#### Mathematics of Dancing

# What is Symmetry?







#### Types of Symmetries: Translational



#### Types of Symmetries: *Reflectional*



#### Types of Symmetries: Rotational



#### Types of Symmetries: *Glide Reflectional*



#### Types of Symmetries: *Glide Reflectional*





Translational (T)









2nd <sup>2nd2nd</sup> TTM MNA RRG GG



2nd 2nd 2nd 2nd 2nd TNTMN NR RERGGG



Translational (T)



Reflectional (M)



Rotational (R)



Glide Reflectional (G)

#### Compositions of Dance Symmetries



#### Compositions of Dance Symmetries



#### **Activity:** Fill in the Composition Table



#### Fill in the Composition Table

2nd 1st	Т	Μ	R	G
Т				
Μ				
R				
G				



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2nd 1st	Т	Μ	R	G
Т				
Μ			G	
R				
G				



#### Fill in the Composition Table

2nd 1st	Т	Μ	R	G
Τ	Τ	Μ	R	G
Μ	Μ	Τ	G	R
R	R	G	Τ	Μ
G	G	R	Μ	Т



2nd 1st	Т	Μ	R	G
Τ	Τ	Μ	R	G
Μ	Μ	Τ	G	R
R	R	G	Т	Μ
G	G	R	Μ	Т



2nd 1st	Т	Μ	R	G
Т	Τ	Μ	R	G
Μ	Μ	Τ	G	R
R	R	G	Т	Μ
G	G	R	Μ	Τ

(1) The operation  $\bullet$  takes elements of *G* to other elements of *G*. (If *x* and *y* are in *G*, so is  $x \bullet y$ .)



2nd 1st	Т	Μ	R	G
Τ	Т	Μ	R	G
Μ	Μ	Τ	G	R
R	R	G	Т	Μ
G	G	R	Μ	Т

(2) **Identity:** There is a special element *e* in *G* (called the *identity*) such that for every *x* in  $G, e \bullet x = x \bullet e = x$ .



2nd 1st	Т	Μ	R	G
Τ	Τ	Μ	R	G
Μ	Μ	Τ	G	R
R	R	G	Т	Μ
G	G	R	Μ	Τ

(3) **Inverses:** every x in G has an *inverse*, an element y in G for which  $x \bullet y = y \bullet x = e$ .



2nd 1st	Т	Μ	R	G
Τ	Т	Μ	R	G
Μ	Μ	Τ	G	R
R	R	G	Т	Μ
G	G	R	Μ	Т

(4) **Associativity**: for all *x*, *y*, and *z* in *G*,  $(x \bullet y) \bullet z = x \bullet (y \bullet z)$ .

# What is a group?

A **group** is a *set G* together with an *operation* "•" that satisfies four properties.

- (1) The operation  $\bullet$  takes elements of *G* to other elements of *G*. (If *x* and *y* are in *G*, so is  $x \bullet y$ .)
- (2) **Identity:** There is a special element *e* in *G* (called the *identity*) such that for every *x* in *G*,  $e \bullet x = x \bullet e = x$ .
- (3) **Inverses:** every x in G has an *inverse*, an element y in G for which  $x \bullet y = y \bullet x = e$ .

(4) **Associativity**: for all *x*, *y*, and *z* in *G*,  $(x \bullet y) \bullet z = x \bullet (y \bullet z)$ .

Let Z denote the set of integers:

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$$Z = \{ \dots, -3, -2, -1, 0, 1, 2, 3, \dots \}.$$

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(b) **Identity:** the number 0 is the identity: 0 + n = n + 0 = n for any *n*.

Let Z denote the set of integers:

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Then Z is a group with operation "+".

(a) The sum of two integers is an integer.

- (b) **Identity:** the number 0 is the identity: 0 + n = n + 0 = n for any *n*.
- (c) **Inverses:** the inverse of an integer *n* is *-n*.

#### Mattress Flipping Problem

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# Mattress Flipping Problem

**Goal:** Find an "move" that we can do to a mattress to move it through every possible position.



#### Mattress Moves



Translational

Reative tive type

Glide Refletional

#### Fill in the Mattress Move Table

2nd 1st	Ι	R	Ρ	Y
I				
R				
Р				
Y				

Translational

Reation to ready a

Glide Refletional

#### Fill in the Mattress Move Table

2nd 1st	I	R	Р	Y
I	I	R	Ρ	Y
R	R	I	Y	Ρ
Р	Ρ	Y	I	R
Y	Y	Р	R	I

Translational

Reation to the top at the second seco

Glide Refletional

#### Fill in the Mattress Move Table

2nd 1st	Ι	R	Ρ	Y
Ι	I	R	Ρ	Y
R	R	I	Y	Ρ
Ρ	Ρ	Y	I	R
Y	Y	Ρ	R	I

So why can't we apply a single move to put the mattress into all possible positions?

### What's the Difference?

# Translational Wheeler and t'S Rotational Official terms of the set of the set

#### Line Dancing Moves

2nd 1st	Т	Μ	R	G
Т	Т	Μ	R	G
Μ	Μ	Т	G	R
R	R	G	Т	Μ
G	G	R	Μ	Т



#### Line Dancing Moves

2nd 1st	Т	Μ	R	G
Т	Т	Μ	R	G
Μ	Μ	Т	G	R
R	R	G	Т	М
G	G	R	М	Т

#### Mattress Flipping Moves

2nd 1st	I	R	Р	Y
I	I	R	Ρ	Y
R	R	I	Y	Р
Р	Ρ	Y	I	R
Y	Y	Р	R	I



#### Line Dancing Moves

#### Mattress Flipping Moves

2nd 1st	Т	Μ	R	G
Т	Т	Μ	R	G
Μ	М	Т	G	R
R	R	G	Т	М
G	G	R	Μ	Т

2nd 1st	I	R	Ρ	Y
I	Ι	R	Ρ	Y
R	R	I	Y	Р
Р	Ρ	Y	I	R
Y	Y	Р	R	I

 $\{T,M,R,G\}$  and  $\{I,R,P,Y\}$  are **isomorphic** groups.

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- Groups arise from "real life" as well as from pure mathematics (like the integers *Z*).
- Different objects can have the same (isomorphic!) groups of symmetries
- Studying the group of symmetries of an object can help to obtain non-obvious properties of this object. (Like the impossibility of constructing a simple mattress flipping schedule.)

Thank you!

#### **For More Information**

Here is the link to a book about the mathematics of dancing: <u>https://www.artofmathematics.org/books/dance</u>

Here is a link to lecture notes by P. Etingof, which is a fantastic introduction to group theory:

http://www-math.mit.edu/~etingof/groups.pdf