The Scaling Limit of Diaconis-Fulton Addition

Lionel Levine

August 31, 2007

Joint work with Yuval Peres

Lionel Levine (joint work with Yuval Peres) The Scaling Limit of Diaconis-Fulton Addition

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- ▶ To form A + B, let $C_0 = A \cup B$ and

$$C_j = C_{j-1} \cup \{y_j\}$$

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- Define $A + B = C_k$.
- ► Abeilan property: the law of A + B does not depend on the ordering of x₁,..., x_k.

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- More precisely, for any $\varepsilon > 0$, with probability one we have

$$B_{r(1-\varepsilon)} \subset A_{\lfloor \omega_d r^d \rfloor} \subset B_{r(1+\varepsilon)}$$

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► Here $B_r = \{x \in \mathbb{Z}^d : |x| < r\}$, and ω_d is the volume of the unit ball in \mathbb{R}^d .

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The Rotor-Router Model

Deterministic analogue of random walk.

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- ▶ Each site $x \in \mathbb{Z}^2$ has a **rotor** pointing North, South, East or West.

(Start all rotors pointing North, say.)

The Rotor-Router Model

- Deterministic analogue of random walk.
- ► Each site x ∈ Z² has a rotor pointing North, South, East or West.

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- ▶ A particle starts at the origin. At each site it comes to, it
 - 1. Turns the rotor clockwise by 90 degrees;
 - 2. Takes a step in direction of the rotor.

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Rotor-Router Aggregation

Sequence of lattice regions

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• $x_n \in \mathbb{Z}^2$ is the site at which rotor walk first leaves the region A_{n-1} .

• Makes sense in \mathbb{Z}^d for any d.



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$$B_{r-c\log r} \subset A_n \subset B_{r(1+c'r^{-1/d}\log r)},$$

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• B_{ρ} is the ball of radius ρ centered at the origin.

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- c, c' depend only on d.
- **Corollary**: Inradius/Outradius $\rightarrow 1$ as $n \rightarrow \infty$.

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- **Sandpile**: Leave the extra particles where they are.
- **Rotor**: Send extra particles according to the usual rotor rule.

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Lionel Levine (joint work with Yuval Peres) The Scaling Limit of Diaconis-Fulton Addition

Bounds for the Abelian Sandpile

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Improves the bounds of Le Borgne and Rossin.



(Disk of area n/3) $\subset S_n \subset$ (Disk of area n/2)

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- ▶ As $t \to \infty$, get a limiting region A_m of mass 1, fractional mass on ∂A_m , and zero outside.
- Theorem (L.-Peres): There are constants c and c' depending only on d, such that

$$B_{r-c} \subset A_m \subset B_{r+c'}$$

where $m = \omega_d r^d$.

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- If so, can we describe the limiting shape?
- Is it the same for all three models?
- Not clear how to define dynamics in \mathbb{R}^d .

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= mass received – mass emitted
$$= \begin{cases} -1 & x \in A \cap B \\ 0 & x \in A \cup B - A \cap B \\ 1 & x \in A \oplus B - A \cup B. \end{cases}$$

Let

$$\gamma(x) = -|x|^2 - \sum_{y \in A} g(x,y) - \sum_{y \in B} g(x,y),$$

where g is the Green's function for SRW in \mathbb{Z}^d , $d \ge 3$.

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- Let $s(x) = \inf\{\phi(x) \mid \phi \text{ superharmonic, } \phi \geq \gamma\}$.

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- Let $s(x) = \inf\{\phi(x) \mid \phi \text{ superharmonic, } \phi \geq \gamma\}$.
- **Claim**: odometer = $s \gamma$.

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$$\Delta u = m - 1_A - 1_B$$
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Since

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the sum $u + \gamma$ is superharmonic, so $u + \gamma \ge s$.

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► Reverse inequality: $s - \gamma - u$ is superharmonic on $A \oplus B$ and nonnegative outside $A \oplus B$, hence nonnegative inside as well.

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• Odometer:
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Main Result

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- Let A, B ⊂ ℝ^d be bounded open sets with ∂A, ∂B having measure zero.
- Lattice spacing $\delta_n \downarrow 0$.
- Write $A^{::} = A \cap \delta_n \mathbb{Z}^d$.

