A convexity theorem for the real part of a Borel invariant subvariety

Timothy Goldberg Cornell University

goldberg@math.cornell.edu www.math.cornell.edu/~goldberg

Joint Mathematics Meetings Monday, January 5, 2009 "A convexity theorem for the real part of a Borel invariant subvariety"

To appear in *Proceedings of the AMS*, April 2009.

Suppose:

 (M, ω) is a compact and connected Kähler manifold, and $[\omega]$ is an *integral* cohomology class.

Then:

- $\bullet \ \exists$ holomorphic line bundle $L \to M$ with Chern class $[\omega].$
- \exists Hermitian metric on L with compatible connection ∇ whose curvature is $\frac{1}{2\pi i} \omega$.
- M is a complex projective variety (Kodaira Embedding Theorem).

Suppose also:

G is a compact and connected Lie group with complexification $G_{\mathbb{C}},$ and

$$G, G_{\mathbb{C}} \circlearrowleft (M, L)$$

by holomorphic bundle automorphisms, preserving ω and $\nabla.$

Then:

- These actions are *algebraic* (Serre's GAGA).
- ∃ canonical G-equivariant *moment map*

$$\Phi: M \to \mathfrak{g}^*$$
,

so $G \circlearrowright (M, \omega)$ is a *Hamiltonian action* — (Kostant).

Choose in a compatible way:

 $T \subset G$ maximal torus

 $\mathfrak{t}_+^* \subset \mathfrak{t}^*$ closed positive Weyl chamber

 $\Lambda \subset \mathfrak{t}^*$ weight lattice

 $\Lambda_{\mathbb{Q}} \subset \mathfrak{t}^*$ rational points, $\Lambda_{\mathbb{Q}} := \Lambda \otimes_{\mathbb{Z}} \mathbb{Q}$

 $B\subset G_{\mathbb C}$ Borel subgroup corresponding to $\mathfrak t_+^*$

Example:

$$\begin{split} G &= \textbf{SU}(n), \\ G_{\mathbb{C}} &= \textbf{GL}(n;\mathbb{C}), \\ T &= \{ \text{diagonal elements of } G \}, \\ B &= \{ \text{upper triangular elements of } G_{\mathbb{C}} \} \end{split}$$

For each $r\geq 0,$ let $\Gamma(M,L^{\otimes r})=$ holomorphic global sections of $L^{\otimes r}\to M.$

$$\begin{array}{ll} G \circlearrowleft (M,L) & \Rightarrow & G \circlearrowleft (M,L^{\otimes r}), \, \forall r \geq 0 \\ \\ \Rightarrow & G \circlearrowleft \Gamma(M,L^{\otimes r}), \, \forall r \geq 0. \end{array}$$

So:

Each $\Gamma(M, L^{\otimes r})$ is a finite-dimensional G-representation space, and has a *weight space decomposition*

$$\Gamma(M,L^{\otimes r}) = \bigoplus_{\lambda \in \Lambda} \Gamma(M,L^{\otimes r})_{\lambda}.$$

Definition:

Let $A \subset M$. The *highest weight space* C(A) of A consists of $\lambda \in \Lambda_{\mathbb{Q}}$ such that:

- $\exists r > 0$ with $r\lambda \in \Lambda_+$,
- $r\lambda$ is a highest weight for the G-representation space $\Gamma(\mathcal{M},L^{\otimes r}),$ and
- \exists an eigensection $s \in \Gamma(M, L^{\otimes r})_{r\lambda}$ with $s|_A \not\equiv 0.$

Note:

$$\mathcal{C}(A) \subset \mathfrak{t}_+^*$$
.

Fact:

Let $X \subset M$ be a closed, irreducible, and $G_{\mathbb{C}}$ -invariant subvariety. Then $\mathcal{C}(X)$ is a *convex polytope* in the \mathbb{Q} -vector space $\Lambda_{\mathbb{Q}}$.

Put
$$\Delta(X) := \Phi(X) \cap \mathfrak{t}_+^*$$
.

Theorem: (Brion, 1986)

If $X\subset M$ is a closed, irreducible, $G_{\mathbb{C}}$ -invariant subvariety, then

$$\mathfrak{C}(X) = \Delta(X) \cap \Lambda_{\mathbb{Q}} \quad \text{and} \quad \overline{\mathfrak{C}(X)} = \Delta(X).$$

Hence $\Delta(X)$ is a rational convex polytope.

Theorem: (Guillemin-Sjamaar, 2006)

Brion's theorem still holds even if X is only B-invariant.

Suppose:

- $\tau \curvearrowright M$ and $\sigma \curvearrowright G_{\mathbb{C}}$ are anti-holomorphic involutions.
- $\tau \curvearrowright (M, \omega)$ is anti-symplectic.
- σ preserves G and T.

$$\sigma \curvearrowright G \quad \rightsquigarrow \quad \sigma \curvearrowright \mathfrak{g}, \mathfrak{g}^*$$

Suppose further:

• **Distibution**: $\forall g \in G, x \in M$

$$\tau(g \cdot x) = \sigma(g) \cdot \tau(x).$$

• Anti-equivariance: $\forall x \in M$,

$$\Phi\left(\tau(x)\right) = -\sigma\left(\Phi(x)\right).$$

$$\sigma,\,\tau\qquad \Longleftrightarrow\qquad \text{``complex conjugation''}$$

$$M^{\tau},~G^{\sigma}$$
 real parts" of $M,~G.$

Observe:

$$x \in M^{\tau}$$
 \Rightarrow $\Phi(x) = \Phi(\tau(x)) = -\sigma(\Phi(x))$ \Rightarrow $\sigma(\Phi(x)) = -\Phi(x)$ \Rightarrow $\Phi(x) \in \mathfrak{g}_{-1}^*.$

Thus:

$$\Phi\left(M^{\tau}\right)\subset\mathfrak{g}_{-1}^{*}.$$

Theorem: (O'Shea-Sjamaar, 2000)

Suppose X is preserved by $G_{\mathbb{C}}$ and τ , and X^{τ} contains a smooth point. Then

$$\Delta(X^{\tau}) = \Delta(X) \cap \mathfrak{g}_{-1}^*.$$

Hence $\Delta(X^{\tau})$ is a convex polytope, because it is the intersection of the convex polytope $\Delta(X)$ (Brion's Theorem) with the linear subspace \mathfrak{g}_{-1}^* .

Main Theorem of this Paper: (G., 2008)

If $\sigma \curvearrowright G_{\mathbb{C}}$ preserves B, then the O'Shea–Sjamaar Theorem still holds even if X is only B-invariant.

Examples:

The main source of examples is the **Borel–Weil Theorem**.

If G is compact and connected, $T \subset G$ is a maximal torus, $\mathfrak{t}_+^* \subset \mathfrak{t}^*$ is a Weyl chamber, and $\lambda \in \Lambda \cap \mathfrak{t}_+^*$ is a dominant weight, then

$$M_{\lambda} := G_{\mathbb{C}}/P_{\lambda} \approx G/\operatorname{Stab}_{G}(\lambda) \approx \operatorname{Coad}_{G}(\lambda)$$

is

- a compact, connected, and integral Kähler manifold,
- a Hamiltonian G-manifold, and
- something to which we can often apply the Main Theorem.

Summary:

- Convexity theorems.
- In many cases, the real part of the moment polytope is the moment polytope of the real part.
- In the integral Kähler case, the moment polytope can be described using geometric representation theory.

THE END



Thank you for listening.