

PROBLEM SET 3: SOLUTIONS.

Back problems (starred) (for rest, ask at recitation.)

2.4.6. Suppose that \vec{v} and \vec{w} are two vectors of an orthonormal basis of \mathbb{R}^3 . We want to show that the third vector is $\pm \vec{v} \times \vec{w}$.

We know that \vec{v} & \vec{w} span a 2-dimensional subspace of \mathbb{R}^3 . Thus, there is a 1-dimensional subspace of vectors perpendicular to \vec{v} and \vec{w} . Moreover, $\vec{v} \times \vec{w}$ is ^{non-zero and} perpendicular to \vec{v} & \vec{w} , so any vector in the space perpendicular to \vec{v} & \vec{w} must be a multiple of $\vec{v} \times \vec{w}$. In particular, the third element \vec{u} of the orthonormal basis must be a multiple of $\vec{v} \times \vec{w}$. We know that

$$\begin{aligned} |\vec{v} \times \vec{w}| &= \text{area of parallelogram spanned by } \vec{v} \text{ \& } \vec{w}. \\ &= \text{area of a unit square} \\ &= 1. \end{aligned}$$

Thus, we must have $\vec{u} = c \cdot (\vec{v} \times \vec{w})$ for some $c \in \mathbb{R}$ such that

$$\begin{aligned} |\vec{u}| &= |c \cdot \vec{v} \times \vec{w}| \\ &= |c| \cdot |\vec{v} \times \vec{w}| \\ &= |c|. \end{aligned}$$

But we need $|\vec{u}| = 1$, so we must have $c = \pm 1$.

Hence $\boxed{\vec{u} = \pm \vec{v} \times \vec{w}}$, as desired.

2.4.12. We compute, for $A_t = \begin{bmatrix} 2 & t \\ 0 & 2 \end{bmatrix}$

$$I = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

$$A_t = \begin{bmatrix} 2 & t \\ 0 & 2 \end{bmatrix}$$

$$A_t^2 = \begin{bmatrix} 4 & 4t \\ 0 & 4 \end{bmatrix}$$

$$A_t^3 = \begin{bmatrix} 8 & 12t \\ 0 & 8 \end{bmatrix}$$

(a) These four vectors are not linearly independent for any t .

For example,

$$-4 \cdot \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} + 4 \cdot \begin{bmatrix} 2 & t \\ 0 & 2 \end{bmatrix} - \begin{bmatrix} 4 & 4t \\ 0 & 4 \end{bmatrix} = \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix}$$

The subspace V_t spanned by these vectors is either one or two dimensional, depending on $t=0$ or $t \neq 0$.

If $t=0$, then $A_t^n = \begin{bmatrix} 2^n & 0 \\ 0 & 2^n \end{bmatrix}$, and the space V_t consists of all diagonal matrices.

If $t \neq 0$, then I and A_t are a basis for V_t , which is the space of all matrices of the form $\begin{bmatrix} a & b \\ 0 & a \end{bmatrix}$, with $a, b \in \mathbb{R}$.

2.5.8. Let $f: \mathbb{R}^m \rightarrow \mathbb{R}^k$ and $g: \mathbb{R}^n \rightarrow \mathbb{R}^m$ be linear transformations.

True or false: $f \circ g = 0$ implies $\text{img}(g) = \ker(f)$.

FALSE: Consider $f = \vec{0}$ and $g = \vec{0}$ the zero-functions. Then $f \circ g = \vec{0}$ is zero, but $\text{img}(g) = \{\vec{0}\}$ and $\ker(f) = \mathbb{R}^m$.

SALVAGE: What is true is that

$$f \circ g = \vec{0} \text{ implies } \text{img}(g) \subseteq \ker(f).$$

1. Prove one of the following statements.

(a) If (v_1, \dots, v_n) spans V , then so does the list

$$(v_1 - v_2, v_2 - v_3, \dots, v_{n-1} - v_n, v_n)$$

obtained by subtracting from each vector (except the last) the following vector.

