

A-14-1

		Triv	Ref	Sgn
1	(1)	1	2	1
3	(12)	1	0	-1
2	(123)	1	-1	1

		(4)	(31)	(22)	(211)	(14)	Gx
1	(1)	1	3	2	3	1	24
6	(12)	1	1	0	-1	-1	4
3	(12)(34)	1	-1	2	-1	1	8
8	(123)	1	0	-1	0	1	3
6	(1234)	1	-1	0	1	-1	4

A-14-2

$$\langle \delta_x, \chi_\pi \rangle = \frac{1}{|G|} \sum_{y=gxg^{-1}} \overline{\chi_\pi(y)} = \frac{|G|/|G_x|}{|G|} \overline{\chi_\pi(x)}$$

$$= \frac{1}{|G_x|} \cdot \overline{\chi_\pi(x)}$$

So  ~~$\delta_x = \frac{1}{|G_x|} \sum_{g \in G_x} \chi_\pi(gxg^{-1})$~~

$$|G_x| \delta_x(y) = \sum \overline{\chi_\pi(x)} \chi_\pi(y)$$

$$|G| \delta_1 = \sum \dim \pi \chi_\pi$$

PLANCHEREL FORMULA:

$$\# \delta_e = \sum \dim \pi \chi_\pi$$

IN GENERAL,  $f \in C(G) \mapsto \pi(f)$

$$\pi(f)(v) := \int_G f(x) \pi(x)v \, dx$$

$$\chi_\pi(f) = \text{tr } \pi(f).$$

Rep's of  $S_4$ : Triv, Sgn, Refl.

~~Triv, Sgn, Refl~~ Sgn  $\otimes$  Refl

$$1 + \mathfrak{g} + ? + \mathfrak{g} + 1 = 24 \Rightarrow ? = 2.$$

Example:  $G = SU(2)$   $V(1/2)$  of dimension 2.

$$V \otimes V = S^2 V \oplus \Lambda^2 V \quad \text{action of } S_2$$

$V \otimes V \otimes V$  has an action of  $S_3$

$$S^3 V + V_{\text{refl}} + \Lambda^3 V$$

Same for  $G = S_4$   $V$  3-dim'l

$$V \otimes V = S^2 V + \Lambda^2 V$$

$$3 \cdot 3 = \frac{3 \cdot 4}{2} + \frac{3 \cdot 2}{2}$$

$$6 + 3$$

$$\chi_{S^2 V} + \chi_{\Lambda^2 V} = \chi_V^2$$

Character of  $S^2 V$ : ~~Triv~~

$\Lambda^2 V$ :

$$\sum_{i, j} \langle \pi(x) e_i \otimes \pi(x) e_j, e_j \otimes e_i \rangle = \chi_{S^2 V} - \chi_{\Lambda^2 V}$$

$$\delta_{\hat{x}}(y) = \begin{cases} 1 & y \in \{x\} \\ 0 & \text{otherwise} \end{cases}$$

$$\int_G \delta_{\hat{x}}\left(\frac{y}{z}\right) \cdot \overline{f\left(\frac{y}{z}\right)} d\frac{y}{z} =$$

$$\int_G \delta_{\hat{x}}(zyz^{-1}) \overline{f(y)} dy = \int_G \int_G \delta_{\hat{x}}(zyz^{-1}) \overline{f(y)} dy dz$$

Change the order of integration & change variables!

$$u = zyz^{-1} \quad \int_{G \setminus \{e\}} \delta_{\hat{x}}(u) \int_G \overline{f(z^{-1}uz)} dz du$$

$y = z^{-1}uz$

class function.

$$Af(x) := \int_G f(gxg^{-1}) dg$$

$$A^2 = A$$

called a projector:

$$A^2 = A$$

$$A + (I - A) = I$$

$$(I - A) \cdot A = A \cdot (I - A) = 0$$

$$(I - A)^2 = 0$$

So "Fourier Coefficients" only  $\neq 0$  for class functions.

$$\begin{aligned} \text{Basis } \chi_{\pi} & \int_G \delta_{\hat{x}}(g) \overline{\chi_{\pi}(g)} dg = \\ &= \frac{1}{|G|} \sum_{g \in O(\hat{x})} \overline{\chi_{\pi}(g)} = \frac{|O(\hat{x})|}{|G|} \overline{\chi_{\pi}(\hat{x})} \\ &= \frac{1}{|G_{\hat{x}}|} \overline{\chi_{\pi}(\hat{x})}. \end{aligned}$$

### Symplectic Groups:

$\Phi$ : Any bilinear nondegenerate symplectic form  
 $\sim \begin{pmatrix} 0 & I \\ -I & 0 \end{pmatrix}$ .

