a \in A$ on $\mathbf{x}.\mathbf{q}$ gives us a new pair $\mathbf{x}'.\mathbf{q}'$, where

$$\begin{aligned}\mathbf{q}' &= t_a(\mathbf{q}); \\ \mathbf{x}' &= \mathbf{x} - \mathbf{1}_a + \mathbf{o}_a(\mathbf{q}).\end{aligned}$$

We use $\pi_a(\mathbf{x}.\mathbf{q})$ as a shorthand for the pair $\mathbf{x}'.\mathbf{q}'$.

If $\omega = a_1 a_2 \dots a_r \in A^*$, then executing ω on $\mathbf{x}.\mathbf{q}$ gives us:

$$\pi_\omega(\mathbf{x}.\mathbf{q}) = \pi_{a_r} \circ \pi_{a_{r-1}} \circ \dots \circ \pi_{a_1}(\mathbf{x}.\mathbf{q}).$$

Abelian networks (ct'd)

We use the pair $\mathbf{x}.\mathbf{q}$ to describe the current state $\mathbf{q} \in Q$ of the network and the number of letters $\mathbf{x} \in \mathbb{Z}^A$ waiting to be executed.

Executing a letter $a \in A$ on $\mathbf{x}.\mathbf{q}$ gives us a new pair $\mathbf{x}'.\mathbf{q}'$, where

$$\begin{aligned}\mathbf{q}' &= t_a(\mathbf{q}); \\ \mathbf{x}' &= \mathbf{x} - \mathbf{1}_a + \mathbf{o}_a(\mathbf{q}).\end{aligned}$$

We use $\pi_a(\mathbf{x}.\mathbf{q})$ as a shorthand the pair $\mathbf{x}'.\mathbf{q}'$.

If $\omega = a_1 a_2 \dots a_r \in A^*$, then executing ω on $\mathbf{x}.\mathbf{q}$ gives us:

$$\pi_\omega(\mathbf{x}.\mathbf{q}) = \pi_{a_r} \circ \pi_{a_{r-1}} \circ \dots \circ \pi_{a_1}(\mathbf{x}.\mathbf{q}).$$

Abelian networks (ct'd)

We use the pair $\mathbf{x}.\mathbf{q}$ to describe the current state $\mathbf{q} \in Q$ of the network and the number of letters $\mathbf{x} \in \mathbb{Z}^A$ waiting to be executed.

Executing a letter $a \in A$ on $\mathbf{x}.\mathbf{q}$ gives us a new pair $\mathbf{x}'.\mathbf{q}'$, where

$$\begin{aligned}\mathbf{q}' &= t_a(\mathbf{q}); \\ \mathbf{x}' &= \mathbf{x} - \mathbf{1}_a + \mathbf{o}_a(\mathbf{q}).\end{aligned}$$

We use $\pi_a(\mathbf{x}.\mathbf{q})$ as a shorthand the pair $\mathbf{x}'.\mathbf{q}'$.

If $\omega = a_1 a_2 \dots a_r \in A^*$, then executing ω on $\mathbf{x}.\mathbf{q}$ gives us:

$$\pi_\omega(\mathbf{x}.\mathbf{q}) = \pi_{a_r} \circ \pi_{a_{r-1}} \circ \dots \circ \pi_{a_1}(\mathbf{x}.\mathbf{q}).$$

Production matrix

We say that a network \mathcal{N} is **irreducible** if for any $\mathbf{q}, \mathbf{q}' \in Q$ there exists a word $\omega \in A^*$ such that $t_\omega(\mathbf{q}) = \mathbf{q}'$.

The **production matrix** $P \in \text{Mat}(A, \mathbb{Q})$ is a square matrix indexed by A such that the column of P associated to $a \in A$ is equal to:

$$P_a = \lim_{n \rightarrow \infty} \frac{1}{n} \sum_{i=1}^n \mathbf{o}_a((t_a)^i(\mathbf{q})).$$

Halting networks

An irreducible abelian network \mathcal{H} is called a **halting network** if the production matrix P has Perron eigenvalue strictly less than 1.