PROOF. We need to show that for any $v \in V$, we can write v as a linear combination of $(v_1 - v_2, v_2 - v_3, \dots, v_{n-1} - v_n, v_n)$. We know that (v_1, \dots, v_n) spans V , so we may write

$$(1) \quad v = a_1 v_1 + \dots + a_n v_n.$$

We are looking for coefficients x_1, x_2, \dots, x_n such that

$$v = x_1(v_1 - v_2) + x_2(v_2 - v_3) + \dots + x_n v_n.$$

Let's set

$$\begin{aligned} x_1 &= a_1 \\ x_2 &= a_2 + a_1 \\ x_3 &= a_3 + a_2 + a_1 \\ &\vdots \\ x_n &= a_n + a_{n-1} + \dots + a_1 + a_1. \end{aligned}$$

Then the linear combination $x = x_1(v_1 - v_2) + x_2(v_2 - v_3) + \dots + x_n v_n$ becomes

$$\begin{aligned} x &= a_1(v_1 - v_2) + (a_2 + a_1)(v_2 - v_3) + \dots + (a_n + a_{n-1})v_n \\ &= a_1 v_1 - a_1 v_2 + (a_2 + a_1)v_2 - (a_2 + a_1)v_3 + \dots - (a_{n-1} + \dots + a_1)v_n + (a_n + \dots + a_1)v_n \\ &= a_1 v_1 + \dots + a_n v_n \\ &= v \quad \text{by equation (1).} \end{aligned}$$

Thus, this linear combination is v , and so this list spans all of V . \square

(b) If (v_1, \dots, v_n) is linearly independent in V , then so is the list

$$(v_1 - v_2, v_2 - v_3, \dots, v_{n-1} - v_n, v_n)$$

obtained by subtracting from each vector (except the last) the following vector.

PROOF. To prove that the list is independent, we must take a linear combination adding up to 0, and prove that all the coefficients are zero. So suppose

$$0 = b_1(v_1 - v_2) + b_2(v_2 - v_3) + \dots + b_n v_n.$$

Then we may rearrange the right hand side to get

$$\begin{aligned} 0 &= b_1 v_1 - b_1 v_2 + b_2 v_2 - b_2 v_3 + \dots + b_{n-1} v_{n-1} - b_{n-1} v_n + b_n v_n \\ &= b_1 v_1 + (b_2 - b_1)v_2 + \dots + (b_n - b_{n-1})v_n. \end{aligned}$$

But this is a linear combination of the list (v_1, \dots, v_n) , which we have assumed is linearly independent. Thus, the coefficients of this linear combination must all be zero. In other

words,

$$\begin{aligned} b_1 &= 0 \\ b_2 - b_1 &= 0 \\ b_3 - b_2 &= 0 \\ &\vdots \\ b_n - b_{n-1} &= 0. \end{aligned}$$

In other words, $b_1 = 0$, $b_2 = b_1$, $b_3 = b_2$, and so on until we conclude that $b_n = b_{n-1} = \dots = b_1 = 0$. Thus, we have shown that the list $(v_1 - v_2, v_2 - v_3, \dots, v_{n-1} - v_n, v_n)$ is linearly independent. \square

(c) Suppose that (v_1, \dots, v_n) is linearly independent in V , and $w \in V$. If the list $(v_1 + w, \dots, v_n + w)$ is linearly dependent, then $w \in \text{span}(v_1, \dots, v_n)$.

PROOF. By assumption, the list $(v_1 + w, \dots, v_n + w)$ is linearly dependent, which means that there exist scalars $a_1, \dots, a_n \in \mathbb{R}$ not all zero so that

$$\begin{aligned} 0 &= a_1(v_1 + w) + a_2(v_2 + w) + \dots + a_n(v_n + w) \\ &= a_1v_1 + a_2v_2 + \dots + a_nv_n + (a_1 + \dots + a_n)w. \end{aligned}$$

