CERF THEORY FOR GRAPHS

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ABSTRACT

We develop a deformation theory for \( k \)-parameter families of pointed marked graphs with fixed fundamental group \( F_n \). Applications include a simple geometric proof of stability of the rational homology of \( \text{Aut}(F_n) \), computations of the rational homology in small dimensions, proofs that various natural complexes of free factorizations of \( F_n \) are highly connected, and an improvement on the stability range for the integral homology of \( \text{Aut}(F_n) \).

1. Introduction

It is standard practice to study groups by studying their actions on well-chosen spaces. In the case of the outer automorphism group \( \text{Out}(F_n) \) of the free group \( F_n \) on \( n \) generators, a good space on which this group acts was constructed in [3]. In the present paper we study an analogous space on which the automorphism group \( \text{Aut}(F_n) \) acts. This space, which we call \( \mathcal{A}_n \), is a sort of Teichmüller space of finite basepointed graphs with fundamental group \( F_n \).

As often happens, specifying basepoints has certain technical advantages. In particular, basepoints give rise to a nice filtration \( \mathcal{A}_{n,0} \subset \mathcal{A}_{n,1} \subset \ldots \) of \( \mathcal{A}_n \) by degree, where we define the degree of a finite basepointed graph to be the number of non-basepoint vertices, counted 'with multiplicity' (see Section 3). The main technical result of the paper, the Degree Theorem, implies that the pair \( (\mathcal{A}_n, \mathcal{A}_{n,k}) \) is \( k \)-connected, so that \( \mathcal{A}_{n,k} \) behaves something like the \( k \)-skeleton of \( \mathcal{A}_n \).

From the Degree Theorem we derive these applications:

(1) We show the natural stabilization map \( H_i(\text{Aut}(F_n); \mathbb{Z}) \rightarrow H_i(\text{Aut}(F_{n+1}); \mathbb{Z}) \) is an isomorphism for \( n \geq 2i + 3 \), a significant improvement on the quadratic dimension range obtained in [5]. For homology with \( \mathbb{Q} \) coefficients there is a particularly simple, geometric proof of homology stability which gives an isomorphism for \( n \geq 3(i+1)/2 \).

(2) We give an explicit description of a finite complex which can be used to compute the rational homology \( H_i(\text{Aut}(F_n); \mathbb{Q}) \). This complex is much smaller than complexes which were previously available, and independent of \( n \) for \( n \) large with respect to \( i \). As an example, we see immediately that \( H_i(\text{Aut}(F_n); \mathbb{Q}) = 0 \) for \( i = 1, 2 \) and all \( n \). In [6] we push this approach further to compute \( H_i(\text{Aut}(F_n); \mathbb{Q}) \) for \( i \leq 6 \) as well, with the following results. The groups \( H_3(\text{Aut}(F_n); \mathbb{Q}) \), \( H_5(\text{Aut}(F_n); \mathbb{Q}) \), and \( H_6(\text{Aut}(F_n); \mathbb{Q}) \) are zero for all \( n \). In dimension four, we have \( H_4(\text{Aut}(F_n); \mathbb{Q}) = 0 \) for \( n \neq 4 \), but \( H_4(\text{Aut}(F_4); \mathbb{Q}) = \mathbb{Q} \).

(3) Consider the free factorizations \( F_n = H_1 \ast \cdots \ast H_m \) where the \( H_i \) are nontrivial proper subgroups of \( F_n \). The collection of all such factorizations (without regard to the order of the factors \( H_i \)) is a partially ordered set with respect to refinement, that is, the further decomposition of the \( H_i \) into free products. The simplicial complex associated to this partially ordered set is \((n-2)\)-dimensional, and we show it is homotopy equivalent to a wedge of \((n-2)\)-dimensional spheres.

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The proof of the Degree Theorem is of some interest in its own right, involving a sort of parameterized Morse theory for graphs which has not yet appeared in this subject. This is what title of the paper refers to, since Cerf theory in differential topology is the study of families of real-valued $C^\infty$ functions on a smooth manifold. Each point in $\mathcal{A}_n$ is represented by a basepointed graph whose edges have assigned lengths, giving a path-metric on the graph. We can then regard the distance to the basepoint as defining a canonical ‘Morse function’ on the graph. To prove the Degree Theorem, one needs to show that a $k$-parameter family of such metric graphs can be deformed so as to lower their degrees to at most $k$ for all parameter values. This is done by a process of simplifying the associated Morse functions so as to push as many of the vertices of the graphs down to the basepoint as possible, using general position arguments and a fairly delicate induction.

2. The space $\mathcal{A}_n$

2.1. Points of $\mathcal{A}_n$

By a graph $\Gamma$ we mean a one-dimensional CW-complex, with vertices the 0-cells and edges the 1-cells. The valence of a vertex $v$ is the number $|v|$ such that a sufficiently small connected neighborhood of $v$ is a cone on $|v|$ points, with $v$ as its cone point. An edge is a separating edge if removing a point in its interior disconnects the graph.

A point of $\mathcal{A}_n$ is an equivalence class of triples $(\Gamma, v_0, \phi)$ where:

1. $\Gamma$ is a finite connected graph with no separating edges.
2. $v_0$ is a basepoint vertex of $\Gamma$. All other vertices have valence at least 3.
3. $\phi : F_1 \longrightarrow \pi_1(\Gamma, v_0)$ is an isomorphism.
4. The edges of $\Gamma$ are assigned positive real lengths in such a way that the sum of the lengths of all the edges is 1. This determines a natural metric on $\Gamma$.
5. $(\Gamma, v_0, \phi)$ is equivalent to $(\Gamma', v_0', \phi')$ if there is a basepoint-preserving isometry $\rho : \Gamma \longrightarrow \Gamma'$ inducing $\rho_*$ on $\pi_1$ with $\phi' = \rho_* \phi$.

2.2. Topology on $\mathcal{A}_n$

To define the topology on $\mathcal{A}_n$, consider first the possibility of varying the lengths of the edges of $\Gamma$ for $(\Gamma, v_0, \phi) \in \mathcal{A}_n$, keeping the length of each edge positive and the sum of all the lengths equal to 1. This defines a collection of points $(\Gamma_s, v_0, \phi) \in \mathcal{A}_n$ parameterized by points $s$ in the interior of a simplex $\Delta^k$, whose barycentric coordinates are the lengths of the edges. These points $(\Gamma_s, v_0, \phi) \in \mathcal{A}_n$ are all distinct since any nontrivial isometry $\Gamma \longrightarrow \Gamma'$ acts nontrivially on $H_1(\Gamma)$, and hence changes $\phi$.

Each point $(\Gamma, v_0, \phi) \in \mathcal{A}_n$ lies in such an open simplex $\sigma = \sigma(\Gamma, v_0, \phi) \subset \mathcal{A}_n$. Some (but not all) open faces of $\sigma$ also belong to $\mathcal{A}_n$, as follows. Passing to a face of $\sigma$ corresponds to shrinking the lengths of certain edges of $\Gamma$ to zero (while increasing the lengths of the other edges), thereby producing a quotient graph $\Gamma'$. If the quotient map $q : \Gamma \longrightarrow \Gamma'$ induces an isomorphism on $\pi_1$, then $(\Gamma', q(v_0), q_* \phi)$ is a point in $\mathcal{A}_n$. Varying the lengths of the edges of $\Gamma'$, which we identify with the edges of $\Gamma$ which are not shrunk to zero length, we trace out an open simplex $\tau$ of $\mathcal{A}_n$ forming a face of $\sigma$. The topology of $\mathcal{A}_n$ is defined by these face relations among all such pairs of open simplices $\sigma, \tau \in \mathcal{A}_n$. More precisely, define a formal closure $\overline{\sigma}$ of each open simplex $\sigma$ of $\mathcal{A}_n$ by adjoining to an abstract copy of $\sigma$ those of its open faces which
give rise to open simplices of \( \mathbb{A}_n \). Then we have a natural map \( \bar{\sigma} \longrightarrow \mathbb{A}_n \), and we define a topology on \( \mathbb{A}_n \) by saying that a set is open if and only if its inverse images under all such maps \( \bar{\sigma} \longrightarrow \mathbb{A}_n \) are open. It follows from Proposition 2.1 below that the projections \( \bar{\sigma} \longrightarrow \mathbb{A}_n \) are in fact embeddings, so the formal closure \( \bar{\sigma} \) is the same as the actual closure in \( \mathbb{A}_n \).

2.3. Sphere complexes and \( \mathbb{A}_n \)

There is another way of looking at \( \mathbb{A}_n \) as a subspace of the sphere complex \( S(M) \) of [5], where \( M \) is the compact 3-manifold obtained from the connected sum of \( n \) copies of \( S^1 \times S^2 \) by deleting an open ball. Vertices of \( S(M) \) are isotopy classes of embedded 2-spheres in \( M \), excluding those which bound a ball or are isotopic to the boundary sphere of \( M \). A collection of \( k + 1 \) vertices of \( S(M) \) spans a \( k \)-simplex of \( S(M) \) if the corresponding \( k + 1 \) isotopy classes of 2-spheres can be represented by a system of \( k + 1 \) disjoint 2-spheres. Let \( \mathbb{A}_n^* \) be the subcomplex of \( S(M) \) corresponding to systems of nonseparating spheres, that is, spheres \( S \subset M \) such that \( M - S \) is connected. Let \( \partial \mathbb{A}_n^* \) be the subcomplex of \( \mathbb{A}_n^* \) consisting of sphere systems \( S_0 \cup \ldots \cup S_k \) such that at least one component of \( M - (S_0 \cup \ldots \cup S_k) \) is not simply-connected. There is a natural map from \( \mathbb{A}_n^* - \partial \mathbb{A}_n^* \) to \( \mathbb{A}_n \), obtained in the following way. Each sphere system \( S_0 \cup \ldots \cup S_k \) has a dual graph \( \Gamma \), whose vertices are the components of \( M - (S_0 \cup \ldots \cup S_k) \) and whose edges are the spheres \( S_i \). There is a natural quotient map \( M \longrightarrow \Gamma \), inducing a homomorphism \( \phi : \pi_1(M, v_0) \cong F_n \longrightarrow \pi_1(\Gamma, v_0) \) where \( v_0 \) is a basepoint in the boundary of \( M \) and \( v_0 \) is its image in \( \Gamma \). The barycentric coordinates of a point in the open simplex of \( S(M) \) spanned by \( S_0 \cup \ldots \cup S_k \) determine lengths on the edges of \( \Gamma \). Thus to each point in \( S(M) \) we have an associated triple \((\Gamma, v_0, \phi)\) consisting of a metric graph \( \Gamma \), a basepoint vertex \( v_0 \), and a homomorphism \( \phi : F_n \longrightarrow \pi_1(\Gamma, v_0) \). The points in the subspace \( \mathbb{A}_n^* - \partial \mathbb{A}_n^* \) of \( S(M) \) are precisely those for which \((\Gamma, v_0, \phi)\) is a point in \( \mathbb{A}_n \). Namely, restricting to nonseparating spheres corresponds to \( \Gamma \) having no separating edges, and \( \phi \) being an isomorphism corresponds to the components of \( M - (S_0 \cup \ldots \cup S_k) \) being simply-connected.