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- Theorem (L.-Peres) For any $\varepsilon > 0$, with probability one

$$D_{\varepsilon}^{::} \subset D_n, R_n, I_n \subset D^{\varepsilon::}$$

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- $\triangleright \quad D = A \cup B \cup \{s > \gamma\}.$
- $D_{\varepsilon}, D^{\varepsilon}$ are the inner and outer ε -neighborhoods of D.

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• Fix centers $x_1, \ldots, x_k \in \mathbb{R}^d$ and $\lambda_1, \ldots, \lambda_k > 0$.

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- *D* is the continuum Diaconis-Fulton sum of the balls $B(x_i, r_i)$, where $\lambda_i = \omega_d r_i^d$.

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 Follows from the main result and the case of a single point source.

Steps of the Proof

convergence of densities $\label{eq:convergence} \psi$ convergence of obstacles

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convergence of densities $$\downarrow$$ convergence of obstacles $$\downarrow$$ convergence of odometer functions

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convergence of densities $\downarrow \downarrow$ convergence of obstacles $\downarrow \downarrow$ convergence of odometer functions $\downarrow \downarrow$ convergence of domains.

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 Inspired by the Lawler-Bramson-Griffeath argument for a single point source.

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- Inspired by the Lawler-Bramson-Griffeath argument for a single point source.
- After all particles have aggregated (stage 1), let them resume walking until they exit D^{::} (stage 2).
- ▶ Fix $z \in D_{\varepsilon}^{::}$, and let
 - M = number of particles that visit z during stages 1 and 2.

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- Inspired by the Lawler-Bramson-Griffeath argument for a single point source.
- After all particles have aggregated (stage 1), let them resume walking until they exit D^{::} (stage 2).
- ► Fix $z \in D_{\varepsilon}^{::}$, and let
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- ▶ $\mathbb{P}(z \notin I_n) = \mathbb{P}(L = M).$

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Strategy: show 𝔅ἶ < 𝔅𝑘 and use concentration of measure.</p>

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Let

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The divisible sandpile odometer satisfies

$$\Delta u_n = 1 - 1_{\mathcal{A}^{::}} - 1_{\mathcal{B}^{::}}, \quad \text{on } D_n$$

 $u_n = 0, \quad \text{on } \partial D_n.$

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▶ Using the fact that $D_n \rightarrow D$, $u_n \rightarrow u$, and the positivity of u, can show that

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- Large deviations:

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• Conclude that $\mathbb{P}(\tilde{L} \ge M) < 4e^{-c_{\varepsilon}'\delta_n^{-2}}$.

Finishing Up

- Summing over z ∈ D^{::}_ε and over n, by Borel-Cantelli only finitely many of the events {z ∉ I_n} occur, a.s.
- ▶ Hence $D_{\varepsilon}^{::} \subset I_n$ for sufficiently large *n*.

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Circularity for the Divisible Sandpile

Dirichlet problem for the odometer function

$$\Delta u = 1 \qquad \text{on } A_m - \{o\}$$
$$\Delta u(o) = 1 - m \qquad u = 0 \qquad \text{on } \partial A_m.$$

Idea: Compare u to the function

$$\gamma(x)=|x|^2-ma(x).$$

where a is the potential kernel

$$a(x) = \lim_{n \to \infty} (G_n(o) - G_n(x))$$

and $G_n(x)$ is the expected number of visits to x by SRW before time n.

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Taylor expansion

Standard estimate:

$$a(x) = \frac{2}{\pi} \log |x| + k + O(|x|^{-2})$$

gives

$$\gamma(x) = |x|^2 - \frac{2m}{\pi} \log |x| + km + O(m|x|^{-2}).$$

• Get a constant K = K(m) such that

- If $r \le |x| < r+1$, then $\gamma(x) = K + O(1)$.
- $\gamma(x) \geq K + (r |x|)^2 + O\left(\frac{r^2}{|x|^2}\right).$

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Inner Radius

- $u \gamma$ is superharmonic in B_r
- $u \gamma \ge -K + O(1)$ on the boundary, hence on all of B_r .
- \triangleright γ grows quadratically as we move away from the boundary
- ▶ ∴ u > 0 on B_{r-c} .