Because the list (v_1, \dots, v_n) is linearly independent, the coefficient on w must be non-zero. In other words, $a_1 + \dots + a_n \neq 0$. Thus, we can rearrange the equation to get

$$-(a_1 + \dots + a_n)w = a_1v_1 + \dots + a_nv_n,$$

and since $-(a_1 + \dots + a_n) \neq 0$, we can divide by $-(a_1 + \dots + a_n) \neq 0$ to get

$$w = \frac{a_1}{-(a_1 + \dots + a_n)}v_1 + \dots + \frac{a_n}{-(a_1 + \dots + a_n)}v_n.$$

In other words, w is a linear combination of (v_1, \dots, v_n) , so $w \in \text{span}(v_1, \dots, v_n)$, which is what we wanted to show. \square

2. Find a function $f : \mathbb{R}^2 \rightarrow \mathbb{R}$ that satisfies $f(a \cdot v) = a \cdot f(v)$ for every $a \in \mathbb{R}$ and $v \in \mathbb{R}^2$, but which is **not** linear.

EXAMPLE. Consider the function

$$f((x, y)) = \sqrt[3]{x^3 + y^3}$$

Then $f(a \cdot (x, y)) = \sqrt[3]{a^3x^3 + a^3y^3} = a \cdot \sqrt[3]{x^3 + y^3}$, so this satisfies homogeneity. However, $f((0, 2)) = \sqrt[3]{8}$, $f((2, 0)) = \sqrt[3]{8}$, but $f((0, 2) + (2, 0)) = f((2, 2)) = \sqrt[3]{16} \neq \sqrt[3]{8} + \sqrt[3]{8}$. Thus, this function does not satisfy the additivity property, and hence is not linear. \diamond

3. For V and W subspaces of \mathbb{R}^n , prove that

(a) $V \cap W$ is a subspace of \mathbb{R}^n ; and

(b) $V \cup W$ is a subspace of \mathbb{R}^n if and only if $V \subseteq W$ or $W \subseteq V$.

(a) To show that $V \cap W$ is a subspace, we need to show it's closed under scalar multiplication and vector addition.

First, suppose $v \in V \cap W$ and $a \in \mathbb{R}$. Then $v \in V$ and $v \in W$, by definition of intersection, and since those are subspaces, $a \cdot v \in V$ and $a \cdot v \in W$. But this means exactly that $a \cdot v \in V \cap W$.

Second, if $v, w \in V \cap W$, then $v, w \in V$ and $v, w \in W$. Since they are subspaces, $v+w \in V$ and $v+w \in W$, and so $v+w \in V \cap W$.

This proves $V \cap W$ is a subspace of \mathbb{R}^n .

(b) (\Leftarrow) If $V \subseteq W$, then $V \cup W = W$ is a subspace.
If $W \subseteq V$, then $V \cup W = V$ is a subspace.

(\Rightarrow) We prove this by proving the contrapositive. Suppose $V \not\subseteq W$ and $W \not\subseteq V$. Then we want to show $V \cup W$ is not a subspace of \mathbb{R}^n .

Choose $v \in V$ with $v \notin W$, (such elements exist)
and $w \in W$ with $w \notin V$. (by hypothesis)

Then $v+w$ cannot be in $V \cup W$! If it were, $v+w \in V$ or $v+w \in W$. In the first case $v+w, -v \in V$, so $(v+w)+(-v) = w \in V$, contradicting our choice of $w \notin V$. In the second, $v+w, -w \in W$, so $(v+w)+(-w) = v \in W$, contradicting our choice of $v \notin W$. Hence, $V \cup W$ is not closed under vector addition, so is not a subspace.

4. We say that two subspaces V and W are **orthogonal** to each other if $v \cdot w = 0$ for every $v \in V$ and $w \in W$. Given an $m \times n$ matrix A , let $R(A)$ denote the subspace of \mathbb{R}^n spanned by the rows of A (thought of, of course, as column vectors!). Prove that $R(A)$ is orthogonal to the kernel of A . Deduce that the image of A is orthogonal to the kernel of A^T .

$R(A) \perp \ker(A)$:

For any vector $v \in \ker(A)$, $A \cdot v = \vec{0}$. But the i^{th} coordinate of $A \cdot v$ is the dot product of the i^{th} row of A with v . Hence, all of these dot products are 0, so v is orthogonal to each row of A , and hence to $\text{span}(\text{rows}(A)) = R(A)$.

