

Math 2940: Homework 7 Solutions

6.1

14. Since $\mathbf{u} = \begin{bmatrix} 0 \\ -5 \\ 2 \end{bmatrix}$ and $\mathbf{z} = \begin{bmatrix} -4 \\ -1 \\ 8 \end{bmatrix}$, $\|\mathbf{u} - \mathbf{z}\|^2 = [0 - (-4)]^2 + [-5 - (-1)]^2 + [2 - 8]^2 = 68$ and
 $\text{dist}(\mathbf{u}, \mathbf{z}) = \sqrt{68} = 2\sqrt{17}$.

28. An arbitrary \mathbf{w} in $\text{Span}\{\mathbf{u}, \mathbf{v}\}$ has the form $\mathbf{w} = c_1\mathbf{u} + c_2\mathbf{v}$. If \mathbf{y} is orthogonal to \mathbf{u} and \mathbf{v} , then $\mathbf{u} \cdot \mathbf{y} = \mathbf{v} \cdot \mathbf{y} = 0$. By Theorem 1(b) and 1(c),

$$\mathbf{w} \cdot \mathbf{y} = (c_1\mathbf{u} + c_2\mathbf{v}) \cdot \mathbf{y} = c_1(\mathbf{u} \cdot \mathbf{y}) + c_2(\mathbf{v} \cdot \mathbf{y}) = 0 + 0 = 0$$

30. a. If \mathbf{z} is in \mathcal{W}^\perp , \mathbf{u} is in \mathcal{W} , and c is any scalar, then $(c\mathbf{z}) \cdot \mathbf{u} = c(\mathbf{z} \cdot \mathbf{u}) = c \cdot 0 = 0$. Since \mathbf{u} is any element of \mathcal{W} , $c\mathbf{z}$ is in \mathcal{W}^\perp .
- b. Let \mathbf{z}_1 and \mathbf{z}_2 be in \mathcal{W}^\perp . Then for any \mathbf{u} in \mathcal{W} , $(\mathbf{z}_1 + \mathbf{z}_2) \cdot \mathbf{u} = \mathbf{z}_1 \cdot \mathbf{u} + \mathbf{z}_2 \cdot \mathbf{u} = 0 + 0 = 0$. Thus $\mathbf{z}_1 + \mathbf{z}_2$ is in \mathcal{W}^\perp .
- c. Since $\mathbf{0}$ is orthogonal to every vector, $\mathbf{0}$ is in \mathcal{W}^\perp . Thus \mathcal{W}^\perp is a subspace.

6.2

10. Since $\mathbf{u}_1 \cdot \mathbf{u}_2 = \mathbf{u}_1 \cdot \mathbf{u}_3 = \mathbf{u}_2 \cdot \mathbf{u}_3 = 0$, $\{\mathbf{u}_1, \mathbf{u}_2, \mathbf{u}_3\}$ is an orthogonal set. Since the vectors are non-zero, \mathbf{u}_1 , \mathbf{u}_2 , and \mathbf{u}_3 are linearly independent by Theorem 4. Three such vectors in \mathbb{R}^3 automatically form a basis for \mathbb{R}^3 . So $\{\mathbf{u}_1, \mathbf{u}_2, \mathbf{u}_3\}$ is an orthogonal basis for \mathbb{R}^3 . By Theorem 5,

$$\mathbf{x} = \frac{\mathbf{x} \cdot \mathbf{u}_1}{\mathbf{u}_1 \cdot \mathbf{u}_1} \mathbf{u}_1 + \frac{\mathbf{x} \cdot \mathbf{u}_2}{\mathbf{u}_2 \cdot \mathbf{u}_2} \mathbf{u}_2 + \frac{\mathbf{x} \cdot \mathbf{u}_3}{\mathbf{u}_3 \cdot \mathbf{u}_3} \mathbf{u}_3 = \frac{4}{3} \mathbf{u}_1 + \frac{1}{3} \mathbf{u}_2 + \frac{1}{3} \mathbf{u}_3$$

28. If U is an $n \times n$ orthogonal matrix, then $I = UU^{-1} = UU^T$. Since U is the transpose of U^T , Theorem 6 applied to U^T says that U^T has orthogonal columns. In particular, the columns of U^T are linearly independent and hence form a basis for \mathbb{R}^n by the Invertible Matrix Theorem. That is, the rows of U form a basis (an orthonormal basis) for \mathbb{R}^n .