If \mathcal{H} is a halting network, then for each $a \in A$ there exists a **global action** $\tau_a : Q \rightarrow Q$ that sends one state of \mathcal{H} to another state.

A state $\mathbf{q} \in Q$ of \mathcal{H} is **recurrent** if for all $\mathbf{q}' \in Q$ there exists a word $\omega = a_1 \dots a_r \in A^*$ such that

$$\tau_{a_r} \circ \dots \circ \tau_{a_1}(\mathbf{q}') = \mathbf{q}.$$

Halting networks

An irreducible abelian network \mathcal{H} is called a **halting network** if the production matrix P has Perron eigenvalue strictly less than 1.

If \mathcal{H} is a halting network, then for each $a \in A$ there exists a **global action** $\tau_a : Q \rightarrow Q$ that sends one state of \mathcal{H} to another state.

A state $\mathbf{q} \in Q$ of \mathcal{H} is **recurrent** if for all $\mathbf{q}' \in Q$ there exists a word $\omega = a_1 \dots a_r \in A^*$ such that

$$\tau_{a_r} \circ \dots \circ \tau_{a_1}(\mathbf{q}') = \mathbf{q}.$$

Markovian networks

Markovian networks

We say that an irreducible abelian network \mathcal{M} is **Markovian** if

- the production matrix P is an irreducible matrix;
- $\mathbf{1}^\top \cdot P = \mathbf{1}^\top$.

Examples of Markovian networks

Sandpile network

Let $G = (V, E)$ be a strongly-connected digraph and let $V = \{1, \dots, n\}$.

The alphabet space A of $\text{Sand}(G)$ is the vertex set V .

The state space Q of $\text{Sand}(G)$ is $\prod_{i=1}^n \mathbb{Z}_{\text{outdeg}(i)}$.

For each $i \in V$, the transition function $t_i : Q \rightarrow Q$ is defined by

$$t_i(z_1, z_2, \dots, z_n) = (z_1, \dots, z_{i-1}, z_i + 1, z_{i+1}, \dots, z_n).$$

The output vector $\mathbf{o}_i : Q \rightarrow \mathbb{N}^A$ is defined by:

$$\mathbf{o}_i(z_1, \dots, z_n) = \begin{cases} \mathbf{0} & \text{if } z_i \neq \text{outdeg}(i) - 1; \\ (a_{ij})_{j \in V} & \text{if } z_i = \text{outdeg}(i) - 1. \end{cases}$$

Examples of Markovian networks

Sandpile network

Let $G = (V, E)$ be a strongly-connected digraph and let $V = \{1, \dots, n\}$.

The alphabet space A of $\text{Sand}(G)$ is the vertex set V .

The state space Q of $\text{Sand}(G)$ is $\prod_{i=1}^n \mathbb{Z}_{\text{outdeg}(i)}$.

For each $i \in V$, the transition function $t_i : Q \rightarrow Q$ is defined by

$$t_i(z_1, z_2, \dots, z_n) = (z_1, \dots, z_{i-1}, z_i + 1, z_{i+1}, \dots, z_n).$$

The output vector $\mathbf{o}_i : Q \rightarrow \mathbb{N}^A$ is defined by:

$$\mathbf{o}_i(z_1, \dots, z_n) = \begin{cases} \mathbf{0} & \text{if } z_i \neq \text{outdeg}(i) - 1; \\ (a_{ji})_{j \in V} & \text{if } z_i = \text{outdeg}(i) - 1. \end{cases}$$

Examples of Markovian networks (ct'd)

Rotor network

The alphabet space A of $\text{Rotor}(G)$ is the vertex set V .

The state space Q of $\text{Rotor}(G)$ is $\prod_{i=1}^n \mathbb{Z}_{\text{outdeg}(i)}$.