$\text{Im}(A) \perp \ker(A^T)$:

We deduce this by noting $\text{Im}(A) = \text{Col}(A) = R(A^T)$. Hence, $\text{Im}(A) \perp \ker(A^T)$, by the first part.

5. For subspaces V and W in \mathbb{R}^n , define their sum to be

$$V + W = \{v + w \mid v \in V, w \in W\}.$$

- (a) Prove that $V + W$ is a subspace of \mathbb{R}^n .
 (b) What is $V + V$?
 (c) Prove or give a counterexample to the following statement: If $V_1, V_2, W \subseteq \mathbb{R}^n$ are subspaces such that

$$V_1 + W = V_2 + W,$$

then $V_1 = V_2$.

- (d) What can you say about $\dim(V_1 + V_2)$?

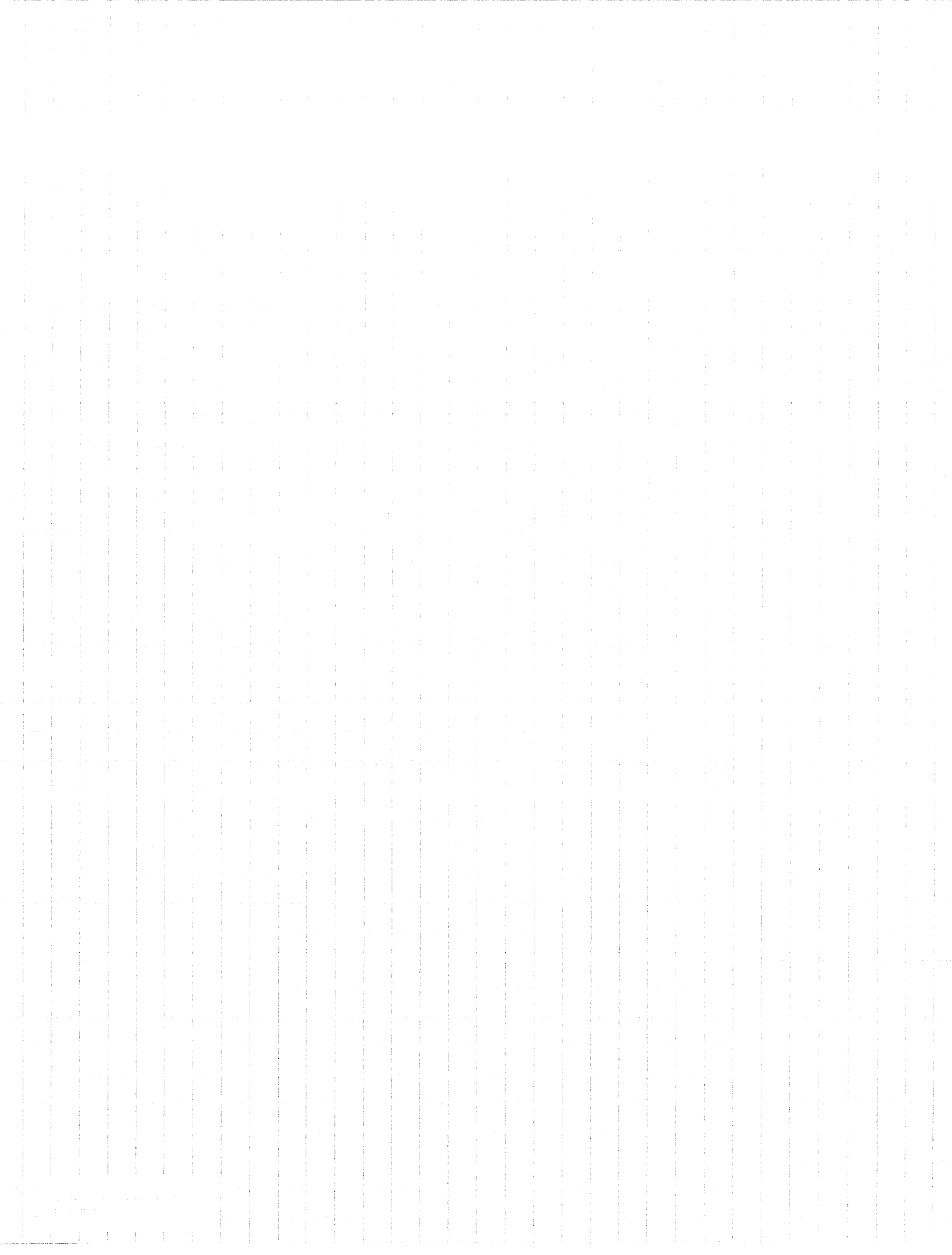
5(a). $V + W$ is closed under vector addition, since