**Proposition 2.1.** The map \( \mathbb{A}_n^* - \partial \mathbb{A}_n^* \longrightarrow \mathbb{A}_n \) constructed above is a homeomorphism. Hence \( \mathbb{A}_n \) is contractible.

This is proved in the Appendix of [5] for the analogous unbasepointed situation. Adding basepoints is completely straightforward and we shall leave the proof as an exercise, with the following remarks. Separating spheres were allowed in [5]. This makes no difference for proving the first statement of the proposition. For the second statement one can argue as follows. The contraction of the sphere complex \( S(M) \) constructed in the proof of Theorem 2.1 of [5] restricts to a contraction of the subspace consisting of sphere systems having simply-connected complementary regions. This subspace retracts in turn onto its subspace consisting of sphere systems without separating spheres, by simply deleting any separating spheres. Since a retract of a contractible space is contractible, this finishes the argument.

**Remark 2.2.** The space \( \mathbb{A}_n^* \) can also be identified with the space of minimal actions of the free group \( F_n \) on rooted simplicial \( \mathbb{R} \)-trees with trivial edge stabilizers, where two actions are considered to be the same if they differ only by a constant scaling of the tree. The subspace \( \mathbb{A}_n \) corresponds to actions whose vertex stabilizers
are trivial as well, that is, free actions. Each such action determines a Lyndon length function \( L: F_n \rightarrow \mathbb{R} \), where the length of an element is the distance it moves the root in the tree. The map sending an action to its Lyndon length function gives an embedding from \( A_n^* \) to an infinite-dimensional real projective space. The topology on \( A_n \) is equivalent to the subspace topology, but the subspace topology on \( A_n^* \) is not the same as the simplicial topology.

2.4. Spine of \( A_n \)

Our description of \( A_n \) as a union of open simplices does not give it the structure of a simplicial complex since not all faces of its open simplices are in \( A_n \). However, the geometric realization of the partially ordered set of open simplices is a simplicial complex, denoted \( SA_n \). The vertices of \( SA_n \) are the open simplices of \( A_n \), and a \( k \)-simplex is a chain of \( k + 1 \) open simplices, each of which is a face of the next. There is a natural embedding of \( SA_n \) in \( A_n \) which sends each vertex to the barycenter of the corresponding open simplex, and each \( k \)-simplex to the convex hull of the corresponding barycenters. There is a natural deformation retraction of \( A_n \) onto \( SA_n \), by pushing within each open simplex of \( A_n \) away from its missing faces, that is, the faces of \( \partial A_n^* \). For this reason, \( SA_n \) is called the spine of \( A_n \).

The dimension of \( A_n \) is \( 3n - 3 \) since the maximum number of edges which a graph satisfying (1)–(3) can have is \( 3n - 2 \). The dimension of the spine is \( 2n - 2 \).

3. The Degree Theorem

3.1. Degree of a graph

**Definition 3.1.** The degree of a finite connected graph \( \Gamma \) with basepoint \( v_0 \) is

\[
\deg(\Gamma) = \sum_{v \neq v_0} |v| - 2.
\]

For each vertex \( v \) of \( \Gamma \) we can think of the number \( |v| - 2 \) as the ‘multiplicity’ of \( v \). If two vertices \( v_1 \) and \( v_2 \) are joined by an edge, then collapsing this edge produces a single vertex \( v \) in the quotient graph with \( |v| - 2 = |v_1| - 2 + |v_2| - 2 \), so the multiplicity of \( v \) is the sum of the multiplicities of \( v_1 \) and \( v_2 \). By collapsing the edges in a maximal tree, one by one, we see that the sum \( \sum_{v}(|v| - 2) \) over all vertices of \( \Gamma \) is equal to \( 2n - 2 \) if \( \pi_1(\Gamma) \cong F_n \), since this is its value when \( \Gamma \) has a single vertex. It follows that the degree of \( \Gamma \) can also be computed as \( 2n - |v_0| \), and is at most \( 2n - 2 \).

**Example 3.2.** The only graphs of degree 0 are roses (graphs with exactly one vertex, the basepoint). Modulo edges with both endpoints attached to the basepoint, the only graph of degree 1 is the theta graph (the graph with two vertices and three edges, each with distinct endpoints), and the only graphs of degree 2 are the five indicated in Figure 1.

![Fig. 1](image-url)
3.2. Statement of the Degree Theorem

Let $\mathbb{A}_{n,k} \subset \mathbb{A}_n$ be the subspace consisting of triples $(\Gamma, v_0, \phi)$ for which $\Gamma$ has degree at most $k$. Since the degree of $\Gamma$ depends only on the topological type of $(\Gamma, v_0)$, $\mathbb{A}_{n,k}$ is a union of open simplices of $\mathbb{A}_n$. Also, $\mathbb{A}_{n,k}$ is a closed subspace of $\mathbb{A}_n$ since passing to a face of the open simplex of $\mathbb{A}_n$ containing $(\Gamma, v_0, \phi)$ collapses certain edges of $\Gamma$, which can only change the valence of the basepoint by increasing it, thus lowering the degree of $\Gamma$. Since graphs in $\mathbb{A}_n$ have degree at most $2n - 2$, we have $\mathbb{A}_{n,k} = \mathbb{A}_n$ for $k \geq 2n - 2$.

Our main technical result is the following.

**Theorem 3.3.** A piecewise linear map $f_0: D^k \longrightarrow \mathbb{A}_n$ is homotopic to a map $f_1: D^k \longrightarrow \mathbb{A}_{n,k}$ by a homotopy $f_t$ during which degree decreases monotonically, that is, if $t_1 < t_2$ then $\deg(f_{t_1}(s)) \geq \deg(f_{t_2}(s))$ for all $s \in D^k$.

**Corollary 3.4.** The pair $(\mathbb{A}_n, \mathbb{A}_{n,k})$ is $k$-connected. Equivalently, since $\mathbb{A}_n$ is contractible, $\mathbb{A}_{n,k}$ is $(k-1)$-connected.

The proof of the theorem will be given in the next section. In the rest of this section we make various definitions we will need and explain something of the idea of the proof.

3.3. Height and critical points

Given a point $(\Gamma, v_0, \phi) \in \mathbb{A}_n$, let $h: \Gamma \longrightarrow \mathbb{R}$ be the function measuring distance to $v_0$, using the given metric on $\Gamma$. We think of $h$ as a height function on $\Gamma$, as in Morse theory. A point $x \in \Gamma$ is called a critical point if near $x$ there are at least two different paths leading down from $x$, that is, paths along which $h$ decreases. The critical points of $\Gamma$ are isolated, clearly. As motivation for this terminology, note that the homotopy type of the subspace $h^{-1}([0, r])$ of $\Gamma$ changes with varying $r$ only when $r$ passes through a critical value of $h$, just as for Morse functions on manifolds.

An example is shown in Figure 2(a). In this figure we think of $h$ literally as the height function, so the lengths of edges are determined by their vertical heights rather
than their lengths as arcs in the plane. The height function has seven critical points, indicated by the dots. Four of them are vertices and the other three occur at interior points of edges.

The function $h$ measuring distance to the basepoint has one special property not satisfied by an arbitrary piecewise linear function $\Gamma \rightarrow \mathbb{R}$, namely, it has only one local minimum, the basepoint. Conversely, it is not hard to see that any piecewise linear function $\Gamma \rightarrow \mathbb{R}$ with a unique local minimum is the distance function for some metric on $\Gamma$, with the minimum as the basepoint. Thus by restricting our ‘Morse functions’ to distance functions we are not straying too far from a general ‘Morse theory’ of graphs, and we avoid quite a bit of unwanted noise which unrestricted local minima would generate.

3.4. Cones and canonical splitting

To give an idea of how the proof of the Degree Theorem proceeds, let us look at the unparameterized case, when $k = 0$. Here one is given a single point $(\Gamma, v_0, \phi) \in \mathcal{A}_n$ which one wants to deform so as to reduce its degree monotonically to 0, eliminating all vertices except $v_0$. The obvious way to do this would be simply to shrink the lengths of all edges in a maximal tree to zero, but this approach does not seem to work very well in the parameterized case.

For a critical point $x \in \Gamma$ which is a vertex, the cone $C_x$ is the union of $x$ with all open edges of $\Gamma$ incident to $x$ and lying below $x$. In case $x$ is a critical point which is not a vertex, define $C_x$ to be the open edge containing $x$. In either case $C_x$ consists of two or more branches leading down from $x$, which are arcs along which $h$ decreases. If $x$ is not a vertex, then there are just two branches. If $x$ is a vertex there can be two or more branches, and there may also be edges coming into $x$ from above which are not part of $C_x$. The $\varepsilon$-cone $C_x^\varepsilon$ consists of the points of $C_x$ within distance $\varepsilon$ of $x$.

If one begins travelling down a branch of a cone, it is possible to continue moving monotonically downward toward the basepoint without ambiguity until one first meets another critical point. If no critical points are encountered, one can travel all the way to the basepoint. Each such extended branch, connecting $x$ with a lower critical point or the basepoint, is embedded in $\Gamma$, but different extended branches can merge at noncritical vertices. There is a canonical way of deforming $\Gamma$ to eliminate these junctions, by splitting the extended branches apart, splitting downward to the next critical point, or all the way to the basepoint in favorable cases. One can start at the top of $\Gamma$ and split downward at each noncritical vertex as one comes to it, like pulling a comb through matted hair. We refer to this process as canonically splitting $\Gamma$. For example, canonically splitting the graph in Figure 2(a) produces the graph in Figure 2(b).

Canonical splitting does not increase degree, and decreases it if some noncritical vertices split all the way down to the basepoint. Thus in the example of Figure 2 the degree drops from 16 to 11.