6.3

10. Since $\mathbf{u}_1 \cdot \mathbf{u}_2 = \mathbf{u}_1 \cdot \mathbf{u}_3 = \mathbf{u}_2 \cdot \mathbf{u}_3 = 0$, $\{\mathbf{u}_1, \mathbf{u}_2, \mathbf{u}_3\}$ is an orthogonal set. By the Orthogonal Decomposition Theorem,

$$\hat{\mathbf{y}} = \frac{\mathbf{y} \cdot \mathbf{u}_1}{\mathbf{u}_1 \cdot \mathbf{u}_1} \mathbf{u}_1 + \frac{\mathbf{y} \cdot \mathbf{u}_2}{\mathbf{u}_2 \cdot \mathbf{u}_2} \mathbf{u}_2 + \frac{\mathbf{y} \cdot \mathbf{u}_3}{\mathbf{u}_3 \cdot \mathbf{u}_3} \mathbf{u}_3 = \frac{1}{3} \mathbf{u}_1 + \frac{14}{3} \mathbf{u}_2 - \frac{5}{3} \mathbf{u}_3 = \begin{bmatrix} 5 \\ 2 \\ 3 \\ 6 \end{bmatrix}, \mathbf{z} = \mathbf{y} - \hat{\mathbf{y}} = \begin{bmatrix} -2 \\ 2 \\ 2 \\ 0 \end{bmatrix} \text{ and } \mathbf{y} = \hat{\mathbf{y}} + \mathbf{z},$$

where $\hat{\mathbf{y}}$ is in \mathcal{W} and \mathbf{z} is in \mathcal{W}^\perp .

Note: Exercise 6.3.12 was not assigned, but it is an intermediate step in exercise 6.3.16.

12. Note that \mathbf{v}_1 and \mathbf{v}_2 are orthogonal. The Best Approximation Theorem says that $\hat{\mathbf{y}}$, which is the orthogonal projection of \mathbf{y} onto $\mathcal{W} = \text{Span}\{\mathbf{v}_1, \mathbf{v}_2\}$, is the closest point to \mathbf{y} in \mathcal{W} . This vector is

$$\hat{\mathbf{y}} = \frac{\mathbf{y} \cdot \mathbf{v}_1}{\mathbf{v}_1 \cdot \mathbf{v}_1} \mathbf{v}_1 + \frac{\mathbf{y} \cdot \mathbf{v}_2}{\mathbf{v}_2 \cdot \mathbf{v}_2} \mathbf{v}_2 = 3\mathbf{v}_1 + 1\mathbf{v}_2 = \begin{bmatrix} -1 \\ -5 \\ -3 \\ 9 \end{bmatrix}.$$

16. The distance from the point \mathbf{y} in \mathbb{R}^4 to a subspace \mathcal{W} is defined as the distance from \mathbf{y} to the closest point in \mathcal{W} . Since the closest point in \mathcal{W} to \mathbf{y} is $\hat{\mathbf{y}} = \text{proj}_{\mathcal{W}} \mathbf{y}$, the desired distance is $\|\mathbf{y} - \hat{\mathbf{y}}\|$. One

computes that $\hat{\mathbf{y}} = \begin{bmatrix} -1 \\ -5 \\ -3 \\ 9 \end{bmatrix}$, $\mathbf{y} - \hat{\mathbf{y}} = \begin{bmatrix} 4 \\ 4 \\ 4 \\ 4 \end{bmatrix}$, and $\|\mathbf{y} - \hat{\mathbf{y}}\| = 8$.

6.4

2. Set $\mathbf{v}_1 = \mathbf{x}_1$ and compute that $\mathbf{v}_2 = \mathbf{x}_2 - \frac{\mathbf{x}_2 \cdot \mathbf{v}_1}{\mathbf{v}_1 \cdot \mathbf{v}_1} \mathbf{v}_1 = \mathbf{x}_2 - \frac{1}{2} \mathbf{v}_1 = \begin{bmatrix} 5 \\ 4 \\ -8 \end{bmatrix}$. Thus an orthogonal basis for \mathcal{W}

$$\text{is } \left\{ \begin{bmatrix} 0 \\ 4 \\ 2 \end{bmatrix}, \begin{bmatrix} 5 \\ 4 \\ -8 \end{bmatrix} \right\}.$$