Pf: ~~pick~~ Pick  $e \neq 0$ .  $\nexists \Omega(e, e) = 0$ .  $\exists f$   
 such that  $\Omega(e, f) = 1$ ; otherwise  $\Omega(e, \cdot) = 0 \forall$ .

$$\Rightarrow e = 0, \quad e = e_1, \quad f = f_1$$

$$V^1 := \{v \in V : \Omega(e, v) = \Omega(f, v) = 0\}$$

claim:  $\Omega|_{V^1}$  is symplectic nondegenerate  
 clear.

Continue with  $e_1 f_1 e_2 f_2 \dots e_n f_n$

$\Rightarrow \dim V$  is even. Order the basis  $\{e_1 \dots e_n f_1 \dots f_n\}$

$$\Omega \leftrightarrow J = \begin{pmatrix} 0 & I \\ -I & 0 \end{pmatrix}.$$

$$Sp(n, \mathbb{C}) \simeq \{g \in GL(2n, \mathbb{C}) : g^T J g = J\}.$$

$$sp(n, \mathbb{C}) \simeq \{X \in gl(2n, \mathbb{C}) : g^T J + J g = 0\}.$$

Exercise:  $Sp(n, \mathbb{C})$  is path connected.

$$g \in Sp(n, \mathbb{C}) \Rightarrow g^T \in Sp(n, \mathbb{C})$$

$$\bar{g} \in Sp(n, \mathbb{C})$$

$$J g^T J = -g^{-1}.$$

$$Sp(n) := Sp(2n, \mathbb{C}) \cap U(2n) = \{g \in Sp(2n, \mathbb{C}) : g^* g = I \text{ and } g^T J g = J\}$$

Exercise:  $g \in Sp(2n, \mathbb{C}) \Rightarrow \det g = 1$

Follows from  $(\det g)^2 = 1$  and path connected.

n=1:  $Sp(1) \begin{pmatrix} a & b \\ c & d \end{pmatrix}$   ~~$\begin{pmatrix} \alpha & \beta \\ -\bar{\beta} & \bar{\alpha} \end{pmatrix}$~~

~~$\begin{pmatrix} \alpha & \beta \\ \beta & \alpha \end{pmatrix}$~~   ~~$\begin{pmatrix} a^* & c^* \\ b^* & d^* \end{pmatrix}$~~   $\begin{pmatrix} a & c \\ b & d \end{pmatrix} \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix} \begin{pmatrix} a & b \\ c & d \end{pmatrix} = \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix}$

$Sp(1) = SU(2) \simeq \mathbb{C} \times \mathbb{C}^*$   $\begin{pmatrix} -c & a \\ -d & b \end{pmatrix} \cdot \begin{pmatrix} a & b \\ c & d \end{pmatrix} = \begin{pmatrix} 0 & ad-bc \\ ad+bc & 0 \end{pmatrix}$

Adh unless  $Sp(n)$  is different

Want to know:

(1) what are the connected compact gps?

(2) When do Lie algebra homomorphisms exponentiate?

DEF:  $\mathfrak{g}$  is called simple if it has no nontrivial ideals

$G$  Compact  $\implies \mathcal{L}(G)$  has a positive/negative definite invariant inner product

Pf: integrate over  $G$ .

$$(\text{Ad}_g X, \text{Ad}_g Y) = (X, Y)$$

For a matrix group  $\text{Ad}_g X := gXg^{-1}$ .

$\mathcal{L}(2, \mathbb{R})$  does not admit such an object

$$(gXg^{-1}, gYg^{-1}) = (X, Y)$$

$$\iff ([Z, X], Y) + (X, [Z, Y]) = 0$$

$$([H, E], E) + (E, [H, E]) = 0 \iff (E, E) = 0$$

$\text{su}(2)$  is different.