A canonically split $\Gamma$ is the disjoint union of the basepoint and the cones $C_x$. We can regard $\Gamma$ as being built in stages, starting with the basepoint and attaching the cones in sequence, according to the heights of the critical points.

3.5. Sliding in the $\varepsilon$-cones

Having canonically split $\Gamma$, we may perturb the attaching points of the branches of the cones $C_x$ by sliding them downwards, so that they remain in the $\varepsilon$-cones which
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contain them, but no longer lie at critical points. This perturbation can be viewed as putting the attaching points in 'general position' with respect to the critical points. Such a perturbation of attaching points has no effect on degree, but canonical splitting of the perturbed \( \Gamma \) will reduce its degree further. In fact, this canonical splitting will deform \( \Gamma \) so that all the cones \( C_x \) attach directly to the basepoint, as in Figure 2(c).

The preceding deformations of \( \Gamma \) do not change its \( \epsilon \)-cones \( C_x^\epsilon \). If the \( \epsilon \)-cones of the original \( \Gamma \) each had just two branches, we would now have succeeded in deforming \( \Gamma \) to a graph of degree 0. So it would have sufficed to have done a preliminary perturbation of \( \Gamma \) to make all its critical points interior points of edges. Such a preliminary perturbation is easy to do since if a vertex \( x \) is a critical point, then by small changes in the lengths of the edges of \( C_x \) we can insure that \( x \) is no longer a critical point.

4. Proof of the Degree Theorem

The proof proceeds in two main stages. In the first, a \( k \)-parameter family of graphs is perturbed to make the critical points as simple as possible for a generic \( k \)-parameter family. This involves only perturbations of the lengths of the edges of the graphs, and does not affect their topological types, so there is no reduction of degree. In the second stage, deformations are made which do not change the local structure of the critical points, that is, the \( \epsilon \)-cones, but the degree is monotonically reduced to be at most \( k \) throughout the family.

4.1. Codimension

Definition 4.1. The codimension of a critical point \( x \) is defined to be 0 if \( x \) is an interior point of an edge, and \( b - 1 \) if \( x \) is a vertex whose \( \epsilon \)-cone \( C_x^\epsilon \) has \( b \) branches. The codimension of a graph \( \Gamma \) is the sum of the codimensions of its critical points.

If a critical point \( x \) is an interior point of an edge, small perturbations of \( \Gamma \) clearly produce a critical point near \( x \) in the same edge, which is why we say such critical points have codimension 0. On the other hand, if the critical point \( x \) is a vertex, the \( b \) branches of \( C_x^\epsilon \) are the initial segments of \( b \) edgpaths from \( x \) to \( v_0 \) of equal length, and the condition that these paths have equal length is given by \( b - 1 \) linear equations among the lengths of the edges of \( \Gamma \). These equations are independent since the corresponding edgpaths all begin with different edges. Hence the solution set of these equations is a codimension \( b - 1 \) linear subspace of the open simplex \( \sigma \) containing \( (\Gamma, v_0, \varnothing) \) in \( \mathbb{A}_n \).

Example 4.2. Let \( \Gamma \) be the graph with two vertices \( v_0 \) and \( v_1 \) joined by \( n + 1 \geq 3 \) edges of length \( 1/(n+1) \). Then the nonbasepoint vertex \( v_1 \) is a critical point of codimension \( n \). The open simplex \( \sigma \) containing \( \Gamma \) is the interior of an \( n \)-simplex with barycentric coordinates the lengths of the edges of \( \Gamma \), and \( \Gamma \) itself lies at the barycenter of this simplex. Any small perturbation of \( \Gamma \) produces critical points of smaller codimension. The case \( n = 2 \) is illustrated in Figure 3. Here \( v_1 \) becomes a critical point of codimension 1 along the three line segments from the barycenter to the vertices of \( \sigma \), and elsewhere in \( \sigma \) there are two critical points of codimension 0.
4.2. Critical planes and a stratification of $\mathbb{A}_n$

Consider a point $(\Gamma, v_0, \phi) \in \mathbb{A}_n$ lying in an open simplex $\sigma$ obtained by varying the lengths of the edges of $\Gamma$. Using these lengths as coordinates, we identify $\sigma$ with the open simplex in $\mathbb{R}^m$ consisting of points with positive coordinates whose sum is 1, and $(\Gamma, v_0, \phi)$ with a point $s$ in this simplex.

The minimum distance from a vertex $x$ of $\Gamma$ to $v_0$ is always realized by a path which passes through each edge of $\Gamma$ at most once. We call such oriented edgepaths in $\Gamma$ preferred. The length $l_\gamma$ of a preferred path $\gamma$ is a linear function on $\mathbb{R}^m$, the sum of certain of the coordinates of $\mathbb{R}^m$. By a critical hyperplane we mean the codimension-one linear subspace of $\mathbb{R}^m$ defined by equating two length functions $l_\gamma$ corresponding to distinct preferred paths $\gamma$ from the same vertex $x$ to $v_0$. A critical plane is an intersection of critical hyperplanes.

The critical hyperplanes determine a stratification of $\mathbb{R}^m$, hence also a stratification of $\sigma$. The strata are open convex polyhedra of various dimensions, each defined by a set of equalities and strict inequalities among pairs of length functions $l_\gamma$ associated to preferred paths $\gamma$.

As we pass from $\sigma$ to a codimension-one open face $\tau$ in $\mathbb{A}_n$, an edge of $\Gamma$ shrinks to zero length, forming a quotient graph $\Gamma'$. Preferred paths $\gamma$ in $\Gamma$ map to preferred paths $\gamma'$ in $\Gamma'$ under the quotient map $\Gamma \to \Gamma'$, so each critical hyperplane in $\sigma$ meets $\tau$ in a critical hyperplane in $\tau$. Thus we have a stratification of all of $\mathbb{A}_n$.

As $\Gamma$ varies over $\sigma$, its topological type does not change. The following lemma says that if we restrict to individual strata within $\sigma$, the critical points of $\Gamma$ do not essentially change either.

**Lemma 4.3.** If we let a graph $(\Gamma, v_0, \phi) \in \sigma$ vary over a stratum in $\sigma$, then:

(i) Each vertex of $\Gamma$ which is a critical point remains a critical point throughout the stratum, and the homeomorphism type of its $e$-cone does not change.

(ii) A critical point which is not a vertex varies continuously within the edge containing it.
(iii) The codimension of each critical point is constant over the stratum, hence the codimension of $\Gamma$ remains constant. If the codimension of $\Gamma$ is $i$, then the stratum is contained in a critical plane of codimension $i$.

Proof. For a given $(\Gamma, v_0, \phi)$, the branches of an $\varepsilon$-cone $C_x^\varepsilon$ at a critical vertex $x$ are contained in initial edges of a certain collection of preferred paths $\gamma$ from $x$ to $v_0$, all having the same length which is shorter than the length of any other preferred path from $x$. As we move through the stratum containing $(\Gamma, v_0, \phi)$ these same $\gamma$ remain the shortest paths from $x$ to $v_0$, and all other preferred paths from $x$ remain longer than these, so $C_x^\varepsilon$ does not change over the stratum.

For a critical point $x$ interior to an edge, there are two shortest paths from $x$ to the basepoint passing through the two adjacent vertices $v_1$ and $v_2$. These two paths contain subpaths $\gamma_1$ and $\gamma_2$ which are shortest paths from $v_1$ and $v_2$ to the basepoint. As we vary over the stratum, $\gamma_1$ and $\gamma_2$ remain shortest paths. The critical point $x$ can only vary within the open edge containing it while the parameter $s$ remains within the stratum, since if $x$ moved to one of its endpoints $v_i$, this would create a new shortest path from $v_i$ to the basepoint.

The last statement of the lemma follows from the observation that the length functions for a collection of preferred paths with distinct initial edges are independent.

4.3. Stage 1: Simplifying the critical points

Let us relabel the given map $f_0$ as $f: D^k \to \mathbb{A}_n$, and let $f(s) = (\Gamma_s, v_s, \phi_s)$. We will deform $f$ by deforming the family $\Gamma_s$ in such a way that it will be obvious how to carry along the basepoint $v_s$ and the isomorphism $\phi_s: F_n \to \pi_1(\Gamma_s, v_s)$. Therefore no confusion should ensue if we are somewhat free with our notation, sometimes writing $\Gamma_s$ when we really mean $(\Gamma_s, v_s)$ or $(\Gamma_s, v_s, \phi_s)$.

Let $\Sigma_i \subset \mathbb{A}_n$ be the subspace consisting of triples $(\Gamma, v_0, \phi)$ of codimension at least $i$, so we have a decreasing filtration $\mathbb{A}_n = \Sigma_0 \supset \Sigma_1 \supset \Sigma_2 \supset \ldots$. By Lemma 4.3, $\Sigma_i$ is a union of strata of $\mathbb{A}_n$ having codimension at least $i$ in each open simplex of $\mathbb{A}_n$. Moreover, $\Sigma_i$ is a closed subset of $\mathbb{A}_n$ since the codimension of a critical point cannot decrease as we pass to the boundary of a stratum.

Lemma 4.4. The map $f: D^k \to \mathbb{A}_n$ can be homotoped, preserving degree, to a piecewise linear map such that, for all $i$, $f^{-1}(\Sigma_i)$ has codimension at least $i$ in $D^k$.

Proof. Since the given $f$ is piecewise linear, there is a triangulation of $D^k$ for which $f$ maps each simplex linearly to the closure of an open simplex of $\mathbb{A}_n$. If we barycentrically subdivide this triangulation, we will have the additional property that the image of each simplex meets at most one codimension-one face of each open simplex $\sigma$ of $\mathbb{A}_n$. We shall homotope $f$ by perturbing the images of the vertices within the open simplices of $\mathbb{A}_n$ which contain them. Thus the homotopy will consist only of perturbing the lengths of edges of the graphs $\Gamma_s$, so degree will be preserved.

By a preliminary perturbation of $f$ on vertices we may assume each image $f(\Delta'_l)$ of a simplex $\Delta'_l$ of $D^k$ has maximal dimension, either $l$ or the dimension of the open simplex of $\mathbb{A}_n$ containing it. Subsequent small perturbations of $f$ on vertices will not affect this property.

