

1. Let B be a manifold and $\pi: E \rightarrow B$ a real vector bundle.
 - (a) Assume that E is a tensor bundle, i.e. $E = \mathcal{F}(TB)$, where \mathcal{F} is a smooth (say, contravariant) functor from the category of finite-dimensional real vector spaces to itself. Then sections s of E can be pulled back along smooth maps $\phi: B \rightarrow B$, namely $\phi^*(s)(b) = \mathcal{F}(T_b\phi) \circ s \circ \phi(b)$ for $b \in B$. The *Lie derivative* $\mathcal{L}_\xi(s)$ of a smooth section s along a smooth vector field ξ on B is defined by $\mathcal{L}_\xi(s) = \frac{d}{dt}\theta_t^*(s)|_{t=0}$, where θ is the flow of ξ . Show that $\mathcal{L}_\xi(fs) = \mathcal{L}_\xi(f)s + f\mathcal{L}_\xi(s)$ for every smooth function $f: B \rightarrow \mathbf{R}$.
 - (b) Show that for every $b \in B$ and $h \in E_b$ there exists a smooth section $s \in \Gamma(B, E)$ with the property that $s(b) = h$.
 - (c) Let $\mathbf{k} = C^\infty(B)$ be the ring of smooth functions on B . Let E^* be the dual bundle to E and let $\Gamma(B, E)^* = \text{Hom}_{\mathbf{k}}(\Gamma(B, E), \mathbf{k})$ be the \mathbf{k} -module dual to $\Gamma(B, E)$. Define a \mathbf{k} -bilinear pairing

$$P: \Gamma(B, E^*) \times \Gamma(B, E) \longrightarrow \mathbf{k}$$

by $P(\sigma, s)(b) = \sigma(b)(s(b))$ for $b \in B$. Let $P^\sharp: \Gamma(B, E^*) \rightarrow \Gamma(B, E)^*$ be the \mathbf{k} -linear map defined by $P^\sharp(\sigma)(s) = P(\sigma, s)$. Prove that P^\sharp is an isomorphism.

2. Let V be a finite-dimensional real vector space and let $\alpha \in A^k(V)$. We call α *decomposable* if $\alpha \neq 0$ and $\alpha = v_1 \wedge v_2 \wedge \cdots \wedge v_k$ for some $v_1, v_2, \dots, v_k \in V$. The *annihilator* of α is the linear subspace $\alpha^\perp = \{v \in V \mid \alpha \wedge v = 0\}$ of V . Prove the following statements.
 - (a) Let $\alpha \neq 0$. Then $\dim(\alpha^\perp) = k$ if and only if α is decomposable.
 - (b) Every k -dimensional subspace W of V is of the form $W = \alpha^\perp$ for a decomposable element $\alpha \in A^k(V)$, which is uniquely determined by W up to a multiplicative constant.
 - (c) Let $\beta \in A^l(V)$. If α and β are decomposable, then $\alpha^\perp \subseteq \beta^\perp$ if and only if $\beta = \alpha \wedge \gamma$ for some $\gamma \in A(V)$.
 - (d) If α and β are decomposable, then $\alpha^\perp \cap \beta^\perp = \{0\}$ if and only if $\alpha \wedge \beta \neq 0$, and in that case $(\alpha \wedge \beta)^\perp = \alpha^\perp \oplus \beta^\perp$.
 - (e) Every nonzero element of $A^{n-1}(V)$ is decomposable, where $n = \dim(V)$.

Let $\xi: I \rightarrow TM$ be a time-dependent vector field on a manifold M , where I is an open interval containing 0. Let $\hat{\xi} = \frac{\partial}{\partial t} + \xi$ be the associated time-independent vector field on $I \times M$, and let $\hat{\theta}: \hat{\mathcal{D}} \rightarrow I \times M$ be the flow of $\hat{\xi}$, where $\hat{\mathcal{D}} \subseteq \mathbf{R} \times I \times M$ is the flow domain of $\hat{\xi}$. Write points in $\mathbf{R} \times I \times M$ as (s, t, x) . Since the first component of $\hat{\xi}$ is $\frac{\partial}{\partial t}$, the flow is of the form $\hat{\theta} = (s + t, \theta(s, t, x))$ for a unique smooth map $\theta: \hat{\mathcal{D}} \rightarrow M$. The path $\gamma(s) = \theta(s - t, t, x)$ is the trajectory of ξ passing through x at time $s = t$.

In particular, $\gamma(s) = \theta(s, 0, x)$ is the trajectory of ξ passing through x at time $s = 0$. In the sequel we abbreviate $\theta(s, 0, x)$ to $\theta(s, x)$ and refer to θ as the *flow* of ξ . The domain $\mathcal{D} \subseteq \mathbf{R} \times M$ of θ consists of all (s, x) with $(s, 0, x) \in \hat{\mathcal{D}}$ and is therefore an open subset of $\mathbf{R} \times M$.