Symplectic Groups:

$$\Omega/\mathbb{C} \text{ or } \mathbb{R} \quad \Omega(x, y) = -\Omega(y, x) \neq$$

$\Omega$  nondegenerate.  $\Omega(x, y) = 0 \forall y \Rightarrow x = 0$

In coordinates:  $(x, y) := \sum x_i y_i$

$\Omega(x, y) = (Jx, y)$  with  $J^T = -J$  nondegenerate

Change of basis  $y \rightarrow M^T y M$

Prop:  $\exists$  basis  $\exists J = \begin{pmatrix} 0 & I \\ -I & 0 \end{pmatrix}$

Pf: ...

$$Sp(2n, \mathbb{F}) = \left\{ g \in GL(2n, \mathbb{F}) : g^T \cdot J \cdot g = J \right\}$$

Exercise:  $\det g = 1$  &  $Sp(2n, \mathbb{F})$  is connected

$n=1$ :  $Sp(2) \cong SL(2, \mathbb{C})$ .

$$Q^x = \left\{ x_0 + ix_1 + jx_2 + kx_3 : \sum x_i^2 = 1 \right\} \cong SU(2)$$

$$x_0 + ix_1 + jx_2 + kx_3 \Leftrightarrow \begin{pmatrix} x_0 + ix_1 & x_2 + ix_3 \\ -x_2 + ix_3 & x_0 - ix_1 \end{pmatrix}$$



Real Forms:  $\sigma: \mathfrak{g} \rightarrow \mathfrak{g} \ni$

$$(1) \sigma([X, Y]) = [\sigma(X), \sigma(Y)]$$

$$(2) \sigma(X + Y) = \sigma(X) + \sigma(Y)$$

$$(3) \sigma(\alpha X) = \bar{\alpha} X$$

$$(4) \sigma^2 = \text{Id} \text{ \& } \sigma \text{ is 1-1.}$$

Lemma:  $\mathfrak{g}^\sigma := \{X \in \mathfrak{g} : \sigma(X) = X\}$  is a real

Lie algebra &  $\mathfrak{g}^\sigma + \sqrt{-1} \mathfrak{g}^\sigma = \mathfrak{g}$ .

Examples:  $\mathfrak{g} = \text{Sp}(2n, \mathbb{C})$ .

$$(1) \sigma(X) = \bar{X} \quad \mathfrak{g}^\sigma = \text{Sp}(2n, \mathbb{R}).$$

$$(2) \sigma(X) = -\bar{X}^T \quad \mathfrak{g}^\sigma = \text{Sp}(n)$$

The corresponding group is compact.

NOTE:  $-\bar{X}^T = J \bar{X} J^{-1}$  because

$$J X^T = -X J \quad J^{-1} = -J$$

FOR THE GROUPS  $-$  makes sense.

4-19-3

The other classical Lie/matrix groups are similar:

$$\mathfrak{gl}(n, \mathbb{C}) \quad \sigma(X) = \bar{X} \text{ gives } \mathfrak{gl}(n, \mathbb{R})$$

$$\sigma(X) = -\bar{X}^T \text{ gives } \mathfrak{u}(n).$$

Same for  $\mathfrak{sl}(n, \mathbb{C})$

$$\mathfrak{so}(n, \mathbb{C}) \quad \sigma(X) = J \bar{X} J^{-1} \quad \left. \begin{array}{l} J^T = J \\ J^2 = I \end{array} \right\}$$

$$J = \left( \begin{array}{c|c} P & Q \\ \hline I & -I \end{array} \right) \begin{array}{l} P \\ Q \end{array}$$

Example:  $J = \begin{pmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \\ 1 & 0 & 0 \end{pmatrix}$

$\mathfrak{so}(2, 1)$

Classification: Killing Cartan ...  $A, B, C, D, E, F, G$   
6, 7, 8, 4 2

Find all "real" forms up to conjugacy.

Example  $\mathfrak{gl}(2n, \mathbb{C}) \quad \sigma(X) = J \bar{X} J^{-1} \text{ u}^*(2n)$

$$\sigma(X) = J_{P, Q} X^* J_{P, Q} \text{ gives } \mathfrak{su}(P, Q).$$

EXAMPLE:  $G = SL(2, \mathbb{R})$

Proposition: Every  $g \in G$  can be written uniquely  $g = r(\theta) \cdot e^X$  where  $X = X^T$  &  $\text{tr} X = 0$

(POLAR DECOMPOSITION)

Pf:  $g^T g \in SL(2, \mathbb{R})$  is symmetric positive definite.  $\exists x \in SL(2, \mathbb{R}) \Rightarrow$

$x (g^T g) x^{-1}$  is diagonal  $\begin{pmatrix} \alpha & 0 \\ 0 & \alpha^{-1} \end{pmatrix}$   $\alpha > 0$

Let  $\delta = x^{-1} \begin{pmatrix} \alpha^{1/2} & 0 \\ 0 & \alpha^{-1/2} \end{pmatrix} x$ . Then  $\delta = e^X$  as

"prescribed," and  $\delta^2 = g^T g$ .