Consider an open simplex $\sigma$ of $\mathbb{A}_n$. As before, we regard $\sigma$ as lying in the Euclidean space $\mathbb{R}^m$ whose coordinates are the lengths of edges of graphs $\Gamma$ for $(\Gamma, v_0, \phi) \in \sigma$. For a simplex $\Delta'_l$ of $D^k$ mapped by $f$ to the closure of $\sigma$, our aim is to put $f(\Delta'_l)$ in general
position with respect to certain critical planes \( H \) in \( \mathbb{R}^m \), in the sense that if \( L \) is the linear subspace of \( \mathbb{R}^m \) spanned by \( f(\Delta^i) \), then either \( L \cap H = 0 \) or \( L \) and \( H \) span \( \mathbb{R}^m \). Note that this is an open condition, preserved by small perturbations of \( f \) on vertices of \( \Delta^i \).

We call a collection \( \mathcal{C} = \{ \gamma_j \} \) of preferred paths in \( \Gamma \) compatible if no edge of \( \Gamma \) is traversed in different directions by different \( \gamma_j \). The critical planes \( H \) we are interested in are those defined by equating lengths of some set of pairs of paths \( \gamma_j \) in a compatible collection \( \mathcal{C} \). Note that \( \Sigma_r \cap \sigma \) is contained in a union of such critical planes \( H \) of codimension \( i \). If we arrange that \( f(\Delta^i) \) is in general position with respect to such planes \( H \), for all simplices \( \Delta^i \) in \( D^k \), then the lemma will follow since the codimension of \( f(\Delta^i) \cap H \) in \( f(\Delta^i) \) is at least as great as the codimension of \( H \) in \( \mathbb{R}^m \), and codimension is preserved under pullbacks via linear maps.

If \( f(\Delta^i) \) is contained entirely in \( \sigma \), not just in the closure of \( \sigma \), then the desired general position for \( f(\Delta^i) \) is easy to achieve just by small perturbations of \( f \) on the vertices of \( \Delta^i \). The difficulty in the general case is that certain vertices of \( \Delta^i \) may map to faces of \( \sigma \), and \( f \) on these vertices can only be perturbed while staying within the respective faces. We need to show that general position can still be achieved with these constraints.

Let \( \tau \) be an open simplex of \( A_n \) which is a face of \( \sigma \). The simplex \( \tau \) spans a linear subspace \( \mathbb{R}^p \) of \( \mathbb{R}^m \) obtained by letting the lengths of some edges of \( \Gamma \) go to zero, producing a quotient graph \( \Gamma' \). We shall show first that the codimension of \( H \cap \mathbb{R}^p \) in \( \mathbb{R}^p \) equals the codimension of \( H \) in \( \mathbb{R}^m \).

The critical plane \( H \) is the intersection of hyperplanes of the form \( l_{\gamma_i} = l_{\gamma_j} \) for a compatible collection of paths \( \gamma_i \). Since the \( \gamma_i \) are compatible, we can orient \( \Gamma \) by assigning each edge which is in some \( \gamma_i \) the orientation coming from \( \gamma_i \) and orienting edges not in any \( \gamma_i \) arbitrarily. To each hyperplane \( l_{\gamma_i} = l_{\gamma_j} \) we then associate the cellular 1-cycle \( \gamma_i - \gamma_j \). Such 1-cycles \( \gamma_i - \gamma_j \) generate a subspace of \( H_1(\Gamma; \mathbb{R}) \) whose dimension is the codimension of \( H \) since there are no cellular 2-chains. The statement that the codimension of \( H \cap \mathbb{R}^p \) in \( \mathbb{R}^p \) equals the codimension of \( H \) in \( \mathbb{R}^m \) now follows: the quotient map \( q: \Gamma \rightarrow \Gamma' \) takes the given collection of compatible preferred paths \( \gamma_i \) to another such collection \( \gamma_i' \) in \( \Gamma' \); a hyperplane \( l_{\gamma_i} = l_{\gamma_j} \) meets \( \mathbb{R}^p \) in the hyperplane \( l_{\gamma_i'} = l_{\gamma_j'} \), so the critical hyperplanes in \( \mathbb{R}^m \) whose intersection is \( H \) meet \( \mathbb{R}^p \) in critical hyperplanes whose intersection is \( H \cap \mathbb{R}^p \); and finally, the induced map \( q_*: H_1(\Gamma; \mathbb{R}) \rightarrow H_1(\Gamma'; \mathbb{R}) \) is an isomorphism since \( q \) is a homotopy equivalence, so the subspace generated by the cycles \( \gamma_i - \gamma_j \) is taken isomorphically to the subspace generated by the cycles \( \gamma_i' - \gamma_j' \).

Now we can put \( f(\Delta^i) \) into general position with respect to \( H \) by an inductive procedure. By our preliminary barycentric subdivision of \( D^k \), \( f(\Delta^i) \) is contained in the union of a chain of open simplices \( \sigma_1, \ldots, \sigma_q = \sigma \) of \( A_n \), each a proper face of the next. Let \( V_i \) be the subspace of \( \mathbb{R}^m \) spanned by \( \sigma_i \) and let \( H_i = H \cap V_i \). Also, let \( \Delta^i \) be the subsimplex of \( \Delta^i \) spanned by the vertices mapping to \( V_i \) and let \( L_i \) be the subspace of \( \mathbb{R}^m \) spanned by \( f(\Delta^i) \). To start the induction there is no difficulty in perturbing \( f \) on the vertices of \( \Delta^i \) so that \( L_i \) is in general position with respect to \( H_i \) in \( V_i \), as we noted before. By the preceding paragraph the codimension of \( H_i \) in \( V_i \) is independent of \( i \), so \( L_i \) is then automatically in general position with respect to \( H_2 \) in \( V_2 \). There is then no difficulty in perturbing \( f \) on vertices of \( \Delta^i - \Delta^1 \) so that \( L_2 \) is in general position with respect to \( H_2 \) in \( V_2 \). The process is then repeated, putting \( L_i \) into general position with respect to \( H_i \) in \( V_i \) for each \( i \). In the end \( f(\Delta^i) \) is in general position with respect to \( H \) in \( \mathbb{R}^m \), as desired.
Then one repeats the procedure for other critical planes $H$ and other simplices $\Delta^i$. Since general position is an open condition, if subsequent perturbations are sufficiently small they will not destroy a general position already created.

4.4. Stage 2: Overview

Having made the deformation of $f$ in Lemma 4.4, all subsequent deformations of $f$ will leave sufficiently small $\epsilon$-cones unchanged.

The filtration of $\mathcal{A}_n$ defined by the subspaces $\Sigma_i$ consisting of graphs of codimension at least $i$ pulls back via $f$ to a filtration of $D^k$ by subpolyhedra $f^{-1}(\Sigma_i)$ of codimension at least $i$ in $D^k$. Let $\mathcal{F}^i = f^{-1}(\Sigma_{k-i})$, so $\dim(\mathcal{F}^i) \leq i$ and $\mathcal{F}^0 \subset \mathcal{F}^1 \subset \ldots \subset \mathcal{F}^k = D^k$. We assume by induction on $i$ that $f$ has already been deformed so that the degree of $\Gamma_s$ is at most $k$ for $s$ in a neighborhood of $\mathcal{F}^{t-1}$.

Let $S$ be a component of $\mathcal{F}^t - \mathcal{F}^{t-1}$. For convenience, delete from $S$ the points lying in a small open neighborhood of $\mathcal{F}^{t-1}$ so that the new $S$ is a compact polyhedron with the degree of $\Gamma_s$ at most $k$ in a neighborhood of its frontier $\partial S$ in $\mathcal{F}^t$. As $s$ varies over $S$, the $\epsilon$-cones of $\Gamma_s$ do not change, since the codimension of critical points of $\Gamma_s$ does not change.

A downward path in $\Gamma_s$ from one critical point to another is called a connecting path. A connecting path may contain critical points in its interior. The number of connecting paths in $\Gamma_s$ is its complexity $c_s$. We shall also be interested in the number $e_s$ of connecting paths in $\Gamma_s$ which are extended branches, containing no critical points in their interior. If $e_s > i$ for some $s \in S$, we will describe a procedure for deforming the family $\Gamma_s$ by a homotopy supported in a neighborhood of $S$ so that:

1. The $\epsilon$-cones of $\Gamma_s$ do not change during the homotopy, and the degree of $\Gamma_s$ is not increased.

2. The maximum complexity of $\Gamma_s$ over $S$ is decreased.

Since the maximum complexity cannot decrease infinitely often, finitely many repetitions of the process will reduce us to the case that $e_s \leq i$ for all $s \in S$. We will then construct a further deformation splitting $\Gamma_s$ to reduce its degree to at most $k$ near $S$, thereby completing the induction step.

4.5. Canonical splitting and extension to a neighborhood

The set $K$ of points $s \in S$ for which the complexity $c_s$ is maximal is a closed subset, and in fact a subpolyhedron, since complexity changes only when lower endpoints of extended branches move off critical points, decreasing the complexity. Let $K_0$ be a connected component of $K$. Since complexity is constant over $K_0$, the extended branches of $\Gamma_s$ are independent of $s$ over $K_0$. Hence we can define a homotopy $\Gamma_s$ for $s \in K_0$ which performs the canonical splitting of $\Gamma_s$. As $s$ passes from $K_0$ to nearby points in $S$, the lower endpoints of extended branches of $\Gamma_s$ can move off critical points, but sufficiently near $K_0$ they at least stay in the associated $\epsilon$-cones. So we can extend the homotopy $\Gamma_s$ over a neighborhood of $K_0$ in $S$ by splitting the extended branches down to these $\epsilon$-cones. As we move off $S$ into $D^k$, each critical point $x$ of $\Gamma_x$ over $S$ can bifurcate into several critical points. Let $H_x \subset \Gamma_x$ be the convex hull of these critical points, and $H_x^\epsilon$ be the downward $\epsilon$-neighborhood of this hull, consisting of $H_x$ together with points of $\Gamma_x$ closer to the basepoint within distance $\epsilon$ of $H_x$. The extended branches of critical points of $\Gamma_s$ for $s \in K_0$ can be viewed as attaching at their
lower endpoints to the \( H^r_z \) for nearby \( s \) in \( D^k \), so we can extend the homotopy \( \Gamma_s \) over a neighborhood of \( K_0 \) in \( D^k \) by splitting extended branches down to the \( H^r_z \) where they attach.

This homotopy defined in a neighborhood of \( K_0 \) can be damped down near the boundary of the neighborhood so as to give a homotopy \( \Gamma_s \) defined throughout \( D^k \) and supported near \( K_0 \). For simplicity we rename the result of this homotopy again \( \Gamma_s \).