$$(v_1 + w_1) + (v_2 + w_2) = \underbrace{(v_1 + v_2)}_{\text{in } V} + \underbrace{(w_1 + w_2)}_{\text{in } W} \\ \underbrace{\hspace{10em}}_{\text{in } V+W}.$$

and under scalar multiplication, since

$$a \cdot (v + w) = \underbrace{(a \cdot v)}_{\text{in } V} + \underbrace{(a \cdot w)}_{\text{in } W} \\ \underbrace{\hspace{10em}}_{\text{in } V+W}.$$

Thus, $V + W$ is a vector subspace.



5(b): $V + V = V$. (How do you prove it?!))

5(c): The statement is FALSE. For example,

if $V_1 = \left\{ \begin{pmatrix} x \\ y \end{pmatrix} \in \mathbb{R}^2 \right\} \subseteq \mathbb{R}^2$

$$V_2 = \left\{ \begin{pmatrix} x \\ 0 \end{pmatrix} \in \mathbb{R}^2 \right\} = x\text{-axis}$$

$$W = \left\{ \begin{pmatrix} 0 \\ y \end{pmatrix} \in \mathbb{R}^2 \right\} = y\text{-axis}$$

then $V_1 + W = \mathbb{R}^2 = V_2 + W$. But certainly $V_1 \neq V_2$!

5(d): $\dim(V_1 + V_2) \leq \dim(V_1) + \dim(V_2)$

because any pair of bases, one for V_1 and one for V_2 , give a spanning set for $V_1 + V_2$, but it may not be a linearly independent set.

6. Let $T: \mathbb{R}^n \rightarrow \mathbb{R}^n$ be a linear transformation.

(a) Suppose $\vec{v}_1, \vec{v}_2 \in \mathbb{R}^n$ are non-zero, and satisfy $T(\vec{v}_1) = \alpha_1 \vec{v}_1$ and $T(\vec{v}_2) = \alpha_2 \vec{v}_2$ for α_1 and α_2 distinct real numbers. Show that $\{\vec{v}_1, \vec{v}_2\}$ is an independent set.

(b) Suppose $\vec{v}_1, \dots, \vec{v}_k \in \mathbb{R}^n$ are non-zero, and satisfy $T(\vec{v}_i) = \alpha_i \vec{v}_i$ for $1 \leq i \leq k$, with the α_i distinct real numbers. Show that $\{\vec{v}_1, \dots, \vec{v}_k\}$ is an independent set.

(c) Exhibit a linear transformation $T: \mathbb{R}^2 \rightarrow \mathbb{R}^2$ and find a basis $\{\vec{v}_1, \vec{v}_2\}$ of \mathbb{R}^2 with $T(\vec{v}_1) = 3\vec{v}_1$ and $T(\vec{v}_2) = 5\vec{v}_2$.