Look at  $g \delta^{-1}$   $(g \delta^{-1})(g \delta^{-1})^T = g \delta^{-2} g^T =$

$= g g^{-1} g^T g^T = I$ . So  $g \delta^{-1} = r(\theta)$  and

$g = r \delta = r e^X$ .

Unique:  ~~$r(\theta) \delta = r(\theta_1) \delta_1 = r(\theta_2) \delta_2 \Rightarrow r(\theta) \delta_1 = r(\theta_1) \delta_2$~~

$g = r(\theta) \delta \Rightarrow \delta^2 = g^T g \Rightarrow$  only one such  $\delta$

Corollary:  $SL(2, \mathbb{R})$  is homotopic to  $SO(2)$

$$SO(2) = \{ r(\theta) : \theta \in \mathbb{R} \}$$

What is  $SL(2, \mathbb{R})$ ?

Recall  $g = \begin{pmatrix} a & b \\ c & d \end{pmatrix} \in SL(2, \mathbb{R})$  acts on

$$\mathcal{H} = \{ z \in \mathbb{C} : \text{Im } z > 0 \}$$

$$g \cdot z = \frac{az+b}{cz+d} \quad \text{Im}(gz) = \frac{\text{Im } z}{|cz+d|^2}$$

Define  $j(g, z) = cz+d$ . Then

$$j(g_1 g_2, z) = j(g_1, g_2 z) \cdot j(g_2, z).$$

(called a cocycle)

$$SL(2, \mathbb{R}) = \{ (g, \varphi_g(z)) : e^{\varphi_g(z)} = j(g, z) \}$$

$$\varphi_g : \mathcal{H} \rightarrow \mathbb{C} \quad \text{ex analytic}$$

## Oscillator Representation

$\Delta(\mathbb{R})$  Schwartz space

$$\Omega : \mathfrak{sl}(2) \rightarrow \text{End}(\Delta(\mathbb{R}))$$

$$\Omega(H) = x \partial_x + \frac{1}{2}$$

$$\Omega(E) = \frac{i}{2} m x^2$$

$$\Omega(F) = \frac{i}{2} \partial_x^2$$

THM: This rep'n exponentiates to a unitary rep'n of  $\widetilde{SL}(2, \mathbb{R})$  on  $L^2(\mathbb{R})$

$$\Omega(e^{tH}) f(x) = e^{t/2} f(e^t x)$$

$$\Omega(e^{tE}) f(x) = e^{itx^2/2} f(x)$$

$$\Omega(e^{tF}) f(x) = \text{convolution with } \frac{1+i}{2} \frac{1}{\sqrt{|t|}}$$

$$\Omega(k)$$

$$e^{-ix^2/2t}$$

~~$$\Omega(F-E) = \frac{1}{2} (x^2 - \partial_x^2)$$~~

$$2i \Omega(F-E) = x^2 - \partial_x^2$$

$$2\Omega(k)$$

$$k = 2i(F-E)$$

Basis of Eigenvectors for  $\Omega(k)$ .

$$a = x + \frac{d}{dx} \quad a^\dagger = x - \frac{d}{dx}$$

$$(a^\dagger)^* = a \text{ via } (f, g) := \int_{\mathbb{R}} f(x) \overline{g(x)} dx$$

$$[a, a^\dagger] = 2$$

$$[a, (a^\dagger)^j] = 2j (a^\dagger)^{j-1}$$

$$v_0 := e^{-\frac{x^2}{2}} \quad a v_0 = 0$$

$$v_j = (a^\dagger)^j v_0 \quad \text{then}$$

$$a v_j = 2j v_{j-1}$$

$$(v_j, v_l) = 2^l l! \delta_{jl} (v_0, v_0) = 2^l l! \sqrt{\pi} \delta_{jl}$$

$$v_j = P_j(x) e^{-\frac{x^2}{2}}$$

where  $P_j$  is a polynomial

$$(-1)^j e^{x^2} \left( \frac{d}{dx} \right)^j (e^{-x^2})$$

Hermite functions  
form an o.n. basis  
of  $L^2(\mathbb{R})$ .