4.6. Reducing complexity by sliding in the \( \varepsilon \)-cones

After the preceding homotopy, the attaching point \( \alpha_p \) of a branch \( \beta_s \) of \( \Gamma_s \) lies either in an \( \varepsilon \)-cone \( C^\varepsilon_x \) or at the basepoint, for \( s \) in a neighborhood \( N_0 \) of \( K_0 \) in \( S \). We shall construct a homotopy of \( \Gamma_s \) for \( s \in N_0 \) by perturbing the attaching points \( \alpha_p \), which lie in \( \varepsilon \)-cones \( C^\varepsilon_x \). Each such attaching point can be regarded as a map \( \alpha_p : N_0 \to C^\varepsilon_x \), \( s \mapsto \alpha_p(s) = x \) for \( s \in K_0 \). Taking the product of these maps for all such branches gives a map \( \alpha : N_0 \to \Pi_i C^\varepsilon_x \), the latter product consisting of copies of the various \( \varepsilon \)-cones \( C^\varepsilon_x \) one copy of \( C^\varepsilon_x \) for each branch \( \beta_s \), attaching to \( C^\varepsilon_x \). Inside this product is the point \( p \) whose coordinates are the critical points \( x \in C^\varepsilon_x \). For \( s \in K_0 \) we have \( \alpha(s) = p \), and \( \alpha(s) \neq p \) for \( s \in N_0 - K_0 \) since the complexity of \( \Gamma_s \) decreases once we leave \( K_0 \). We would like to perturb \( \alpha \) to be in general position with respect to the point \( p \), and argue that this implies that \( \alpha(s) \neq p \) for all \( s \in N_0 \), lowering the complexity of \( \Gamma_s \) over \( K_0 \).

We reduce the problem to one of putting a map into general position with respect to a subcomplex of a manifold, then apply standard general position theory for manifolds. Choose an embedding of each \( \varepsilon \)-cone \( C^\varepsilon_x \) into a 2-dimensional disk \( D_x \), such that \( C^\varepsilon_x \) meets \( \partial D_x \) in just the endpoints of the branches of \( C^\varepsilon_x \). Since \( C^\varepsilon_x \) does not change over \( S \), one such embedding works over all of \( S \). Under the natural retraction \( D_x \to C^\varepsilon_x \), the preimage of \( x \) is a star-shaped graph \( Y_x \) homeomorphic to \( C^\varepsilon_x \) itself (see Figure 4).

![Figure 4](image-url)

We regard \( \alpha \) as a map \( N_0 \to \Pi_i D_x \), and perturb \( \alpha \) to be in general position with respect to the subcomplex \( Y = \Pi_i Y_x \). After this perturbation, the codimension of \( \alpha^{-1}(Y) \) in \( N_0 \) is at least as large as the codimension of \( Y \) in \( \Pi_i D_x \), which equals the number of subscripts \( j \), that is, the number of branches attaching to \( \varepsilon \)-cones \( C^\varepsilon_x \). This is exactly the number \( e_s \) since \( \Gamma_s \) has been canonically split over \( K_0 \). Thus if \( e_s > i \), a perturbation of \( \alpha \) makes its image disjoint from \( Y \). Composing with the retractions of the disks \( D_x \) onto the \( \varepsilon \)-cones \( C^\varepsilon_x \), we have then deformed attaching points of branches so that at no point in \( N_0 \) are all the attaching points \( \alpha \) at critical points simultaneously.
Any perturbation of the attaching points $\alpha_j$ so that not all of them are at the critical points reduces complexity. This is because there is a natural quotient map of the perturbed $\Gamma_s$ onto the original $\Gamma_s$ with all $\alpha_j$ at critical points, so the collection of connecting paths in the perturbed $\Gamma_s$ can be regarded as a subcollection of the connecting paths of the original $\Gamma_s$. This will be a proper subcollection if at least one $\alpha_j$ is not at a critical point.

Thus we have succeeded in homotoping $\Gamma_s$ over $N_0$ to decrease the maximum complexity there. We wish to extend this homotopy $\Gamma_{s^*}$ over a neighborhood of $K_0$ in $D^k$. There is a canonical map $r_s: C_s^z \to H^*_s$ taking endpoints of $C_s^z$ to the corresponding endpoints of $H^*_s$, the point $x$ to the barycenter of $H^*_s$, and each segment of $C_s^z$ joining an endpoint to $x$ to the segment in $H^*_s$ joining the corresponding endpoint to the barycenter. By composition with $r_s$, the homotopy of attaching points in the preceding paragraph for $s \in N_0$ gives a homotopy of attaching points for nearby $s$ in $D^k$. For an attaching point $\alpha_j(s) \in H^*_s$ this homotopy starts at $r_s(\alpha_j(s))$ rather than at $\alpha_j(s)$ itself, but we can precede the homotopy by the homotopy from $\alpha_j(s)$ to $r_s(\alpha_j(s))$ along the canonical path in $H^*_s$. If $s \in S$, this preliminary homotopy is constant.

Again we damp this homotopy $\Gamma_{s^*}$ defined in a neighborhood of $K_0$ off near the boundary of the neighborhood to get a homotopy defined over all of $D^k$ and supported near $K_0$. Doing this for all components $K_0$, the result is a new family $\Gamma_s$, whose maximum complexity on $S$ has decreased. So by iteration, as described earlier, we eventually deform $\Gamma_s$ to make $e_s \leq i$ over $S$.

4.7. Reducing the degree

It remains to reduce the degree to at most $k$ near $S$. Define the split-degree $\text{sdeg}(\Gamma_s)$ to be the degree of the canonical splitting of $\Gamma_s$. For a critical point $x$ of $\Gamma_s$, let $a_x$ be the number of extended branches which terminate at $x$, and $b_x$ the number of downward directions from $x$. Then

$$\text{sdeg}(\Gamma_s) = \sum_x (a_x + b_x - 2) \leq \sum_x a_x + \sum_{\text{codim}(x) \geq 1} (b_x - 1) = e_s + \text{codim}(\Gamma_s).$$

Our operations thus far have reduced $e_s$ to at most $i$ on $S$. Since the dimension of $S$ is $i$, the codimension of graphs in the image of $S$ is equal to $k - i$, by Lemma 4.4. Therefore the split-degree of $\Gamma_s$ is at most $k$ over $S$.

To go from split-degree at most $k$ to degree at most $k$, choose a triangulation of $S$ such that split-degree is constant over open simplices. Consider a simplex $\sigma$ of this triangulation, and assume inductively that we have already reduced the degree to at most $k$ near $\partial \sigma$. The discrepancy between degree and split-degree arises from extended branches which can be canonically split all the way down to the basepoint. The collection of extended branches having their lower endpoint at the basepoint does not change over the interior of $\sigma$ since split-degree is constant there. We can apply the canonical splitting procedure from earlier in the proof just to these extended branches ending at the basepoint, damping this splitting off near $\partial \sigma$ where the degree is already at most $k$. In a neighborhood of $\sigma$ in $S$, split-degree can decrease because more extended branches go down to the basepoint, but we ignore these and just split the extended branches which we split over $\sigma$. Similarly, as we pass to points near $\sigma$ in $D^k$ we continue to split the same collection of extended branches, regarding these as extending downward from hulls, as earlier in the proof. The resulting homotopy is then damped off as we move away from $\sigma$ in $D^k$, finishing the induction step.
5. Rational homology

5.1. Definition of $SA_{n,k}$ and $Q_{n,k}$

In this section we will study the rational homology of $\text{Aut}(F_n)$ by studying the action of $\text{Aut}(F_n)$ on subcomplexes of the spine $SA_n$ of $\mathbb{A}_n$. The spine has computational advantages over the whole space since it is of lower dimension and its quotient by $\text{Aut}(F_n)$ is compact.

The subcomplexes we use correspond to the subspaces $\mathbb{A}_{n,k}$ consisting of graphs of degree at most $k$. The deformation retraction of $\mathbb{A}_n$ onto $SA_n$ restricts to a deformation retraction of $\mathbb{A}_{n,k}$ onto the full subcomplex $SA_{n,k}$ of $SA_n$ spanned by barycenters of open simplices in $\mathbb{A}_{n,k}$. It follows from Corollary 3.4 that $SA_{n,k}$ is $(k-1)$-connected.

The group $\text{Aut}(F_n)$ acts on $\mathbb{A}_n$, taking open simplices to open simplices, by

$$(\Gamma, v_0, \phi) \psi = (\Gamma, v_0, \phi \psi).$$

This action restricts to simplicial actions on the spines $SA_n$ and $SA_{n,k}$. Let $Q_n$ be the quotient $SA_n/\text{Aut}(F_n)$ and $Q_{n,k}$ the quotient $SA_{n,k}/\text{Aut}(F_n)$, so that $Q_n$ is filtered by the subspaces $Q_{n,k}$. Since marked graphs which differ by basepoint-preserving homeomorphisms of the graph are equivalent in $SA_n$, and since the action of $\text{Aut}(F_n)$ changes the markings $\phi$ arbitrarily, the vertices of the quotient $Q_n$ are simply the homeomorphism types of basepointed graphs. An $r$-simplex of $SA_n$ is given by a sequence of $r$ forest collapses, where a forest is a disjoint union of trees. This sequence can be regarded as an increasing sequence of forests $\Phi_1 \subset \Phi_2 \subset \ldots \subset \Phi_r$, in the initial pointed marked graph $\Gamma$. Another sequence $\Phi'_1 \subset \Phi'_2 \subset \ldots \subset \Phi'_r$ in $\Gamma$ is equivalent under the action of $\text{Aut}(F_n)$ if and only if there is a basepoint-preserving homeomorphism of $\Gamma$ taking $\Phi_i$ to $\Phi'_i$ for all $i$. Since all vertices of the simplex are graphs with distinct homeomorphism types, the action does not identify any points within a simplex, but only identifies different simplices together. Thus $Q_n$ has a CW structure with each cell a simplex; however, this is not a simplicial complex structure since different simplices can have the same set of vertices, as we shall see in examples below. Since there are only finitely many topological types of basepointed graphs in $\mathbb{A}_n$, $Q_n$ is a finite complex, as are its subcomplexes $Q_{n,k}$.

Every simplex of $Q_n$ or $Q_{n,k}$ is a subsimplex of a simplex obtained by the following procedure. Choose a basepointed graph $\Gamma$ in which all nonbasepoint vertices have valence 3, and choose a maximal tree $T$ in $\Gamma$. If $T$ has $r$ edges, then we get an $r$-simplex by collapsing these edges one by one in some order. Different orders may give the same or different $r$-simplices of $Q_n$, depending on whether they are equivalent under basepoint-preserving symmetries of $\Gamma$. In the case of $Q_{n,k}$, $\Gamma$ will have $k$ vertices other than the basepoint, so $T$ will have $k$ edges joining the $k+1$ vertices of $\Gamma$, and $Q_{n,k}$ will be $k$-dimensional.