For each $i \in V$, the transition function $t_i : Q \rightarrow Q$ is defined by

$$t_i(z_1, z_2, \dots, z_n) = (z_1, \dots, z_{i-1}, z_i + 1, z_{i+1}, \dots, z_n).$$

For each $i \in V$, choose a cyclic ordering $n_{i,0}, n_{i,1}, \dots, n_{i,\text{outdeg}(i)-1}$ for the neighbors of i in G . The output vector $\mathfrak{o}_i : Q \rightarrow \mathbb{N}^A$ is defined by:

$$\mathfrak{o}_i(z_1, \dots, z_n) = \mathbf{1}_{n_{i,z_i+1}}.$$

Examples of Markovian networks (ct'd)

Rotor network

The alphabet space A of $\text{Rotor}(G)$ is the vertex set V .

The state space Q of $\text{Rotor}(G)$ is $\prod_{i=1}^n \mathbb{Z}_{\text{outdeg}(i)}$.

For each $i \in V$, the transition function $t_i : Q \rightarrow Q$ is defined by

$$t_i(z_1, z_2, \dots, z_n) = (z_1, \dots, z_{i-1}, z_i + 1, z_{i+1}, \dots, z_n).$$

For each $i \in V$, choose a cyclic ordering $n_{i,0}, n_{i,1}, \dots, n_{i,\text{outdeg}(i)-1}$ for the neighbors of i in G . The output vector $\mathbf{o}_i : Q \rightarrow \mathbb{N}^A$ is defined by:

$$\mathbf{o}_i(z_1, \dots, z_n) = \mathbf{1}_{n_{i,z_i+1}}.$$

Level of a state

Level of a state

Let \mathcal{M} be a Markovian network, choose an initial state $\mathbf{q}_0 \in Q$.
The **level** of a state $\mathbf{q} \in Q$ is defined by $\text{lvl}(\mathbf{q}) = \mathbf{1} \cdot \mathbf{x} + 1$, where $\mathbf{x} \in \mathbb{Z}^A$ satisfies $\pi_\omega(\mathbf{x}, \mathbf{q}_0) = \mathbf{0}, \mathbf{q}$.

Remark

The level of a state is well defined and does not depend on the choice of vector \mathbf{x} if \mathcal{M} is Markovian.

Level of a state

Let \mathcal{M} be a Markovian network, choose an initial state $\mathbf{q}_0 \in Q$.
The **level** of a state $\mathbf{q} \in Q$ is defined by $\text{lvl}(\mathbf{q}) = \mathbf{1} \cdot \mathbf{x} + 1$, where $\mathbf{x} \in \mathbb{Z}^A$ satisfies $\pi_\omega(\mathbf{x}, \mathbf{q}_0) = \mathbf{0}, \mathbf{q}$.

Remark

The level of a state is well defined and does not depend on the choice of vector \mathbf{x} if \mathcal{M} is Markovian.

Sink of a Markovian network

Markovian network with sink

Let \mathcal{M} be a Markovian network, and let $s \in A$ be a letter of \mathcal{M} . The **Markovian network with sink**, denoted by \mathcal{M}_s , is the abelian network constructed from \mathcal{M} by removing all the alphabets of type s that is produced by the network.

Example of Markovian networks with sink

Sandpile network with sink

Let $\mathcal{M} = \text{Sand}(G)$, and let $s \in V(G)$.

The alphabet space A of $\text{Sand}(G, s)$ is the vertex set V .

The state space Q of $\text{Sand}(G, s)$ is $\prod_{i=1}^n \mathbb{Z}_{\text{outdeg}(i)}$.

For each $i \in V$, the transition function $t_i : Q \rightarrow Q$ is defined by

$$t_i(z_1, z_2, \dots, z_n) = (z_1, \dots, z_{i-1}, z_i + 1, z_{i+1}, \dots, z_n).$$

The output vector $\mathbf{o}_i : Q \rightarrow \mathbb{N}^A$ is defined by:

$$\mathbf{o}_i(z_1, \dots, z_n) = \begin{cases} \mathbf{0} & \text{if } z_i \neq \text{outdeg}(i) - 1; \\ (a_{ji} \mathbf{1}_{j \neq s})_{j \in V} & \text{if } z_i = \text{outdeg}(i) - 1. \end{cases}$$

Example of Markovian networks with sink

Sandpile network with sink

Let $\mathcal{M} = \text{Sand}(G)$, and let $s \in V(G)$.