4-28-3

$$x \text{ (means } m_x) = \frac{1}{2}(a+a^\dagger)$$

$$p_x = \frac{1}{2i}(a-a^\dagger)$$

$$\Omega(E, F) = \frac{1}{8}(a \pm a^\dagger)^2$$

$$\Omega(k) = i\Omega(\overbrace{F-E}^{F-E}) = \frac{1}{4}(aa^\dagger + a^\dagger a)$$

$$\Omega(E) = \frac{1}{8}(a+a^\dagger)^2$$

$$\Omega(F) = \frac{1}{8}(a-a^\dagger)^2$$

$$a \quad x = \frac{1}{2}(a+a^\dagger)$$

$$p_x = \frac{1}{2i}(a-a^\dagger)$$

$$[i(E-F), iH + (E+F)]$$

~~$$\begin{pmatrix} 0 & i \\ -i & 0 \end{pmatrix} \begin{bmatrix} x \\ y \end{bmatrix}$$~~

$$-[E-F, H] + i[E-F, E+F]$$

$$-(-2E + 2F) + i[+H + H] = 2iH + 2(E+F)$$

$$[i(E-F), iH - (E+F)] = 2(E+F) - 2iH$$

$$\{ iH + (E+F), i(E-F), iH - (E+F) \}$$

is another standard  $\mathcal{O}(2, \mathbb{R})$ .

$$\begin{pmatrix} 0 & -i \\ -i & 0 \end{pmatrix}, \begin{pmatrix} i & 1 \\ 1 & -i \end{pmatrix}, \begin{pmatrix} i & -1 \\ 1 & -i \end{pmatrix}$$



$h$



$f$



$e$



$$(g_1, \varphi_{g_1}) \cdot (g_2, \varphi_{g_2}) = (g_1 g_2, \varphi_{g_1}(g_2 z) \cdot \varphi_{g_2})$$

$$e^{\varphi_{g_1}(g_2 z)} \cdot e^{\varphi_{g_2}(z)} = j(g_1, g_2 z) \cdot j(g_2, z)$$
$$= j(g_1 g_2, z).$$

## Covers of orthogonal groups

EXAMPLE 1:  $G = SO(4, \mathbb{C})$

Let  $\mathbb{C}^4 \cong \begin{bmatrix} x_1 & x_2 \\ x_3 & x_4 \end{bmatrix}$  as on the Exam

There is a nondegenerate bilinear form

$$(X, Y) := \text{tr}(X Y Y^T Y) \quad \text{where } Y = \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix}.$$

$$Y Y^T Y = \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix} \begin{pmatrix} y_1 & y_3 \\ y_2 & y_4 \end{pmatrix} \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix} = \begin{pmatrix} -y_4 & y_2 \\ y_3 & -y_1 \end{pmatrix}$$

$$\text{So } (X, Y) = (-x_1 y_4 + x_2 y_3 + x_3 y_2 - x_4 y_1)$$

$$(X, Y) \longleftrightarrow \begin{pmatrix} 0 & 0 & 0 & -1 \\ 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 \\ -1 & 0 & 0 & 0 \end{pmatrix}.$$

$SL(2, \mathbb{C}) \times SL(2, \mathbb{C})$  acts on  $\mathbb{C}^4$  preserving  $(,)$ .

So there is a map  $\Psi: SL(2, \mathbb{C}) \times SL(2, \mathbb{C}) \rightarrow O(4, \mathbb{C})$

By continuity, it maps to  $SO(4, \mathbb{C})$

$$(g_1, g_2) \cdot X := g_1 X g_2^T$$

WE NEED:  $g^T Y g = Y \iff Y g = (g^T)^{-1} Y, Y g^T = g^{-1} Y$

CHECK:  $\text{tr}(g_1 X g_2^T \cdot J \cdot (g_1 Y g_2^T)^T \cdot Y) =$   
 $= \text{tr}(g_1 X g_2^T \cdot J \cdot g_2 \cdot Y^T \cdot g_1^T \cdot Y) = \text{tr}(g_1 X Y Y^T g_1^T J)$   
 $= \text{tr}(X \cdot J \cdot Y^T \cdot g_1^T \cdot Y \cdot g_1) = \text{tr}(X \cdot J \cdot Y^T \cdot J)$