As an example let us determine $Q_{n,2}$. Modulo wedging on circles at the basepoint, there are only five homeomorphism types of pairs $(\Gamma, T)$ as in the previous paragraph, with the degree of $\Gamma$ equal to 2. These are shown in Figure 5. In each case $T$ has two edges. In graphs 1, 3 and 5 there is a symmetry switching the two edges of $T$, so only one 2-simplex is produced in these cases. For graphs 2 and 4 there are two 2-simplices, depending on the order of collapsing the two edges of $T$. Thus $Q_{n,2}$ has a total of seven 2-simplices if $n \geq 4$, and these are attached together as shown. Note that the 2-simplices 1 and 2b have two edges in common, so form a 'pocket', and similarly for
the 2-simplices 3 and 4b. When \( n = 3 \) the simplex labelled 5 is omitted, and when \( n = 2 \) the simplices 3 and 4ab are also omitted. Note that \( Q_{n,2} \) is contractible for all \( n \).

5.2. Stability

The stabilizer of a simplex of \( SA_n \) under the action of \( Aut(F_n) \) is contained in the symmetry group of a finite basepointed graph; in particular it is a finite group. From this finite-stabilizer property and the fact that \( SA_{n,k} \) is \((k-1)\)-connected, it follows that \( Q_{n,k} \) has the same rational homology as \( Aut(F_n) \) in dimensions less than \( k \) (see [2, Exercise 2, p. 174]). More precisely, we have the following lemma.

**Lemma 5.1.** \( H_i(Q_{n,k}; \mathbb{Q}) \) is isomorphic to \( H_i(Aut(F_n); \mathbb{Q}) \) for \( k > i \), and \( H_k(Q_{n,k}; \mathbb{Q}) \) maps onto \( H_k(Aut(F_n); \mathbb{Q}) \).

For example, since \( Q_{n,2} \) is contractible for all \( n \) we deduce that \( H_i(Aut(F_n); \mathbb{Q}) = 0 \) for \( i = 1, 2 \). This is consistent with the classical fact that \( H_1(Aut(F_n); \mathbb{Z}) = \mathbb{Z}_2 \) and the calculations of \( H_k(Aut(F_n); \mathbb{Z}) \) in [4, 7–9].

Stability for the rational homology of \( Aut(F_n) \) will follow from the fact that the homotopy type of the complexes \( Q_{n,k} \) is independent of \( n \), for \( n \) sufficiently large with
respect to \( k \). To prove this, we need the following observations on the relation between the rank, degree and homeomorphism type of a graph. Recall that a vertex of a graph is called a cut vertex if deleting it disconnects the graph.

**Lemma 5.2.** Let \( \Gamma \) be a graph of degree \( k \) and rank \( n \).

(i) If \( k < n/2 \), then \( \Gamma \) has a loop at the basepoint.

(ii) If \( k < 2n/3 \) then \( \Gamma \) has either a loop at the basepoint or a theta graph wedge summand.

(iii) If \( k < n-1 \), then the basepoint is a cut vertex.

**Proof.** Without loss of generality, we may assume that all vertices of \( \Gamma \) other than the basepoint are trivalent. Let \( \Gamma_1 \) be the full subgraph of \( \Gamma \) spanned by all nonbasepoint vertices. Then \( \Gamma_1 \) has \( V_1 = k \) vertices and \( E_1 \) edges.

If \( \Gamma \) has no loops at the basepoint, there are \( |v_0| = 2n-k \) edges not in \( E_1 \), and we compute \( \chi(\Gamma) = 1-n = (1+V_1)-(E_1+|v_0|) = 1+k-E_1-(2n-k) \), so that \( n = 2k-E_1 \). In particular, \( n \leq 2k \) and statement (i) follows. If \( k < 2n/3 \), then \( E_1 = 2k-n < k/2 \), so that \( \Gamma_1 \) has an isolated vertex, and statement (ii) follows. If \( k < n-1 \), then \( E_1 = 2k-n < k-1 \), so \( \chi(\Gamma_1) = V_1-E_1 > k-(k-1) = 1 \), and \( \Gamma_1 \) is disconnected, proving (iii).

We can embed \( SA_{n,k} \) in \( SA_{n+1,k} \) by sending \((\Gamma, v_0, \phi)\) to \((\Gamma \lor S^1, v_0, \phi')\), where \( \phi' \) is \( \phi \) extended to \( E_{n+1} \) by mapping the last generator to the simple loop \( S^1 \). There are two possibilities for \( \phi' \), depending on the orientation chosen for \( S^1 \), but these differ by an isometry of \( \Gamma \lor S^1 \), and hence give the same point in \( SA_{n+1,k} \). This embedding of \( SA_{n,k} \) in \( SA_{n+1,k} \) induces an embedding \( Q_{n,k} \longrightarrow Q_{n+1,k} \), sending a chain of forests in \( \Gamma \) corresponding to a cell in \( Q_{n,k} \) to the same chain of forests in \( \Gamma \lor S^1 \). This embedding is onto if \( n \geq 2k \) by statement (i) of Lemma 5.2, so we have:

**Proposition 5.3.** The map \( Q_{n,k} \longrightarrow Q_{n+1,k} \) is a homeomorphism for \( n \geq 2k \).

For \( n \) between \( 3k/2 \) and \( 2k \), the inclusions are no longer homeomorphisms, but we have:

**Proposition 5.4.** For \( n \geq 3k/2 \), the inclusion \( Q_{n,k} \longrightarrow Q_{n+1,k} \) is a homotopy equivalence.

**Proof.** A graph \( \Gamma \) which is in \( Q_{n+1,k} \) but not in the image of \( Q_{n,k} \) has degree at most \( k \), rank \( n+1 > 3k/2 \) and no loops at the basepoint. Therefore, by statement (ii) of Lemma 5.2, contains \( r \geq 1 \) theta graph wedge summands. Let \( \Theta \) be the union of all the theta graph summands of \( \Gamma \), so that \( \Gamma = \Theta \lor \Gamma' \), with \( \text{rank}(\Gamma') = n+1-2r \). Let \( St_{m,r}(\Gamma) \) denote the union of all the simplicial cells in \( Q_{m,i} \) which contain \( \Gamma \). Then \( St_{n+1,k}(\Gamma) \) is the product of \( St_{2r,r}(\Theta) \) with \( St_{n+1-2r,k-r}(\Gamma') \). Since \( \Theta \) has only one maximal chain of forests up to automorphisms of \( \Theta \), \( St_{2r,r}(\Theta) \) consists of exactly one simplex, all of whose vertices other than \( \Theta \) have lower degree. Shrinking one edge of \( \Theta \) collapses this simplex, giving a deformation retraction of \( St_{n+1,k}(\Gamma) \) into the image of \( Q_{n-1,k-1} \) in \( Q_{n+1,k} \).

The embedding \( Q_{n,k} \longrightarrow Q_{n+1,k} \) is natural with respect to the inclusion \( \text{Aut}(F_n) \longrightarrow \text{Aut}(F_{n+1}) \). Therefore Propositions 5.3 and 5.4, and Lemma 5.1 imply the following theorem.
**Theorem 5.5.** The map $H_i(\text{Aut}(F_n); \mathbb{Q}) \longrightarrow H_i(\text{Aut}(F_{n+1}); \mathbb{Q})$ induced by inclusion is an isomorphism for $n \geq 3(i+1)/2$.

6. Free factorizations and split factorizations

In this section we consider two simplicial complexes with natural $\text{Aut}(F_n)$ actions, and show that they are highly connected. Both are geometric realizations of partially ordered sets (posets) of factorizations of $F_n$.

6.1. Free factorizations and cut vertices

We first consider factorizations $F_n = H_1 \ast \ldots \ast H_m$ where the $H_i$ are nontrivial proper subgroups of $F_n$ and two such factorizations which differ only by a permutation of the factors $H_i$ are regarded as the same. The set of all such factorizations is partially ordered by refinement: $H \succeq K$ if $K$ can be obtained from $H$ by splitting some of the factors of $H$. Define $FF_n$ to be the geometric realization of this poset. Since the number of factors can range from 2 to $n$, $FF_n$ has dimension $n-2$. We will prove:

**Theorem 6.1.** $FF_n$ is $(n-3)$-connected, hence is homotopy equivalent to a wedge of $(n-2)$-spheres.

Free factorizations of $F_n$ are mirrored geometrically by pointed marked graphs whose basepoint is a cut vertex. With this in mind, we define a subcomplex $C_n$ of $SA_n$ by $C_n = \{(\Gamma, v_0, \phi) : \Gamma - v_0 \text{ is disconnected}\}$.

We first prove the geometric version of Theorem 6.1.

**Proposition 6.2.** $C_n$ is $(n-3)$-connected.

**Proof.** Consider a map $S^i \longrightarrow C_n$ where $i \leq n-3$. Since $SA_n$ is contractible, this extends to a map $D^{i+1} \longrightarrow SA_n$. By the Degree Theorem, this extension can be deformed into $SA_{n,n-2}$. By part (iii) of Lemma 5.2, the base vertex of any pointed graph of rank $n$ and degree at most $n-2$ is a cut vertex, so that $SA_{n,n-2} \subset C_n$, proving the proposition.

To go from complexes of graphs to complexes of splittings of $F_n$, we use Quillen's Theorem A [10]. If $X$ and $Y$ are posets, a map $f: X \longrightarrow Y$ is called a poset map if $f(x_1) \leq f(x_2)$ whenever $x_1 \leq x_2$. For $y \in Y$, the fiber $f \lessdot y$ is the set of $x \in X$ with $f(x) \leq y$.

**Theorem 6.3 (Quillen's Theorem A).** A poset map $f: X \longrightarrow Y$ is a homotopy equivalence if and only if the fibers $f \lessdot y$ are contractible for all $y \in Y$.

**Proof of Theorem 6.1.** For $(\Gamma, v_0, \phi)$ a vertex of $C_n$, let $\Gamma_1, \ldots, \Gamma_k$ be the closures of the connected components of $\Gamma - v_0$. The map $f: C_n \longrightarrow FF_n$ sending $(\Gamma, v_0, \phi)$ to the factorization $\phi^{-1}(\pi_0(\Gamma_1, v_0)) \ast \ldots \ast \phi^{-1}(\pi_0(\Gamma_k, v_0))$ of $F_n$ is a poset map, since collapsing a forest of $\Gamma$ can only refine the associated factorization.