The alphabet space A of $\text{Sand}(G, s)$ is the vertex set V .

The state space Q of $\text{Sand}(G, s)$ is $\prod_{i=1}^n \mathbb{Z}_{\text{outdeg}(i)}$.

For each $i \in V$, the transition function $t_i : Q \rightarrow Q$ is defined by

$$t_i(z_1, z_2, \dots, z_n) = (z_1, \dots, z_{i-1}, z_i + 1, z_{i+1}, \dots, z_n).$$

The output vector $\mathbf{o}_i : Q \rightarrow \mathbb{N}^A$ is defined by:

$$\mathbf{o}_i(z_1, \dots, z_n) = \begin{cases} 0 & \text{if } z_i \neq \text{outdeg}(i) - 1; \\ (a_{ij} \mathbf{1}_{j \neq s})_{j \in V} & \text{if } z_i = \text{outdeg}(i) - 1. \end{cases}$$

Example of Markovian networks with sink

Sandpile network with sink

Let $\mathcal{M} = \text{Sand}(G)$, and let $s \in V(G)$.

The alphabet space A of $\text{Sand}(G, s)$ is the vertex set V .

The state space Q of $\text{Sand}(G, s)$ is $\prod_{i=1}^n \mathbb{Z}_{\text{outdeg}(i)}$.

For each $i \in V$, the transition function $t_i : Q \rightarrow Q$ is defined by

$$t_i(z_1, z_2, \dots, z_n) = (z_1, \dots, z_{i-1}, z_i + 1, z_{i+1}, \dots, z_n).$$

The output vector $\mathbf{o}_i : Q \rightarrow \mathbb{N}^A$ is defined by:

$$\mathbf{o}_i(z_1, \dots, z_n) = \begin{cases} \mathbf{0} & \text{if } z_i \neq \text{outdeg}(i) - 1; \\ (a_{ji} \mathbf{1}_{j \neq s})_{j \in V} & \text{if } z_i = \text{outdeg}(i) - 1. \end{cases}$$

Markovian networks with sink (ct'd)

- The state space of \mathcal{M}_s is equal to the state space of \mathcal{M} .
Hence we can define the level of a state \mathbf{q} of \mathcal{M}_s to be equal to the level of \mathbf{q} in \mathcal{M} .
- The production matrix of \mathcal{M}_s has Perron eigenvalue strictly less than 1, so \mathcal{M}_s is a halting network.
Therefore, it makes sense to talk about the recurrent states of the network \mathcal{M}_s .

Markovian networks with sink (ct'd)

- The state space of \mathcal{M}_s is equal to the state space of \mathcal{M} . Hence we can define the level of a state \mathbf{q} of \mathcal{M}_s to be equal to the level of \mathbf{q} in \mathcal{M} .
- The production matrix of \mathcal{M}_s has Perron eigenvalue strictly less than 1, so \mathcal{M}_s is a halting network. Therefore, it makes sense to talk about the recurrent states of the network \mathcal{M}_s .

Markovian networks with sink (ct'd)

- The state space of \mathcal{M}_s is equal to the state space of \mathcal{M} .
Hence we can define the level of a state \mathbf{q} of \mathcal{M}_s to be equal to the level of \mathbf{q} in \mathcal{M} .
- The production matrix of \mathcal{M}_s has Perron eigenvalue strictly less than 1, so \mathcal{M}_s is a halting network.

Therefore, it makes sense to talk about the recurrent states of the network \mathcal{M}_s .

Markovian networks with sink (ct'd)

- The state space of \mathcal{M}_s is equal to the state space of \mathcal{M} .
Hence we can define the level of a state \mathbf{q} of \mathcal{M}_s to be equal to the level of \mathbf{q} in \mathcal{M} .
- The production matrix of \mathcal{M}_s has Perron eigenvalue strictly less than 1, so \mathcal{M}_s is a halting network.
Therefore, it makes sense to talk about the recurrent states of the network \mathcal{M}_s .