(d) Exhibit a linear transformation $T: \mathbb{R}^2 \rightarrow \mathbb{R}^2$ such that for **no** pair of real numbers (α_1, α_2) is there a basis $\{\vec{v}_1, \vec{v}_2\}$ of \mathbb{R}^2 with

$$T(\vec{v}_1) = \alpha_1 \vec{v}_1 \text{ and } T(\vec{v}_2) = \alpha_2 \vec{v}_2.$$

6(a): Suppose (\vec{v}_1, \vec{v}_2) is not independent. Then one must be a multiple of the other, $\vec{v}_1 = c \cdot \vec{v}_2$ for some non-zero $c \in \mathbb{R}$. But applying T to this equation, we have

$$\vec{v}_1 = c \cdot \vec{v}_2$$
$$\Rightarrow T(\vec{v}_1) = T(c \cdot \vec{v}_2)$$

$$\Rightarrow \alpha_1 \vec{v}_1 = c \cdot T(\vec{v}_2) = c \cdot \alpha_2 \vec{v}_2.$$

Now, substituting $v_1 = c \cdot \vec{v}_2$ into the left-hand side, we get

$$\alpha_1 \cdot c \cdot \vec{v}_2 = c \cdot \alpha_2 \cdot \vec{v}_2,$$

whence $\alpha_2 = \alpha_1$, contradicting our hypothesis that $\alpha_1 \neq \alpha_2$. Thus, (\vec{v}_1, \vec{v}_2) must be independent.

5(b) We prove this by induction on k . Part 5(a) provides the base case. Assume $\vec{v}_1, \dots, \vec{v}_{k-1}$ are independent, and suppose $\vec{v}_1, \dots, \vec{v}_k$ is dependent. Then

$$\vec{v}_k = \sum_{i=1}^{k-1} c_i \vec{v}_i \quad (*)$$

is a linear combination of \vec{v}_k in terms of

the coefficients c_i are not all 0, since $\vec{v}_k \neq \vec{0}$. Applying T , we have

$$T(\vec{v}_k) = T\left(\sum_{i=1}^{k-1} c_i \vec{v}_i\right)$$

$$\Rightarrow \alpha_k \vec{v}_k = \sum_{i=1}^{k-1} c_i \alpha_i \vec{v}_i$$

$$\Rightarrow \alpha_k \left(\sum_{i=1}^{k-1} c_i \vec{v}_i\right) = \sum_{i=1}^{k-1} c_i \alpha_i \vec{v}_i \quad \text{by substituting } (*)$$

$$\Rightarrow \vec{0} = \sum_{i=1}^{k-1} c_i (\alpha_i - \alpha_k) \vec{v}_i.$$

Thus, we have a linear combination of $\vec{v}_1, \dots, \vec{v}_{k-1}$, with c_i not all 0 and $\alpha_i - \alpha_k \neq 0$ for all i , since the α_i 's are distinct. This contradicts the hypothesis that $\vec{v}_1, \dots, \vec{v}_{k-1}$ are independent.

Thus, our assumption that $\vec{v}_1, \dots, \vec{v}_k$ are dependent must be false, proving $\vec{v}_1, \dots, \vec{v}_k$ are in fact independent, as desired.

6(c). Consider $T\begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 3x \\ 5y \end{pmatrix}$.

Then for $\vec{v}_1 = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$ and $\vec{v}_2 = \begin{pmatrix} 0 \\ 1 \end{pmatrix}$, we have $T(\vec{v}_1) = 3\vec{v}_1$ and $T(\vec{v}_2) = 5\vec{v}_2$.

6(d). Consider the transformation

$$T\begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} x+y \\ y \end{pmatrix}.$$

To satisfy

$$T\begin{pmatrix} x \\ y \end{pmatrix} = \alpha \begin{pmatrix} x \\ y \end{pmatrix}$$

we must have

$$\begin{cases} x+y = \alpha x \\ y = \alpha y. \end{cases}$$

But $y = \alpha y$ means $\alpha = 1$. Plugging this into the first equation, we have $x+y = x$, ~~and~~ consequently $y = 0$.

But there is no basis of \mathbb{R}^2 which has the y -coordinate 0 in both basis vectors.

We know that if there were such (α_1, α_2) and (\vec{v}_1, \vec{v}_2) with $T(\vec{v}_i) = \alpha_i \vec{v}_i$, with $\alpha_1 \neq \alpha_2$ and $\vec{v}_1 \neq \vec{v}_2$ both nonzero, they WOULD BE a basis by 5(a) & $\dim(\mathbb{R}^2) = 2$. Hence,

no such pair can exist. \square