Let $H_1 \ast H_2 \ast \ldots \ast H_k$ be a factorization of $F_n$. The fiber $f \lessdot H_1 \ast H_2 \ast \ldots \ast H_k$ is the join of the contractible complexes $SA_{n_i}$, where $n_i$ is the rank of $H_i$, so is contractible. We now apply Quillen's Theorem A to prove the theorem.
6.2. Loops at the basepoint and split factorizations

To prove integral homology stability, it is convenient to consider the simplicial complex $SF_n$ whose $k$-simplices are the (unordered) factorizations $Z_0 \ast \cdots \ast Z_k \ast H$ of $F_n$ where each $Z_i$ is a copy of $\mathbb{Z}$. The various faces of dimension $k-1$ of such a $k$-simplex are obtained by amalgamating one $Z_i$ with $H$. The maximal simplices of $SF_n$ are the factorizations $F_n = Z_0 \ast \cdots \ast Z_{n-1}$, so $SF_n$ is $(n-1)$-dimensional.

**Proposition 6.4.** $SF_n$ is $[(n-3)/2]$-connected.

**Proof.** We first compare $SF_n$ with the subcomplex $SF'_n$ of $F_n$ defined by the poset of free factorizations of $F_n$ having at most one noncyclic factor. A vertex $Z_0 \ast \cdots \ast Z_k \ast H$ of $SF_n$ is uniquely determined by the adjacent vertices $Z_0 \ast H_0, \ldots, Z_k \ast H_k$ where $H_i$ is the free product of $H$ with all of the cyclic factors except $Z_i$. This means that $SF_n'$ is a subcomplex of the barycentric subdivision of $SF_n$. Since cyclic factors $H$ are permitted in free factorizations $Z_0 \ast \cdots \ast Z_k \ast H$ for $SF_n$ but not for $SF_n'$, $SF_n'$ intersects each $(n-1)$-simplex of $SF_n$ in the cone on the $(n-3)$-skeleton of the $(n-1)$-simplex. The simplex deformation retracts onto this cone, so $SF_n$ deformation retracts onto $SF_n'$ since each $(n-2)$-simplex of $SF_n'$ is a face of only one $(n-1)$-simplex.

Next we compare $SF_n'$ with the subcomplex $L_n$ of $SA_n$ consisting of pointed marked graphs with at least one loop at the basepoint. Let $(\Gamma, v_0, \phi)$ be a point in $L_n$, so that $\Gamma$ is the wedge sum of circles $c_1, \ldots, c_k$ and a graph $\Gamma_0$ with no loops at the basepoint. A map $f: L_n \longrightarrow SF_n'$ is defined by sending $(\Gamma, v_0, \phi)$ to $\phi^{-1}(\pi_1(c_1, v_0)) \ast \cdots \ast \phi^{-1}(\pi_1(c_k, v_0)) \ast \phi^{-1}(\pi_1(\Gamma_0, v_0))$. This is a poset map, since a forest collapse can only split off more $\mathbb{Z}$-factors from $\pi_1(\Gamma_0, v_0)$. The fibers $f_{\ast H}$ are isomorphic to $SA_{n,H}$, where $n_0$ is the rank of $\pi_1(\Gamma_0)$. Since these fibers are contractible, $f$ is a homotopy equivalence by Quillen's Theorem A.

It remains to show that $L_n$ is $[(n-3)/2]$-connected. By Lemma 5.2, if $(\Gamma, v_0)$ is a pointed graph of rank $n$ and degree $k < n/2$, then $\Gamma$ has at least one loop at the basepoint. By the Degree Theorem, a map $D^k \longrightarrow SA_n$ extending $S^{(k-1)} \longrightarrow L_n$ can be deformed into $L_n$ as long as $k < n/2$, that is, $L_n$ is $[(n-1)/2]-1 = [(n-3)/2]$-connected.

We do not know whether $SF_n$ is more highly connected than the proposition states, but even if it is, this would not improve the homological stability range we obtain in the next section.

7. Integral homology stability

In [5], it is shown that the inclusion $\text{Aut}(F_n) \longrightarrow \text{Aut}(F_{n+1})$ induces an isomorphism on homology in dimension $i$ if $n > i^2/4 + 2i - 1$. The quadratic dependence of $n$ on $i$ was surprising in light of similar bounds for homology stability of various linear groups and mapping class groups, which are linear in $i$. In this section we use a spectral sequence argument to show that the stability range can be improved as follows.

**Theorem 7.1.** The map $H_i(\text{Aut}(F_n); \mathbb{Z}) \longrightarrow H_i(\text{Aut}(F_{n+1}); \mathbb{Z})$ induced by inclusion is surjective for $n \geq 2i+1$ and an isomorphism for $n \geq 2i+3$. 

Remark 7.2. In [5] it is also shown that the natural map $\text{Aut}(F_n) \to \text{Out}(F_n)$ induces an isomorphism on homology in dimension $i$ if $n > i^2/4 + 5i/2$. The above result does not improve the homology stability range for $\text{Out}(F_n)$.

7.1. Construction of the spectral sequence

To streamline the notation in what follows, we will denote $\text{Aut}(F_n)$ by $A_n$.

$A_n$ acts on the complex $SF_n$ of ‘split factorizations’ of $F_n$ defined at the end of the last section. This action gives rise to a spectral sequence as follows.

Let $C_{n-1} \to C_{n-2} \to \cdots \to C_0 \to \mathbb{Z}$ be the augmented simplicial chain complex of $SF_n$. Since $SF_n$ is $m = [(n-3)/2]$-connected, the truncated chain complex

$$0 \to \mathbb{Z}_m \to C_m \to \cdots \to C_0 \to \mathbb{Z} \to 0$$

is exact, where $\mathbb{Z}_m$ is the subgroup of cycles in dimension $m$. We denote this truncated complex by $C_\ast$, with $C_{-1} = \mathbb{Z}$ and $C_{m+1} = \mathbb{Z}_m$. Let

$$\cdots \to E_2 A_n \to E_1 A_n \to E_0 A_n \to \mathbb{Z}$$

be a free $\mathbb{Z}A_n$-resolution of $\mathbb{Z}$. Tensoring $C_\ast$ over $\mathbb{Z}A_n$ with $E_\ast A_n$ gives a double complex:

$$\cdots \to E_2 A_n \otimes C_p \to E_1 A_n \otimes C_p \to E_0 A_n \otimes C_p \to \cdots$$

with $q \geq 0$ and $-1 \leq p \leq m+1$. The horizontal arrows are $d \otimes 1$, where $d$ is the differential in $E_\ast A_n$, and the vertical arrows are $1 \otimes (-1)^q \partial$, where $\partial$ is the differential in $C_\ast$. The columns are exact since $C_\ast$ is exact and $E_q A_n$ is a free $\mathbb{Z}A_n$-module. Therefore the spectral sequence associated to the vertical filtration of this complex converges to zero. Taking the spectral sequence associated to the horizontal filtration gives another spectral sequence converging to zero, whose $E^1_{p,q}$-term is $H_q(A_n; C_p)$.

For each $n$, fix an ordered basis $x_1, \ldots, x_n$ for $F_n$, so that $F_n$ appears naturally as the subgroup of $F_{n+1}$ generated by the first $n$ basis elements. $A_n$ acts transitively on $p$-simplices of $SF_n$, so that

$$C_p \cong \mathbb{Z}A_n \otimes_{\mathbb{Z}S_p} \mathbb{Z}_\sigma$$

for $0 \leq p \leq m$.

where $S_p$ is the stabilizer of the standard $p$-cell $\langle x_1 \rangle \ast \langle x_2 \rangle \ast \cdots \ast \langle x_{p+1} \rangle \ast \langle x_{p+2}, \ldots, x_n \rangle$, and $\mathbb{Z}_\sigma$ is $\mathbb{Z}$ with the action of an element $g$ of $S_p$ being plus or minus the identity depending on whether $g$ preserves or reverses the orientation of the standard $p$-cell (see [2, Example 5.5(b), p. 68]). By Shapiro’s lemma, the inclusion of $S_p$ into $A_n$ induces an isomorphism $H_q(S_p; \mathbb{Z}_\sigma) \cong H_q(A_n; C_p)$ [2, p. 73].

The stabilizer $S_p$ is equal to $\Sigma_{p+1} \times A^\ast_{n-p-1}$, where $\Sigma_{p+1}$ is generated by
automorphisms which permute and invert the first \( p+1 \) basis elements of \( F_n \), and \( A_{n-p-1}^+ \) is the group of automorphisms of the subgroup of \( F_n \) generated by the last \( n-p-1 \) basis elements. We can now identify the \( E_{p,q}^1 \) terms of the horizontal spectral sequence as

\[
E_{p,q}^1 = H_q(\Sigma_{p+1} \times A_{n-p-1}^+; \mathbb{Z}_p).
\]

Note that elements of \( A_{n-p-1}^+ \) act trivially on the module \( \mathbb{Z}_p \), as do inversions of the first \( p+1 \) basis elements. We can apply the Künneth formula [2, Exercise, p. 106] to compute

\[
H_q(\Sigma_p \times A_{n-p-1}^+; \mathbb{Z}_p) \cong \bigoplus_{s+t=q} H_s(\Sigma_{p+1}; \mathbb{Z}_p) \otimes H_t(A_{n-p-1}^+; \mathbb{Z}) \oplus \bigoplus_{s+t=q-1} \text{Tor}(H_s(\Sigma_{p+1}; \mathbb{Z}_p), H_t(A_{n-p-1}^+; \mathbb{Z})).
\]

The inclusion \( F_n \to F_{n+1} \) induces a map of the corresponding complexes \( SF_n \to SF_{n+1} \), mapping a \( p \)-cell \( <w_1> \cdots <w_{p+1}> * H \) to \( <w_1> \cdots <w_{p+1}> * (H * <x_{n+1}>). \) We denote by \( C_\ast \) the truncated chain complex of \( SF_{n+1} \). The inclusion \( A_n \to A_{n+1} \) sends \( \Sigma_{p+1} \times A_{n-p}^+ \) to \( \Sigma_{p+1} \times A_{n-p}^+ \) by the identity on the first factor and the standard inclusion on the second factor. We form a relative spectral sequence from the double complex (Figure 7).

\[
\begin{array}{cccc}
E_{q-1} A_n \otimes C_p \oplus E_q A_{n+1} \otimes C_p' & \to & E_{q-1} A_n \otimes C_p \oplus E_q A_{n+1} \otimes C_p' \\
\downarrow & & \downarrow \\
E_{q-2} A_n \otimes C_p \oplus E_{q-1} A_{n+1} \otimes C_p' & \to & E_{q-2} A_n \otimes C_p \oplus E_{q-1} A_{n+1} \otimes C_p'
\end{array}
\]

Fig. 7.