Recurrent class

Recurrent class

Let \mathcal{M} be a Markovian network and let $s \in A$. We define an equivalence relation \sim on $\text{Rec}(\mathcal{M}_s)$ by $\mathbf{q} \sim \mathbf{q}'$ for $\mathbf{q}, \mathbf{q}' \in \text{Rec}(\mathcal{M}_s)$ if $\mathbf{q}' = (\tau_s)^k(\mathbf{q})$ for some $k \in \mathbb{N}$.

A recurrent class $[\mathbf{q}]$ is the equivalence class of an element $\mathbf{q} \in \text{Rec}(\mathcal{M}_s)$.

The level of a recurrent class $[\mathbf{q}]$ is defined by

$$l([\mathbf{q}]) = \max_{\mathbf{q} \in [\mathbf{q}]} l(\mathbf{q}).$$

Recurrent class

Let \mathcal{M} be a Markovian network and let $s \in A$. We define an equivalence relation \sim on $\text{Rec}(\mathcal{M}_s)$ by $\mathbf{q} \sim \mathbf{q}'$ for $\mathbf{q}, \mathbf{q}' \in \text{Rec}(\mathcal{M}_s)$ if $\mathbf{q}' = (\tau_s)^k(\mathbf{q})$ for some $k \in \mathbb{N}$.

A **recurrent class** $[\mathbf{q}]$ is the equivalence class of an element $\mathbf{q} \in \text{Rec}(\mathcal{M}_s)$.

The level of a recurrent class $[\mathbf{q}]$ is defined by

$$\text{lvl}([\mathbf{q}]) = \max_{\mathbf{q} \in [\mathbf{q}]} \text{lvl}(\mathbf{q}).$$

Recurrent class

Let \mathcal{M} be a Markovian network and let $s \in A$. We define an equivalence relation \sim on $\text{Rec}(\mathcal{M}_s)$ by $\mathbf{q} \sim \mathbf{q}'$ for $\mathbf{q}, \mathbf{q}' \in \text{Rec}(\mathcal{M}_s)$ if $\mathbf{q}' = (\tau_s)^k(\mathbf{q})$ for some $k \in \mathbb{N}$.

A **recurrent class** $[\mathbf{q}]$ is the equivalence class of an element $\mathbf{q} \in \text{Rec}(\mathcal{M}_s)$.

The **level** of a recurrent class $[\mathbf{q}]$ is defined by

$$\text{lvl}([\mathbf{q}]) = \max_{\mathbf{q} \in [\mathbf{q}]} \text{lvl}(\mathbf{q}).$$

A weak version of Merino's Theorem

A weak version of Merino's Theorem

Theorem 3

If \mathcal{M} is a Markovian network and $s \in A$ is a letter of \mathcal{M} , then the polynomial $\mathcal{P}(\mathcal{M}, s; y)$ does not depend on the choice of s :

$$\mathcal{P}(\mathcal{M}, s; y) = \sum_{[\mathbf{q}] \in \text{Rec}(\mathcal{M}_s; \sim)} y^{|\nu([\mathbf{q}])|}.$$

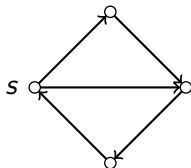
(Full) Merino's Theorem for Eulerian digraphs

In order to state Merino's Theorem for Eulerian digraphs, we need to introduce a generalization of one variable Tutte polynomial for directed graphs.

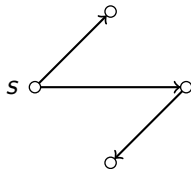
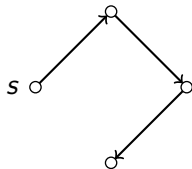
Rooted spanning tree

Let G be a strongly connected digraph, and let s be a vertex of $V(G)$.

An **s -rooted spanning tree** is a subgraph of G such that there is a unique directed path from s to v for each vertex $v \in V(G)$.



s -rooted spanning trees

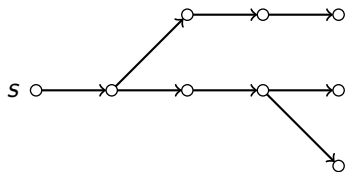


External activity

Fix a total order $<_e$ on $E(G)$.