FACT:  $\begin{pmatrix} 0 & 0 & 0 & -1 \\ 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 \\ -1 & 0 & 0 & 0 \end{pmatrix} \sim \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$  as bilinear forms

$$\begin{pmatrix} \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \\ -\frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \end{pmatrix} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} \frac{1}{\sqrt{2}} & -\frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \quad \square$$

Also  $\sim \begin{pmatrix} 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \end{pmatrix} \cdot \begin{pmatrix} A & B \\ \hline C & -A^T \end{pmatrix}$   $B + B^T = 0$   
 $C + C^T = 0$

### Lie Algebra

$$\dim \mathfrak{so}(4, \mathbb{C}) = 6 = \dim \mathfrak{sl}(2, \mathbb{C}) + \dim \mathfrak{sl}(2, \mathbb{C})$$

FACTS: • kernel of  $\Psi$  is  $\pm(I, I)$ .  
 • map is onto

Compute the differential at  $(I, I)$  and use the fact that a connected group is generated by a neighborhood of the identity.

EXAMPLE 2: Specialize to the real form  $SO(3,1)$ .

$$\begin{pmatrix} t+x & y+iz \\ y-iz & t-x \end{pmatrix} \simeq \mathbb{R}^4 \subseteq \mathbb{C}^4$$

These are the hermitian matrices.

$$\langle X, Y \rangle := \text{tr}(X \cdot J \cdot Y^* \cdot J)$$

$$\text{tr} \begin{pmatrix} t_1+x_1 & y_1+iz_1 \\ y_1-iz_1 & t_1-x_1 \end{pmatrix} \cdot \begin{pmatrix} -t_2+x_2 & y_2+iz_2 \\ y_2-iz_2 & -t_2-x_2 \end{pmatrix} =$$

$$= (t_1+x_1)(-t_2+x_2) + i(y_1+iz_1)(y_2-iz_2) \\ + (t_1-x_1)(-t_2-x_2) + (y_1-iz_1)(y_2+iz_2)$$

Set  $X=Y$ :  $-2t^2 + 2x_1^2 + 2y^2 + 2z^2$

The orthogonal group is  $O(1,3)$

$$\text{Let } SL(2, \mathbb{C}) \hookrightarrow SL(2, \mathbb{C}) \times SL(2, \mathbb{C})$$

$$g \longmapsto (g, \bar{g})$$

$$\text{If } X^* = X, \text{ then } (g, \bar{g}) \cdot X = g X g^*$$

$$\text{So } (g X g^*)^* = g X^* g^* = g X g^* \text{ preserves } \mathbb{R}^4$$

Get a map  $\psi: SL(2, \mathbb{C}) \longrightarrow O(1,3)$ .

FROM EARLIER, IMAGE IS IN  $SO(1,3)$ . 5-5-4

Image is connected;  $\Psi(SL(2, \mathbb{C})) = SO(1,3)_0$ .

### Topology of $SO(1,3)$ :

Cartan decomposition: Any  $g \in SO(1,3)$

can be written uniquely as  $g = u \cdot h$  where

$u \in S[O(1) \times O(3)]$ ,  $h = e^H$  with  $H \in SO(3,1)$  symmetric

"Pf"  $g \in SO(1,3) \implies g^T \in SO(1,3)$ .

$g^T g = A$  as in the proof of the polar decomposition.

NEED:  $A \in SO(1,3)$  symmetric

$$A \cdot I_{1,3} \cdot A = I_{1,3} \stackrel{???}{\implies} \exists h \in SO(1,3) \ni h^2 = A.$$

If  $A \cdot I_{1,3} \cdot A = I_{1,3}$  then  $p(A) \cdot I_{1,3} \cdot p(A) = I_{1,3}$

for any polynomial  $p(t)$ .

$x \cdot A \cdot x^{-1} = \text{diag}(\lambda_1, \lambda_2, \lambda_3, \lambda_4)$  with  $\lambda_j > 0$ .

$\exists p_n(t) \rightarrow \sqrt{t}$  uniformly on an interval

containing  $\lambda_j$ .  $p_n(A) \rightarrow h' \ni h'^2 = A$ .

$p_n(x^{-1} h' x) \rightarrow x^{-1} h' x := h$  such that  $h^2 = A$

$\therefore h \in SO(1,3)$ .