- 3 (Connected manifolds are homogeneous under the diffeomorphism group). Let M be a manifold. Prove the following assertions.

- (a) M is connected if and only if it is C^∞ path-connected (the definition of which is left to your imagination).

- (b) Assume M to be connected. For all x and y in M there exists a diffeomorphism $f: M \rightarrow M$ such that $f(x) = y$. (Choose a smooth path $c: [0, 1] \rightarrow M$ connecting x to y . Show there exists a compactly supported time-dependent vector field ξ on M such that $\xi(t, c(t)) = c'(t)$ for $0 \leq t \leq 1$, and use the flow $(t, x) \rightarrow \theta(t, x)$ of ξ .)

A *time-dependent* differential form on a manifold M is a smooth function $\alpha: I \times M \rightarrow A(T^*M)$ such that $\alpha(t, x) \in A(T_x^*M)$ for all $(t, x) \in I \times M$, i.e. a form on $I \times M$ that does not involve dt . Here I is an open interval. For a time-dependent form α we define forms $\alpha_t \in \Omega(M)$ for each $t \in I$ by $\alpha_t(x) = \alpha(t, x)$.

4. Let α be a time-dependent form and $\xi: I \times M \rightarrow TM$ a time-dependent vector field. Let $(t, x) \mapsto \theta(t, x) = \theta_t(x)$ be the flow of ξ . Then

$$\frac{d}{dt} \theta_t^* \alpha_t = \theta_t^* (\mathcal{L}(\xi_t) \alpha_t + \dot{\alpha}_t),$$

where the dot denotes differentiation with respect to t .

For a module V over a commutative ring \mathbf{k} we let $V^* = \text{Hom}_{\mathbf{k}}(V, \mathbf{k})$ be the dual module and for each $u \in V$ we define a map $\iota(u): A^k(V^*) \rightarrow A^{k-1}(V^*)$ by

$$\iota(u)(\phi_1 \wedge \phi_2 \wedge \cdots \wedge \phi_k) = \sum_{l=1}^k (-1)^{l+1} \phi_l(u) \phi_1 \wedge \phi_2 \wedge \cdots \wedge \widehat{\phi_l} \wedge \cdots \wedge \phi_k$$

for $\phi_1, \phi_2, \dots, \phi_k \in V^*$. Under the canonical isomorphism $A^k(V^*) \cong \text{Alt}_{\mathbf{k}}^k(V)$ we have

$$(\iota(u)\phi)(v_1, v_2, \dots, v_{k-1}) = \phi(u, v_1, v_2, \dots, v_{k-1})$$

for $\phi \in \text{Alt}_{\mathbf{k}}^k(V)$. Applying this to the ring of smooth functions $\mathbf{k} = C^\infty(M)$ of a manifold M and the module of smooth vector fields $V = \mathcal{T}(M)$ we get an operator $\iota(\xi): \Omega^k(M) \rightarrow \Omega^{k-1}(M)$ for each vector field ξ . There are various relationships among the operators $\iota(\xi)$, $\mathcal{L}(\xi)$, and d , the most important of which is *É. Cartan's magic formula*, which says that $\mathcal{L}(\xi)$ is the graded commutator of d and $\iota(\xi)$,

$$\mathcal{L}(\xi) = [d, \iota(\xi)] = d\iota(\xi) + \iota(\xi)d.$$

5. Let μ be a *volume form* on an n -manifold with boundary M , that is a nowhere vanishing n -form ($\mu(x) \neq 0$ for all $x \in M$). Let ξ be a (time-independent) vector field. Then $\mathcal{L}(\xi)\mu$ is an n -form, so there is a unique function $\text{div}(\xi)$, called the *divergence* of ξ relative to μ , satisfying $\mathcal{L}(\xi)\mu = \text{div}(\xi)\mu$. Prove the following statements.

- (a) $\text{div}(\xi) = 0$ if and only if $\theta_t^* \mu = \mu$ for all t , where θ is the flow of ξ .
(b) For compact M we have the *divergence theorem*,

$$\int_M \text{div}(\xi)\mu = \int_{\partial M} \iota(\xi)\mu.$$

(Here we use the orientation of M compatible with μ , i.e. an ordered basis (v_1, v_2, \dots, v_n) of $T_x M$ is positively oriented if $\mu(v_1 \wedge v_2 \wedge \cdots \wedge v_n) > 0$.) (Use Cartan's formula.)

- (c) Now let ξ be a time-dependent vector field on M . Assume ξ is complete with flow θ . Let f be a time-dependent smooth function on M (i.e. a smooth

function $f : I \times M \rightarrow \mathbf{R}$) and A a relatively compact open subset. Then we have the *transport equation*,

$$\frac{d}{dt} \int_{\theta_t(A)} f_t \mu = \int_{\theta_t(A)} (\dot{f}_t + \mathcal{L}(\xi_t) f_t + f_t \operatorname{div}(\xi_t)) \mu.$$