Let T be an s -rooted spanning tree, and let $e \in E(G) \setminus E(T)$.

The graph $T \cup \{e\}$ has a unique circuit C .

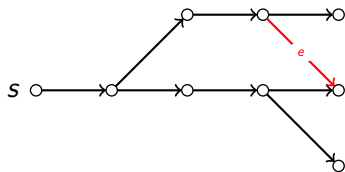


External activity

Fix a total order $<_e$ on $E(G)$.

Let T be an s -rooted spanning tree, and let $e \in E(G) \setminus E(T)$.

The graph $T \cup \{e\}$ has a unique circuit C .

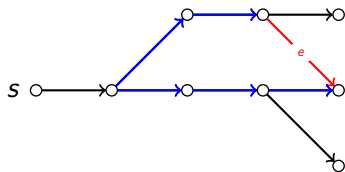


External activity

Fix a total order $<_e$ on $E(G)$.

Let T be an s -rooted spanning tree, and let $e \in E(G) \setminus E(T)$.

The graph $T \cup \{e\}$ has a unique circuit C .

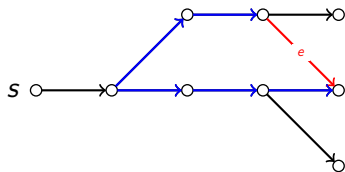


External activity

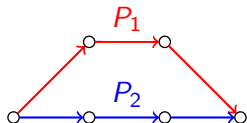
Fix a total order $<_e$ on $E(G)$.

Let T be an s -rooted spanning tree, and let $e \in E(G) \setminus E(T)$.

The graph $T \cup \{e\}$ has a unique circuit C .



The circuit C decomposes to two directed paths P_1 and P_2 . Let P_1 be the path that contains e .

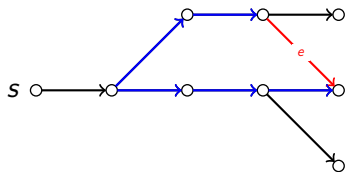


External activity

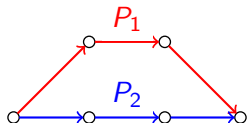
Fix a total order $<_e$ on $E(G)$.

Let T be an s -rooted spanning tree, and let $e \in E(G) \setminus E(T)$.

The graph $T \cup \{e\}$ has a unique circuit C .



The circuit C decomposes to two directed paths P_1 and P_2 . Let P_1 be the path that contains e .



The edge e is **externally active w.r.t. T** if the smallest edge of $E(C)$ is contained in $E(P_1)$.

Greedoid polynomial

The **external activity** of T , denoted by $\text{ext}(T)$, is the number of edges that are externally active w.r.t T .

The **greedoid polynomial** of G w.r.t root vertex s [BKL85] is the polynomial

$$\lambda(G, s; y) = \sum_{T \in \text{RST}(G, s)} y^{\text{ext}(T)}.$$

Merino's Theorem for Eulerian digraphs

Theorem 4 (C., 2015+)

If G is a connected Eulerian digraph and s is a vertex of G , then the following two polynomials are equal:

$$\mathcal{P}(\text{Sand}(G, s); y) = \lambda(G, s; y).$$

Thank you!



Anders Björner, Bernhard Korte, and László Lovász.

Homotopy properties of greedoids.

Adv. in Appl. Math., 6(4):447–494, 1985.



B. Bond and L. Levine.

Abelian networks I. Foundations and examples.

ArXiv e-prints, September 2013.



S. H. Chan.

Abelian sandpile model and Biggs-Merino polynomial for directed graphs.

ArXiv e-prints, December 2014.



Criel Merino López.

Chip firing and the Tutte polynomial.

Ann. Comb., 1(3):253–259, 1997.



K. Perrot and T. Van Pham.

Chip-firing game and partial Tutte polynomial for Eulerian digraphs.

ArXiv e-prints, June 2013.