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Outer Radius

- $u \gamma$ is harmonic in A_m
- $u \gamma \leq -K + O(1)$ on the boundary, hence on all of A_m .
- If $x \in A_m$ with $r \le |x| < r+1$, then $u(x) \le c'$.
- ▶ Lemma: If $y \in A_m \{o\}$ there exists $z \sim y$ with $u(z) \ge u(y) + 1$.
- Proof. For some neighbor z,

$$u(z) \geq \frac{1}{4} \sum_{w \sim y} u(w) = u(y) + 1.$$

$$\blacktriangleright :: A_m \subset B_{r+c'}.$$

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Adapting the Proof for Rotors

Rotor-router odometer:

u(x) = total number of particles emitted from x.

- Instead of $\Delta u = 1$, we only know $-2 \leq \Delta u \leq 4$.
- Repeating the argument only gives

$$B_{cr} \subset A_n \subset B_{c'r}$$
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Smoothing

► To do better, let

$$v(x) = \frac{1}{4k^2} \sum_{y \in S_k(x)} u(y)$$

where $S_k(x)$ is a box of side length 2k centered at x. • Using $\Delta = \text{div grad}$, we get

$$\Delta v(x) = \frac{1}{4k^2} \sum_{(y,z)\in\partial S_k(x)} \frac{u(z) - u(y)}{4}$$
$$= 1 + O\left(\frac{1}{k}\right)$$

if $o \notin S_k(x)$ and all sites in $S_k(x)$ are occupied.

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Fancier Smoothing

• Let T be the first exit time of B_r , and

$$v(x) = \mathbb{E}_{x}u(X_{T}) - \mathbb{E}_{x}T + n\mathbb{E}\#\{j < T | X_{j} = o\}.$$

Boundary value problem:

$$\Delta v = 1 \qquad \text{on } A_n \cap B_r - \{o\}$$
$$\Delta v(o) = 1 - n \qquad \text{on } \partial A_n.$$

• Want to show $u \approx v$.

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Green's Function

End up getting

$$u(x) \geq v(x) - \sum_{y \in B_r} \sum_{z \sim y} |G_{B_r}(x,y) - G_{B_r}(x,z)|.$$

- ▶ Error gets smaller as x approaches the boundary, and we can show $B_{r-C\log r} \subset A_n$.
- But for the outer radius, the error is

$$\sum_{y\in A_n}\sum_{z\sim y}|G_{A_n}(x,y)-G_{A_n}(x,z)|.$$

Can't control this, so we need another approach.

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Spreading Out

Spherical shells

$$S_k = \{x \in \mathbb{Z}^d : k \le |x| < k+1\}.$$

▶ Lawler, Bramson, and Griffeath (1992): If j < k, $x \in S_j$, $y \in S_k$, then

$$\mathbb{P}_{x}(X_{T_{k}}=y)\leq C/(k-j)^{d-1}.$$

Want to show the same holds for rotor-router walk, with frequency replacing probability.

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Holroyd-Propp Bound

- recurrent graph G
- $Y \subset Z$ sets of vertices
- s(x) particles start at x
- Stop walks when they hit Z; how many land in Y?
- Let $H(x) = \mathbb{P}_x(X_T \in Y)$. Then

$$|RR(s,Y) - RW(s,Y)| \le \sum_{u \in G} \sum_{v \sim u} |H(u) - H(v)|$$

independent of s and the initial rotor positions!

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Outer Radius

N_j = # particles that ever reach shell S_j.
If r < j < k with N_k > N_j/2, then

$$\frac{CN_j}{(k-j)^{d-1}}\#(S_k\cap A_n)\geq \frac{N_j}{2}$$

hence

$$\sum_{i=j}^k \#(S_i \cap A_n) \ge C(k-j)^d.$$

Since $B_{r-C\log r}$ is fully occupied,

$$k \leq j + C(r^{d-1}\log r)^{1/d}$$

which gives

$$A_n \subset B_{r(1+Cr^{-1/d}(\log r)^{1+1/d})}.$$

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- Is the occupied region simply connected?
- Understand the patterns in the picture of rotor directions.
- Identify the limiting shape of the "broken rotor" models.



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- Start every site in \mathbb{Z}^2 at height *h*.

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- In all other cases, even the existence of a limiting shape is open.
- Even for h = 2, the rate of growth of the square is not known.

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h = 2



$$h = 1$$



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