The columns are the mapping cones of the chain map \( E_\# A_n \otimes C_p \to E_\# A_{n+1} \otimes C_p \). The \( E_{p,q}^1 \)-terms of the spectral sequence are

\[
E_{p,q}^1 = H_q(\Sigma_{p+1} \times A_{n-p-1}^+; \Sigma_{p+1} \times A_{n-p-1}^+; \mathbb{Z}_p) \\
= H_q((\Sigma_{p+1}; \mathbb{Z}) \times (A_{n-p}^+ \times A_{n-p}^+); \mathbb{Z}_p).
\]

By the Künneth formula (see [11, pp. 234–235]) this becomes

\[
E_{p,q}^1 \cong \bigoplus_{s+t=q} H_s(\Sigma_{p+1}; \mathbb{Z}_p) \otimes H_t(A_{n-p}^+, A_{n-p}^+; \mathbb{Z}) \oplus \bigoplus_{s+t=q-1} \text{Tor}(H_s(\Sigma_{p+1}; \mathbb{Z}_p), H_t(A_{n-p}^+, A_{n-p}^+; \mathbb{Z})).
\]

7.2. Stability with slope 3

We first show that \( H(A_n; \mathbb{Z}) \to H(A_{n+1}; \mathbb{Z}) \) is surjective for \( n \geq 3i+1 \) and an isomorphism for \( n \geq 3i+2 \).
We prove this by induction on $i$. Specifically, we assume that for $k < i$ the following statements hold:

(a) For $n \geq 3k$, $H_k(A_n) \rightarrow H_k(A_{n+1})$ is surjective.
(b) For $n \geq 3k+1$, $H_k(A_n) \rightarrow H_k(A_{n+1})$ is an isomorphism.

In particular, (a) and (b) imply that $H_k(A_{n+1}, A_n) = 0$ for $n \geq 3k$. In the spectral sequence constructed above, the map $d^1: E^1_{0,1} \rightarrow E^1_{1,0}$ is

$$H_i(A_n^+, A_{n-1}^+; \mathbb{Z}) \rightarrow H_i(A_{n+1}^+, A_n^+; \mathbb{Z})$$

since $H_0(\Sigma_{n+1}; \mathbb{Z}) = \mathbb{Z}$ for $p \leq 0$, the coefficients $\mathbb{Z}$ being untwisted in this case. By induction the terms $E^k_{t,t}$ with $t \leq i-1$ and $s+t = i$ are all zero. Since the only differentials that can ever hit $E^k_{2i,0}$ originate in $E^k_{s,t}$ with $s+t = i$, and since the spectral sequence converges to zero, this $d^1$ map must be onto.

The subgroup $A^+_n$ of $A_{n+1}$ is conjugate to the standard $A_n$ by an automorphism of $F_{n+1}$ (sending $x_i$ to $x_{i+1}$ for $i \leq n$ and $x_{n+1}$ to $x_0$). Therefore the composition $A_n \rightarrow A^+_n \rightarrow A_{n+1}$ is equal to the standard inclusion $A_n \rightarrow A_{n+1}$ on the level of homology.

A diagram chase of Figure 8 now shows $H_i(A_{n+1}, A_n) = 0$, which implies (a).

**Fig. 8.**

To prove (b), we consider the same spectral sequence, assuming $n \geq 3i+1$. By (a), the terms $E^k_{t,t}$ with $t \leq i$ and $s+t = i+1$ are all zero, so that the differential $d^1: E^1_{i+1,0} \rightarrow E^1_{i+1,1}$ is onto.

We now chase Figure 9 to prove (b):

**Fig. 9.**
7.3. Stability with slope 2

Finally, we improve the stability range to prove the theorem. Specifically, we show that $H_1(A_{n+1}, A_n) = 0$ for $n \geq 2i + 1$, so that the map $H_1(A_n; \mathbb{Z}) \to H_1(A_{n+1}; \mathbb{Z})$ induced by inclusion is surjective for $n \geq 2i + 1$ and an isomorphism for $n \geq 2i + 3$.

Assume by induction that $H_1(A_{n}, A_{n-1}) = 0$ for $j < i$ and $k \geq 2i + 1$. We know that $H_1(A_n, A_{n-1})$ is zero for $n$ sufficiently large with respect to $i$, either by the slope 3 argument above or by the theorem of [S]. Therefore it suffices to show the map $H_1(A_{n}, A_{n-1}) \to H_1(A_{n+1}, A_n)$ induced by inclusion is injective for $n \geq 2i + 1$.

This map is the differential $d^1: E_1^{t,w} \to E_1^{t+1,w}$ in the relative spectral sequence for the complex $S_A^{n+1}$ constructed in the previous section. By induction, the terms $E_1^{t,s}$ with $t < i$ and $s + t = i + 1$ are zero, so the only differential with a chance of killing $E_1^{t,s}$ is $d^1: E_1^{t,s} \to E_1^{t+1,s}$. Since $E_1^{\infty} = 0$, injectivity of $d^1: E_1^{0,t} \to E_1^{-1,t}$ will follow if we show that $d = d^1: E_1^{0,t} \to E_1^{1,t}$ is the zero map.

Recall that $E_1^{0,t} = H_1(A_{n+1}, A_n; C_1)$ and $E_1^{1,t} = H_1(A_{n+1}, A_n; C_0)$. The differential $d$ is given on the chain level by $1 \otimes \partial$, where $\partial: C_1 \to C_0$ is the boundary map on the chains of $S_A^{n+1}$. In particular, if $e_0$ is the standard 1-cell $\langle x_1 \rangle * \langle x_2 \rangle * \langle x_3 \rangle * \cdots * \langle x_n \rangle$ and $v_0$ is the standard 0-cell $\langle x_0 \rangle * \langle x_2 \rangle * \cdots * \langle x_n \rangle$, then $\partial e_0 = v_0 - \alpha v_0$, where $\alpha$ is the automorphism interchanging $x_1$ and $x_0$ and fixing the other generators.

Recall also that $S_1 = \Sigma_2 \times A_{n-1}^+$ is the stabilizer of $e_0$ in $A_{n+1}$. By Shapiro's lemma, the map

$$S: H_1(\Sigma_2 \times (A_{n-1}^+, A_n^-); \mathbb{Z}_0) \to H_1(A_{n+1}, A_n; C_1)$$

induced by inclusion is an isomorphism.

By induction, all of the terms in the Künneth expansion of $H_1(\Sigma_2 \times (A_{n-1}^+, A_n^-); \mathbb{Z}_0)$ vanish except one, and we are left with an isomorphism

$$K: H_0(\Sigma_2; \mathbb{Z}_0) \otimes H_1(A_{n-1}^+, A_n^-; \mathbb{Z}_0) \to H_0(\Sigma_2 \times (A_{n-1}^+, A_n^-; \mathbb{Z}_0))$$

given by the homology cross product.

We will compute the maps $K$, $S$ and $d$ on the chain level, and show that the composition $K \circ S \circ d$ is zero on homology; since $K$ and $S$ are isomorphisms, this will show that $d$ is zero.

Let $F$ be a free resolution of $\mathbb{Z}$ over $\mathbb{Z}S_1$. Then $F$ is naturally a free resolution over $\mathbb{Z}\Sigma_2$ and over $\mathbb{Z}A_{n-1}^+$ by restriction, so that $F \otimes F$ is a free resolution of $\mathbb{Z}$ over $\mathbb{Z}(\Sigma_2 \times A_{n-1}^+)$, where the action is given by $(x \otimes y)(\sigma, g) = x \sigma \otimes y g$. On the chain level, the map

$$K: (F_0 \otimes \Sigma_2 \otimes (F_1 \otimes A_{n-1}^+)) \to (F_1 \otimes F_0) \otimes (\Sigma_2 \otimes A_{n-1}^+)$$

is given by $(x \otimes y) \otimes (y' \otimes t) \mapsto (x \otimes y \otimes y') \otimes s t$.

From the resolution $F \otimes F$ for $S_1$, we get a free resolution for $A_{n+1}$ by inducing up: $F' = (F \otimes F) \otimes S_1 \otimes A_{n+1}$. On the chain level, the map

$$S: F \otimes F \otimes S_1 \otimes A_{n+1} \to F' \otimes A_{n+1} \otimes C_1 = (F \otimes F \otimes S_1 \otimes A_{n+1}) \otimes (Z A_{n+1} \otimes S_1 \otimes \mathbb{Z})$$

is given by $(x \otimes y) \otimes S_1 \otimes s t \mapsto (x \otimes y \otimes S_1 \otimes S_1 \otimes S_1) \otimes (A_{n+1} \otimes S_1 \otimes S_1)$.

Finally, we compute $d$ on the chain level. For any free resolution $F'$ of $\mathbb{Z}$ over $Z A_{n+1}$, $d$ is given on the chain level $F_1 \otimes C_1 \to F_1 \otimes C_0$ by $x \otimes e \mapsto x \otimes d e$, where $d$ is the boundary map $C_1 \to C_0$. Each edge $e$ is equal to $g e_0$ for some $g \in A_{n+1}$, so that

$$x \otimes e = x \otimes g e_0 \mapsto x \otimes (g v_0 - g \alpha v_0) = (x g - x \alpha g) \otimes v_0$$

that is, the map $1 \otimes d$ is the same as the map $(1 - \alpha) \otimes 1$. 
Note that $x \in \Sigma_2 \leq S_1$. Thus when we apply $d$ to $(x \otimes y \otimes s_1) \otimes_A (1 \otimes s_1^t)$ we get

$$( (x \otimes y \otimes s_1) - (x \otimes y \otimes s_1^\alpha)) \otimes_{A_{n+1}} (1 \otimes s_1^t)$$

$$= ((x \otimes y \otimes s_1) - (xx \otimes y \otimes s_1)) \otimes_{A_{n+1}} (1 \otimes s_1^t)$$

$$= ((x - x\alpha) \otimes y \otimes s_1) \otimes_{A_{n+1}} (1 \otimes s_1^t).$$

But $x - x\alpha = 0$ in $H_0(\Sigma_2; Z) \cong Z/2Z$ since $x \in \Sigma_2$ acts nontrivially on $Z$; thus the last expression is zero on homology.

References


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